COMP-ECO

Research Data Management and Data Management Planning

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Go to menti.com











Let us talk about data

Let us start writing a Data Management Plan

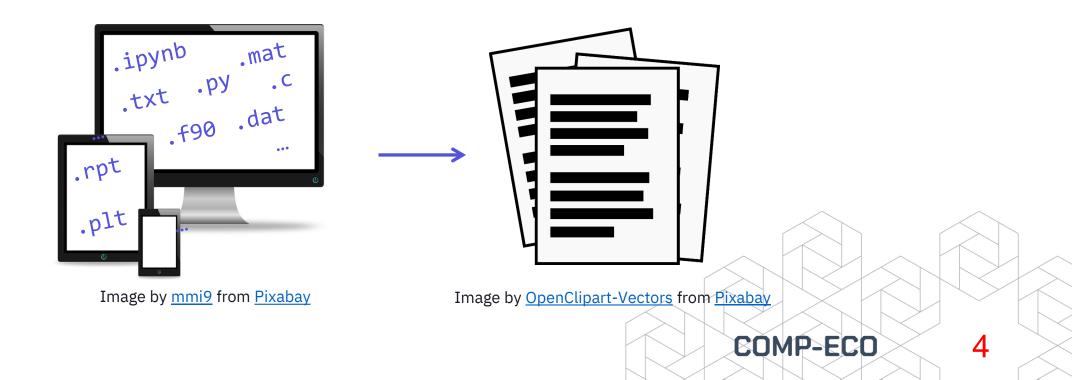






WHAT DO WE CONSIDER AS 'DATA'?

All research output necessary to validate and reuse the results of a project







Raw data

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Processed data #2

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5.8	3.44e-06	1.21e-07
8.0	6.95e-06	2.10e-07
24.0	3.54e-06	3.62e-07
70.0	1.45e-05	2.18e-06

Accompanied by documentation files and processing scripts

Processed data #1

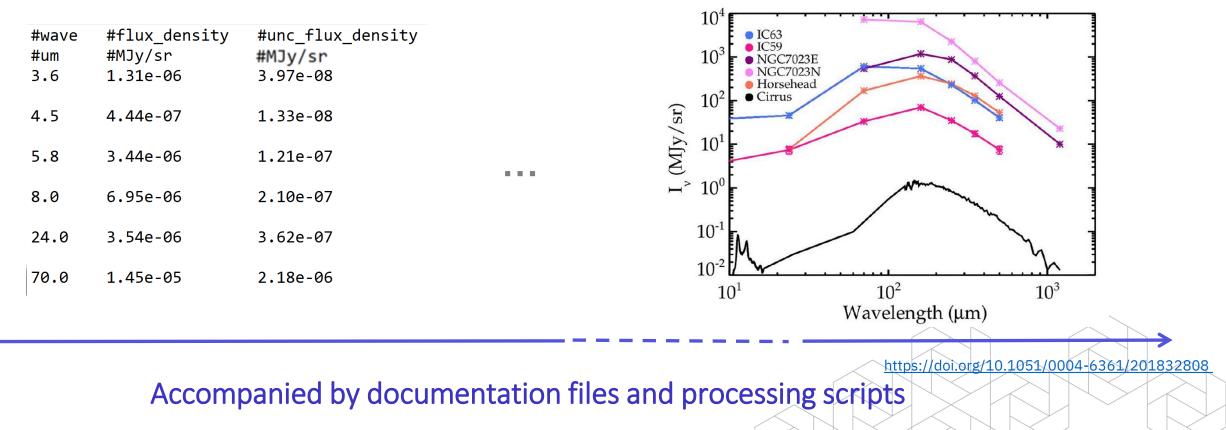
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Processed data #2

Finalized data



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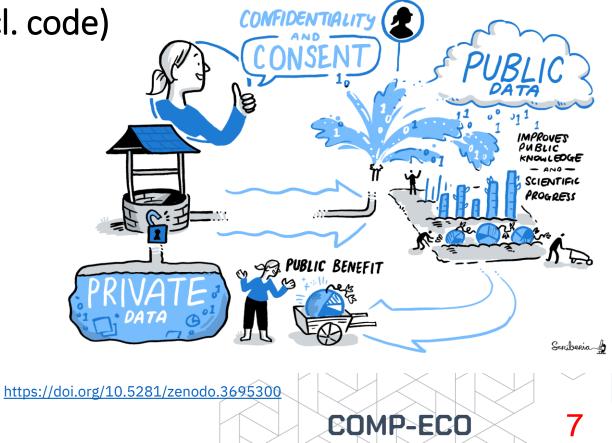




WHAT IS DATA STEWARDSHIP?

It is about taking care of data (incl. code)

Data type Policy and regulations Tools and software Storage and access Backups Transfer and exchange Publishing and archiving







During research and after research... Findable – Accessible – Interoperable – Reusable





Funded by the European Union

Avoid data breaches and data losses





Funded by the European Union

> Avoid data breaches and data losses Make the data/code understandable





During research and after research... Findable – Accessible – Interoperable – Reusable

Funded by the European Unior

> Avoid data breaches and data losses Make the data/code understandable Make the research reproducible and/or replicable





WHAT IS A DATA MANAGEMENT PLAN (DMP)?

Funded by the European Union







LET US DRAFT A DMP!

- Think about a research project
- Go to dmponline.dcc.ac.uk







Plan to make data work for you

Data Management Plans that meet institutional funder requirements.



Sign in	Create account							
* Email								
* Passw	ord							
Forgot pa	<u>issword?</u> nber email							
Sign in								
	- or -							
Sign in with your institutional credentials								

DMPonline helps you to create, review, and share data management plans that meet institutional and funder requirements. It is provided by the Digital Curation Centre (DCC).







DATA/CODE COLLECTION/GENERATION

For example:

Tabular data from fatigue experiments in .csv format X-ray computed tomography measurements in image .tif format Measurement data of aircraft emissions obtained on-site, in .nc4 format Library developed in Python for distributed real-time calculation processes Modules developed in C++ and MATLAB built upon open-source code Video recordings in .mp4 format of interactions between robots and human Simulation data of a jet flame in .cngs format using Ansys CFX solver Processed Particle Image Velocimetry measurements of a cavity model in .dat format Deep learning model for predictive maintenance developed in Python using tensorflow Analysis/visualization scripts developed in Python







DOCUMENTATION - README

Preview	V Code Blame 137 lines (78 loc) · 5.12 KB	
1	</td <td></td>	
2	This is a README.md template for releasing a code project in a GitHub/Gitlab repository.	
з	Under each section you can find commented text with explanation on what to add in each section.	
4	Please modify the sections depending on needs, and delete all commented text once the README is done.	
5	>	
6		
7	# Model name or Project Name	
8		
9	Add here a badge for the ArXiv identifier of the pre-print version of the paper/journal-article</td <td></td>	
10	related to this code project (arXiv:YYMM.NNNNN) (if applicable) e.g.:	
11		
12	[![Paper](http://img.shields.io/badge/Paper-arXiv.YYMM.NNNNN-B3181B?logo=arXiv)](https://arxiv.org/ab	/)
13	>	
14		
15	Add here the hyperlink to the finalized version of the paper/journal-article related to this project</td <td></td>	
16	(the DOI link provided by the journal publisher after peer-review acceptance) (if applicable) e.g.:	
17		
18	This repository is the official implementation of the following paper.	
19		
20	* Paper title: [Paper Title](https://doi.org/YYMM.NNNNN)	
21 22	>	
22		
23		
24	## Description	
26		
27	Provide description of the contents of the code repository</td <td></td>	
28	* Provide information about what the code does	
29		down
30	* Provide links for demos, blog posts, etc. (if applicable) * Mention any caveats and assumptions that were considered	JUWI
21		

README template for <u>code</u> README template for <u>data</u> README template for <u>machine learning</u>







DOCUMENTATION – EXPERIMENTAL DATA

Original plan/protocol. A permanent fixed record of the design of the experiment (goal, team involved, procedure, instrumentation, testing, benchmarking). This file should also point out to the data dictionary and the file naming conventions used. See a template in Markdown (using the Code tab) <u>here</u>

Logbook and dictionary. Have two documentation files per experiment:

1) Logbook: record of *in-situ* settings and configuration of each individual experiment that together with the original plan/protocol- provides sufficient information to enable the reproduction of the experimental results (*what* was modified from the original plan?)

2) Dictionary: a spreadsheet with the definition of variables (for example: location, instruments, dimensions, resolution, aircraft type, studied pollutants, etc.); the units and precision for the numerical variables; the categories for categorical data; any encoding used (e.g., for qualitative variables); etc.







Data dictionary example

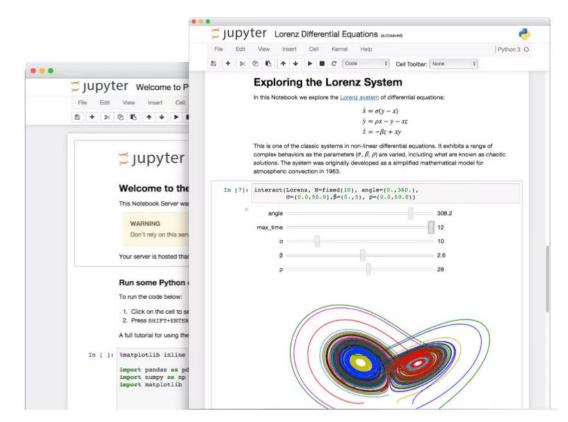
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2	T1_0.1+A	1	-	0.1		0.21	6.1	4.5	6.4	5.8		
0	T1_0.1+B	1	1	0.1		0.16	6.1	4.5	6.2	5.7		
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Zormpa, Eirini, & Martinez-Lavanchy, Paula. (2022, June 13). EMBL-EBI Bioinformatics for PIs 2022: Planning your data management session. Zenodo. https://doi.org/10.5281/zenodo.6637453 COMP-ECO 18





DOCUMENTATION - TOOLS



https://jupyter.org/

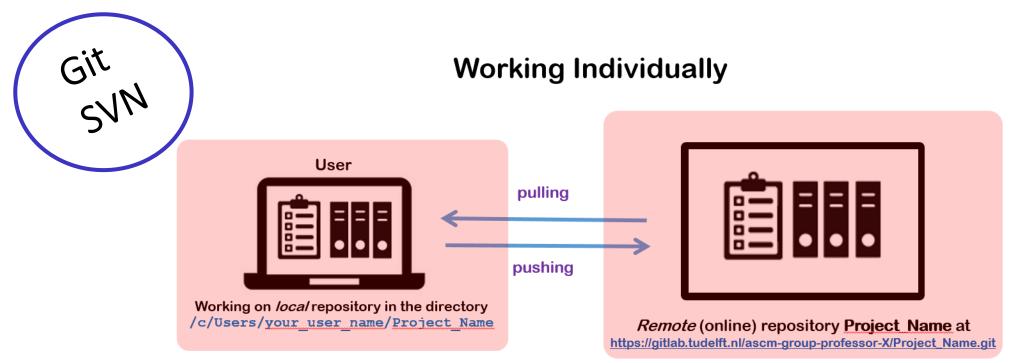
<u>Jupyter Notebooks</u> <u>Quarto</u> <u>Electronic Lab Notebooks</u>

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DOCUMENTATION – VERSION CONTROL



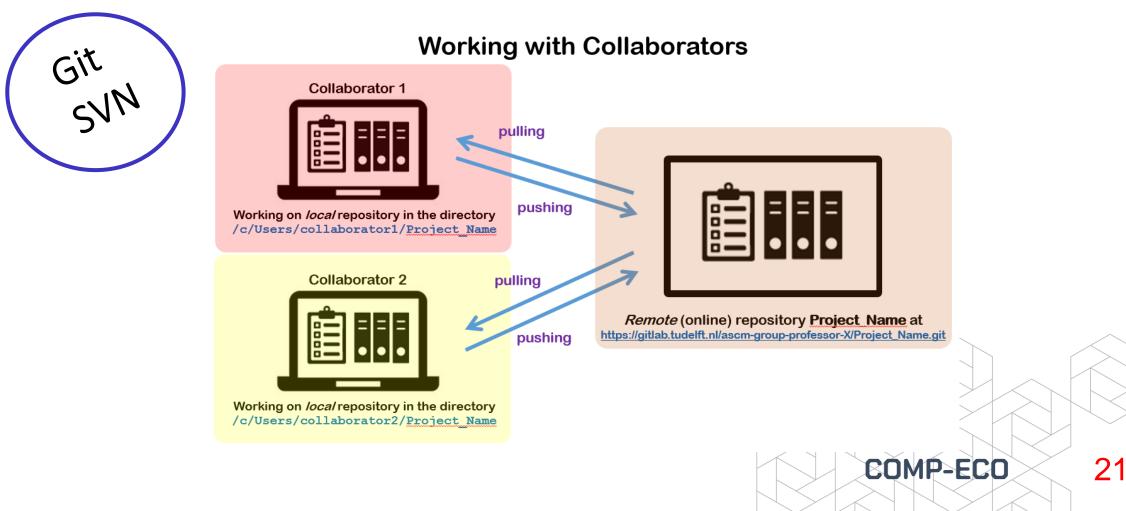








DOCUMENTATION – VERSION CONTROL



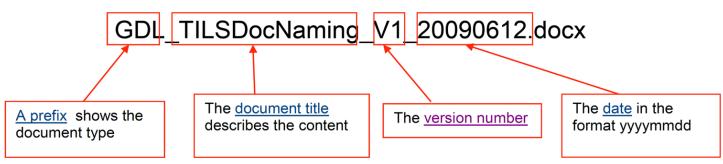




INDIRECT DOCUMENTATION

TILS Document Naming Convention

Document naming for the TILS Division should follow this convention:



http://www.data.cam.ac.uk/files/gdl_tilsdocnaming_v1_20090612.pdf

https://github.com/HeatherAn/recommended-coding-practices/blob/main/13-Naming-Conventions.md

https://datamanagement.hms.harvard.edu/plan-design/file-naming-conventions









https://github.com/cookiecutter/cookiecutter

https://gitlab.tudelft.nl/handrewsmancil/improving-coding-practices-training

https://drivendata.github.io/cookiecutter-data-science/

\vdash	LICENSE	
\vdash	Makefile	<- Makefile with commands like `make data` or `make train`
i_	README.md	<- The top-level README for developers using this project.
Ĺ	data	
ł	└── external	<- Data from third party sources.
ł	└── interim	<- Intermediate data that has been transformed.
-		
1	processed	<- The final, canonical data sets for modeling.
-	∟ raw	<- The original, immutable data dump.
-	docs	<- A default Sphinx project; see sphinx-doc.org for details
-	models	<- Trained and serialized models, model predictions, or model summaries
	notebooks	<- Jupyter notebooks. Naming convention is a number (for ordering),
	IIO CEDOOKS	the creator's initials, and a short `-` delimited description, e.g.
-		
		`1.0-jqp-initial-data-exploration`.
1	references	<- Data dictionaries, manuals, and all other explanatory materials.
	rererences	<- bata dictionaries, manuals, and all other explanatory materials.
Ĺ	reports	<- Generated analysis as HTML, PDF, LaTeX, etc.
i	└── figures	<- Generated graphics and figures to be used in reporting
i i		gp
Ĺ	requirements.txt	<- The requirements file for reproducing the analysis environment, e.g.
i i		generated with `pip freeze > requirements.txt`
i i		generated with pip freeze - requirements fixe
È	setup.py	<- Make this project pip installable with `pip install -e`
i_	src	<- Source code for use in this project.
i	└── init .pv	<- Makes src a Python module
i		
İ	└── data	<- Scripts to download or generate data
i	└── make_datas	et.py
i		
i	— features	<- Scripts to turn raw data into features for modeling
i	│ └── build feat	ures.pv
i		
i	— models	<- Scripts to train models and then use trained models to make
Ì		predictions
i	predict_mo	del.py
i	└── train_mode	
i		
		<- Scripts to create exploratory and results oriented visualizations
1	└── visualize.	ру
	tox.ini	<- tox file with settings for running tox; see tox.testrun.org





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For experimental data: **separate** raw, from processed data and go for a **hierarchical structure**

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-- original plan/protocol
-- data/
      -- logbook
      -- dictionary
      -- raw/ (in raw/ subdivide the data corresponding to each experiment)
           -- location
                -- aircraft
                     -- engine
                          -- pollutant
      -- processed/
            -- location
                -- aircraft
                     -- engine
                          -- pollutant
      -- finalized/
-- docs/
                                                                   COMP-ECO
```





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https://pypi.org/project/h5pyViewer/





DATA STORAGE

- 3-2-1 Rule
 - 3 copies
 - 2 storage media
 - 1 copy in a different (physical) location







DATA STORAGE

Institutional workstations & laptops

Optical Storage (e.g., CDs, DVDs)

External Drives & Thumbdrives (e.g., HDD, USB)

Institutional network drives

Cloud storage (e.g., Onedrive, AWS)

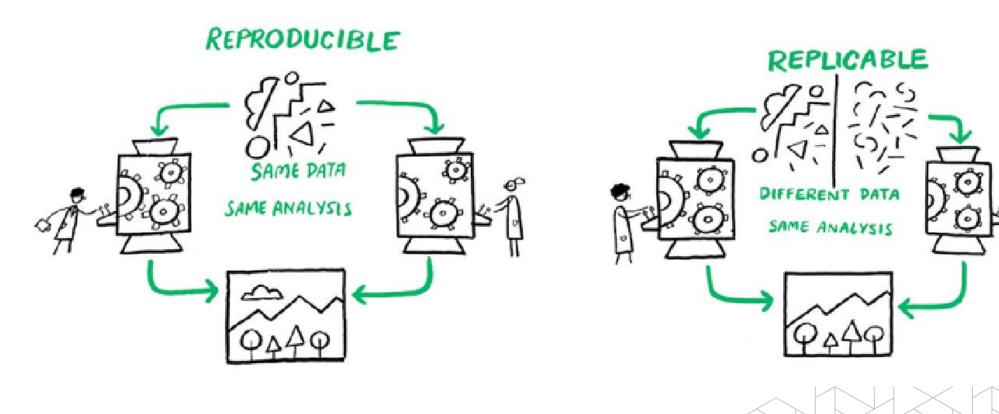
Other cloud services (e.g. MS Teams)





WHAT DATA/CODE SHOULD BE PRESERVED FOR THE LONG-TERM?

COMP-ECO



The Turing Way project illustration by Scriberia. Used under a CC-BY 4.0 licence. DOI: <u>10.5281/zenodo.3332807</u>.



Journal Article

Data/code that can be published

https://doi.org/10.4121/14827680.v1

Data underlying the publication: "A Computationally Efficient Moving Horizon Estimator for UWB Localization on Small Quadrotors""

quadrotor, quadrotor localization, State Estimation, Ultra

RefWorks, BibTeX, Reference Manager, Endnote, DataCite,

CATEGORIES

KEYWORDS

LICENCE

© 0

EXPORT AS...

NLM, DC, CFF

Aerospace Engineering

Wide Band, UWB Applications

doi: 10.4121/14827680.v1

Cite

DATASET

by Sven Pfeiffer ^(D), Christophe de Wagter ^(D), Guido de Croon

This Dataset contains the data files used for simulations in the publication "A Computationally Efficient Moving Horizon Estimator for Ultra-Wideband Localization on Small Quadrotors" (2021) by S. Pfeiffer, C. de Wagter and G.C.H.E de Croon.

The logs were collected in two different UWB modes (TWR and TdoA) and on 6 different trajectories (Square, Triangle, Octagon, Hourglass, Star, Random). UWB data was gathered with 8 anchors positioned roughly in the corners of a cube. Two of the files do not contain complete UWB data and are marked with the suffix "_BAD".

The data was recorded on a Crazyflie 2.1 in the TU Delft "Cyberzoo" indoor flight arena using the scripts found at https://github.com/Huizerd/crazyflie-suite. The code used for the simulations in the paper can be found at https://github.com/SUPfeiffer/uwb-simulator

This dataset contains the following files: anchor_positions.yaml : This file contains the location of the UWB anchors in Cyberzoo coordinates date_time_mode_trajectory.csv : The log files

Data/code that CANNOT be published

Network locations (4)

Staff Group Data (M:)

Staff Bulk Data (N:)

Project Data (U:)

Network Drive Network Drive

Network Drive







Supporting data for ultrasonic guided wave and electro-mechanical reactance tests on a full scale composite torsion box panel

doi: 10.4121/uuid:8c743b60-69f3-4f59-b738-8f58b784bb9f

DOI (persistent identifier) of the dataset

DATASET

by Pedro Carvalho

The data refers to ultrasonic guided wave (GW) measurements on a full-scale composite torsion box stiffened panel. The panel was subjected to realistic low-energy impacts in different critical locations in order to obtain barely-visible impact damage (BVID) of different severities. The purpose of the study was to assess the diagnostic capabilities of the GW based structural health monitoring (SHM) system, which was designed according to a newly developed systematic multi-parameter methodology. Hence, the diagnostic capability assessment served also the purpose of validating the SHM system design methodology. The data in this dataset was collected in the Netherlands Aerospace Centre – NLR, located in Marknesse, the Netherlands, and was integrated in the Thermoplastic Affordable Primary Aircraft Structure 2 (TAPAS 2) project, financed by the Netherlands Enterprise Agency of the Ministry of Economic Affairs

HISTORY

2019-01-28 first online, published, posted

PUBLISHER 4TU.Centre for Research Data Metadata items compatible with that of web search engines

FORMAT

media types: application/pdf, application/x-matlab-data, application/zip, text/csv

REFERENCES

https://doi.org/10.1002/stc.2340



FUNDING

The Netherlands Enterprise Agency of the Ministry of Economic Affairs

ORGANIZATIONS

TU Delft, Faculty of Aerospace Engineering, Department of Aerospace Structures and Materials

CONTRIBUTORS Benedictus, R. (Rinze) Groves, R.M. (Roger)

vas CATEGORIES Pe Aerospace Engineering

Construction Materials Performance and Processes

KEYWORDS

Barely-visible impact damage (BVID), Composite primary structure, Structural health monitoring (SHM), System

design, Ultrasonic guided wave (GW)



Open content license (CC-BY-NC)

EXPORT AS... RefWorks, BibTeX, Reference Manager, Endnote, DataCite,

NLM, DC, CFF

Example of published data via the <u>4TU.ResearchData</u>

https://doi.org/10.4121/uuid:8c743b60-69f3-4f59-b738-8f58b784bb9f



USAGE STATS

99 601

Performance and



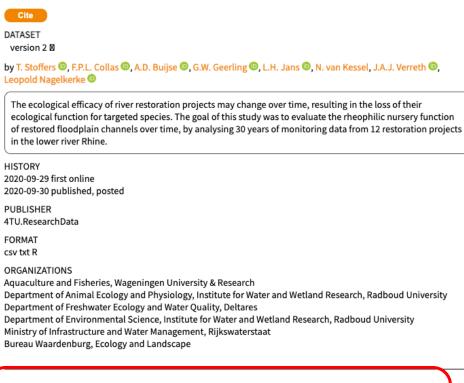






Data from: 30 years of large river restoration: how long do restored floodplain channels remain suitable for targeted rheophilic fishes in the lower river Rhine?

doi: 10.4121/12999575.v2



DATA - restricted access

Reason Request from the researcher. In order to obtain the data, please contact WUR-Library (data.library@wur.nl)

Request access to data.



USAGE STATS

1349 1 views citations

CATEGORIES

Fisheries Sciences

KEYWORDS

cyclic rejuvenation, habitat succession, nursery area, river management, river rehabilitation, riverine fishes

GEOLOCATION The lower river Rhine

TIME COVERAGE 1989-2019



EXPORT AS... RefWorks, BibTeX, Reference Manager, Endnote, DataCite, NLM, DC, CFF

Example of published metadata with the data available upon request

https://doi.org/10.4121/12999575.v2

31

COMP-ECO





LBoW - Linear Buoyancy Wave Package

doi: 10.4121/21711227.v1



SOFTWARE

by Dries Allaerts 💿

LBoW is a python package for solving linear buoyancy wave problems, like for example uniform stratified flow over a bell-shaped hill. The software presents a semi-analytical implementation of linear theory for stratified flow (i.e., the Taylor-Goldstein equation).

Checkout the README.md file for installation instructions, software requirements, etc. More information as well as the latest version of the software can be found in the GitHub repository

HISTORY 2022-12-13 first online, published, posted

PUBLISHER 4TU.ResearchData

FORMAT Python package (compressed into one zip file)

REFERENCES https://github.com/DriesAllaerts/lbow

ORGANIZATIONS TU Delft | Faculty of Aerospace Engineering | Department of Flow Physics and Technology

DATA

FILES

1,213,759 bytes md5 lbow-0.1.0.zip



USAGE STATS

13 155 downloads views

CATEGORIES Mechanical Engineering Aerospace Engineering Environmental Engineering Atmospheric Sciences

KEYWORDS Atmospheric gravity waves, Linear theory, Wind energy

LICENCE

Apache-2.0

EXPORT AS... RefWorks, BibTeX, Reference Manager, Endnote, DataCite, NLM, DC, CFF

Example of published code via the 4TU.ResearchData-Github integration

https://doi.org/10.4121/21711227.v1

COMP-ECO





EXAMPLES OF PUBLISHED DATA AND CODE

Code:

4TU.ResearchData repo: <u>https://doi.org/10.4121/21711227.v1</u> Github repo: <u>https://github.com/DriesAllaerts/lbow</u> 4TU.ResearchData repo: <u>https://doi.org/10.4121/16764238.v1</u> Github repo: <u>https://github.com/bartroot/GSH</u> 4TU.ResearchData repo: <u>https://doi.org/10.4121/13387985.v1</u> Github repo: <u>https://github.com/ROOSTER-fleetmanagement/rooster_fleet_manager</u> (in this case more detailed documentation is shared via Github pages: <u>https://rooster-fleet-management.github.io/rooster_fleet_manager/</u>)

Data:

https://doi.org/10.4121/21667796.v1 https://doi.org/10.4121/uuid:5deaf8cf-ec57-4e33-86c4-8253a00df1d4 https://doi.org/10.4121/16437297.v1 https://doi.org/10.4121/uuid:edfc5304-39ed-4556-a95a-f8b3313f7cfc







Back end

CITATION METADATA

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<dcterms:title> Investigation of fatigue crack growth in a single cycle by means of acoustic emission
</dcterms:title>

<dcterms:identifier>https://hdl.handle.net/10411/20730</dcterms:identifier> <dcterms:creator>Pascoe, John-Alan</dcterms:creator> <dcterms:creator>Zarouchas, Dimitrios</dcterms:creator> <dcterms:creator>Alderliesten, René</dcterms:creator> <dcterms:publisher>DataverseNL</dcterms:publisher> <dcterms:issued>2016-04-13</dcterms:issued> <dcterms:modified>2016-04-18T15:21:40Z</dcterms:modified>

</metadata>

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Front end (repository website)

Citation Metadata 🔺	
Dataset Persistent ID	hdl:10411/20730
Publication Date	2016-04-13 Values
Title	Investigation of fatigue crack growth in a single cycle by means of acoustic emission
Author Elements	Pascoe, John-Alan (Delft University of Technology) Zarouchas, Dimitrios (Delft University of Technology) Alderliesten, René (Delft University of Technology)
Contact	Use email button above to contact. John-Alan Pascoe (Delft University of Technology)





Platform	Storage space	Max file size	Metadata Quality	ID	Location Storage
4TU.ResearchData <u>http://data.4tu.nl</u>	- 1 TB per TU Delft user per year - Public	10 GB	High	DOI	Netherlands
Zenodo https://about.zenodo.org/	 - 50 GB per upload - "No" limit on # of datasets (donate) - Public and Private 	None	High	DOI	CERN Data Center
Figshare <u>https://figshare.com/features</u>	- Private: 20 GB per user - Public: Unlimited - Public and Private	5 GB	Low	DOI	Amazon Web Services
DataverseNL https://dataverse.nl/	- "No" limit (fair use) - Public and Private	2 GB	High	Handle	Netherlands (DANS)
Open Science Framework https://osf.io/	- Adds-on limits - Public and Private	5 GB (add- on for larger files)	Medium	DOI	Google Cloud Amazon Glacier





	Platform	Features	Max project size	Max file size	Supports
Repositories	Github <u>https://github.com/</u>	 Unlimited number of collaborators (free and paid plans) Public: unlimited number of projects (free) Private: unlimited number of project (paid) 	1 GB	100 MB	Git SVN
	Bitbucket <u>https://bitbucket.org</u>	 - 5 collaborators in public and private projects (free and paid plans). More must be paid. - Public: unlimited number of projects (free and paid) - Private: unlimited number of projects (free and paid) 	1(2) GB	None	Git Mercurial SVN SourceForge
Code	GitLab <u>https://gitlab.com/</u>	 Unlimited number of collaborators (free and paid plans) Public: unlimited number of projects (free and paid) Private: unlimited number of projects (free and paid) 	10 GB	None	Git



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