

# COMP-ECO Workshop

Smart structures – health monitoring and self-sensing capabilities of composites

26<sup>th</sup> October 2023 in Delft, the Netherlands

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Aerospace Structures & Materials Department



# Smart Structures – Health Monitoring & Self-sensing Capabilities of Composites

## MAIN FOCUS OF WORKSHOP

- Fibre optic sensing for smart structures
- Guided wave ultrasonic sensing for smart structures

## SCHEDULE

- 13:30 Lecture on Fibre optic sensing (Lecture Room F)
- 14:15 Coffee Break
- 14:30 Lecture on Guided wave ultrasonic sensing (Lecture Room F)
- Lab Demonstrations
  - 15:30 Group 1: Fibre Optic Sensing; Group 2: Ultrasonic Sensing
  - 16:00 Group 1: Ultrasonic Sensing; Group 2: Fibre Optic Sensing
- 16:30 Round-up of Smart Structures workshop (Lecture Room F)



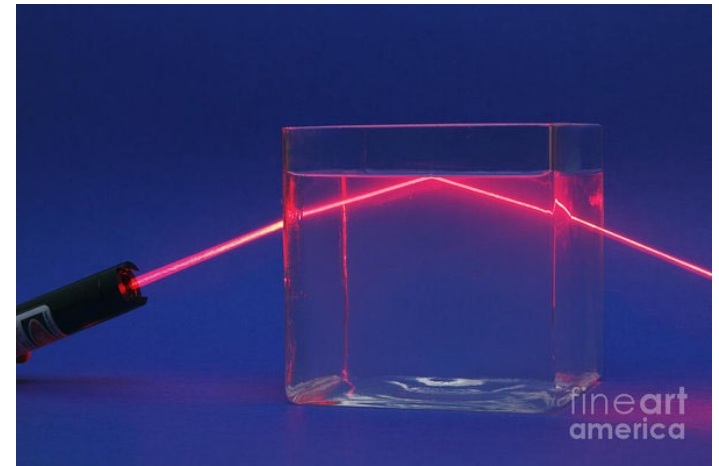
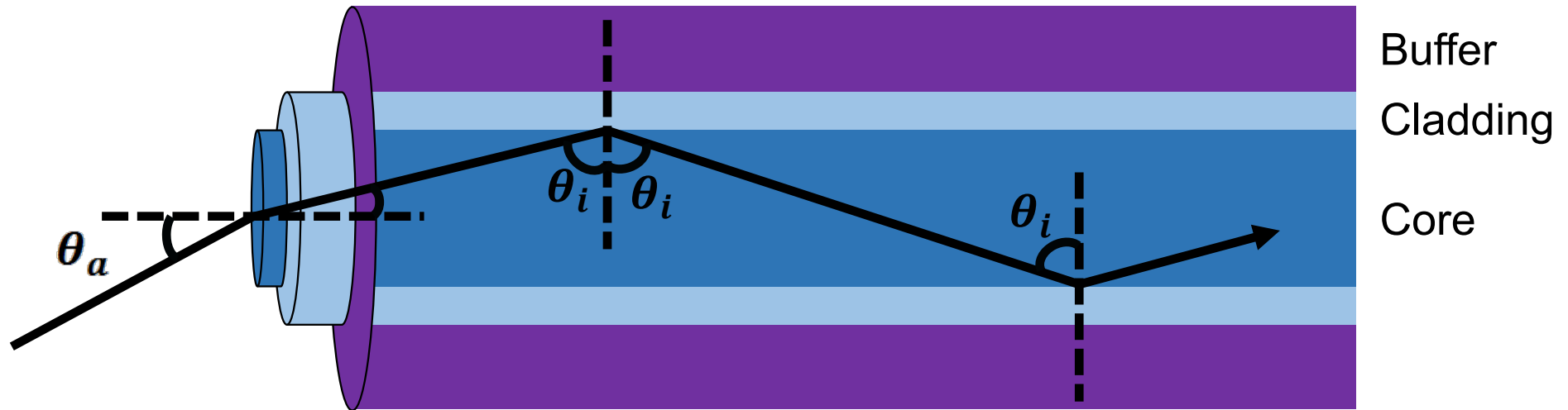
# *Part 1: Fibre optic sensing for smart structures*

# Total Internal Reflection

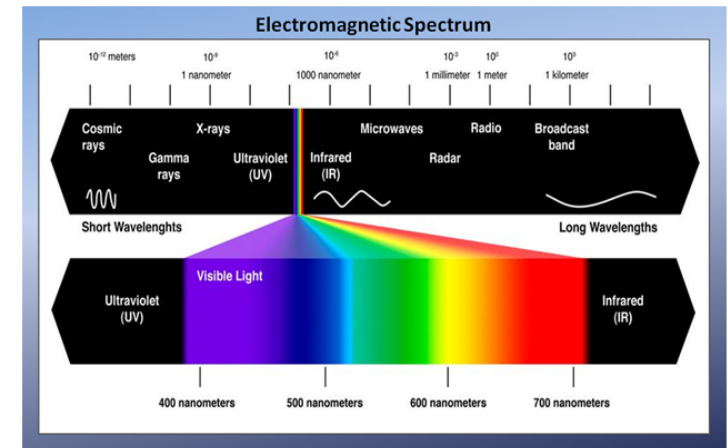
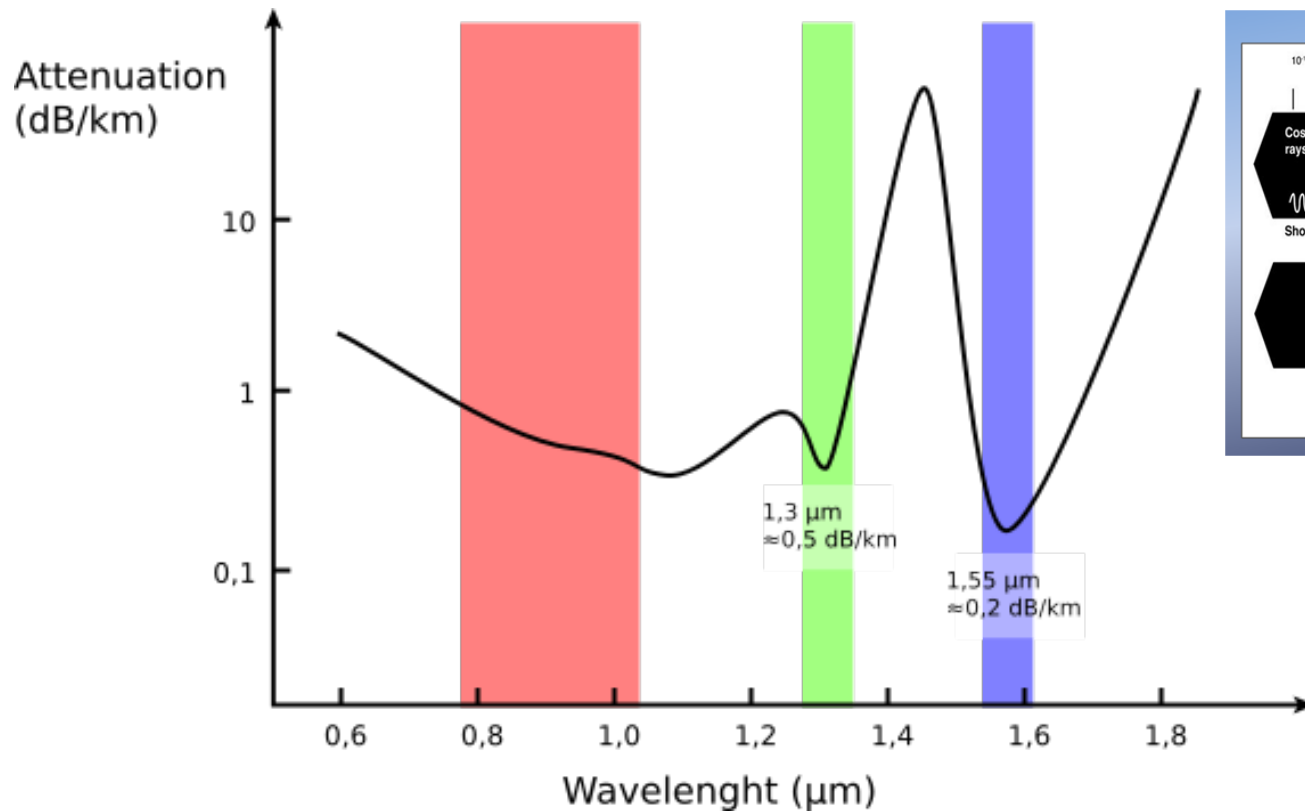


$$n_{\text{core}} > n_{\text{cladding}}$$

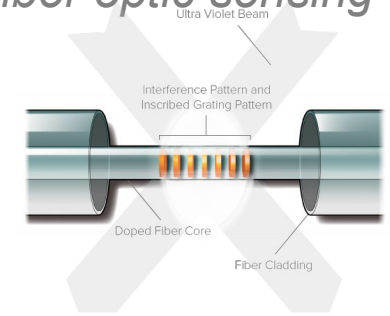
- $\theta_i > \theta_c \rightarrow \sin \theta_c = n_{\text{cladding}}/n_{\text{core}}$



# Attenuation of light in optical fibers

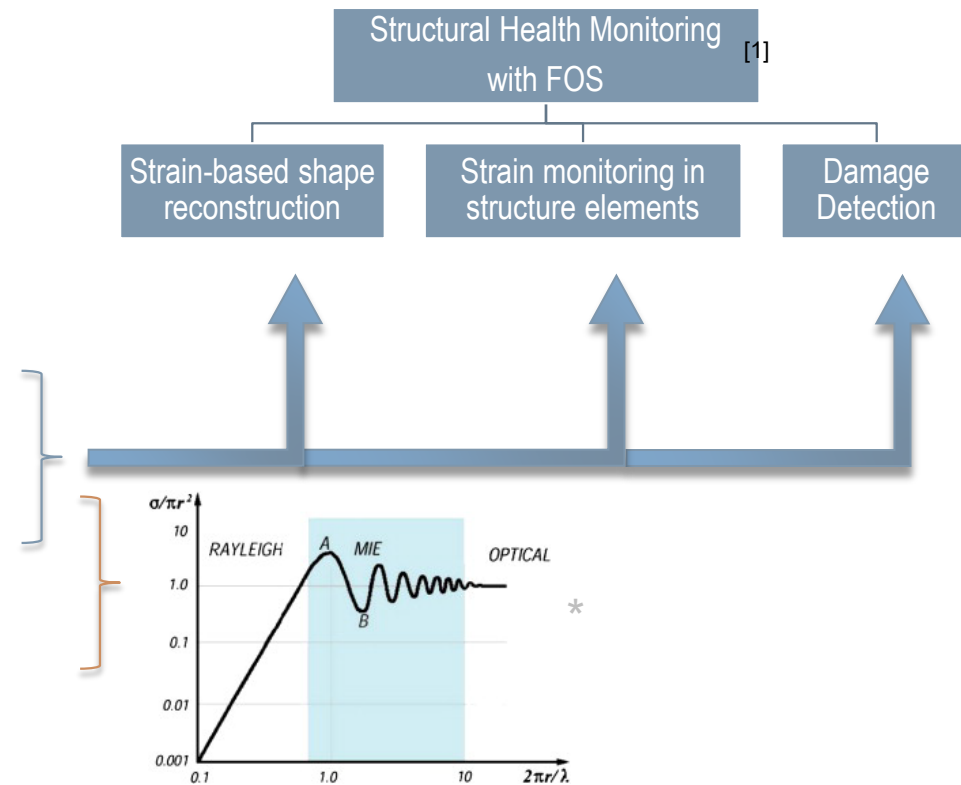
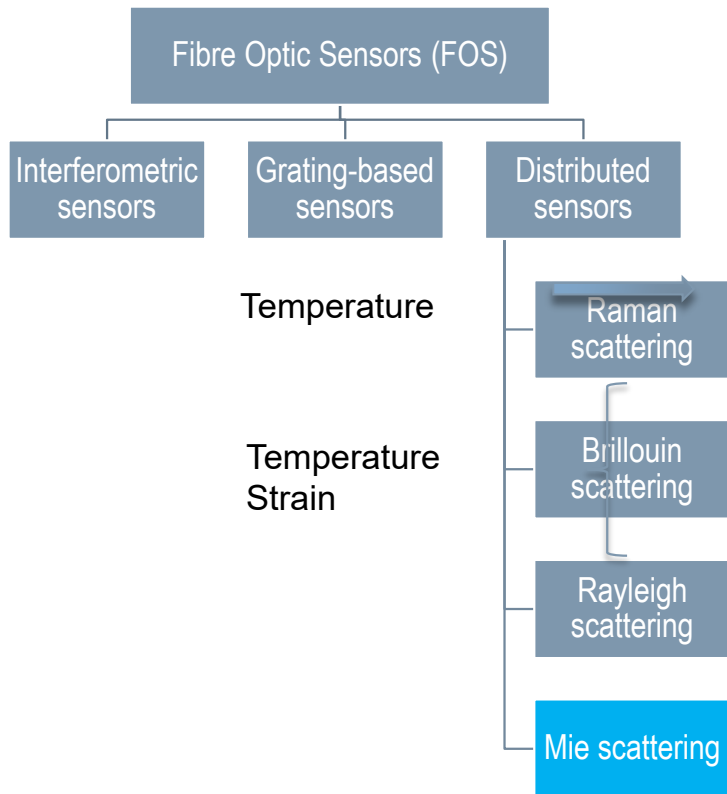


- 3dB = 50%
- 1 dB = 10%



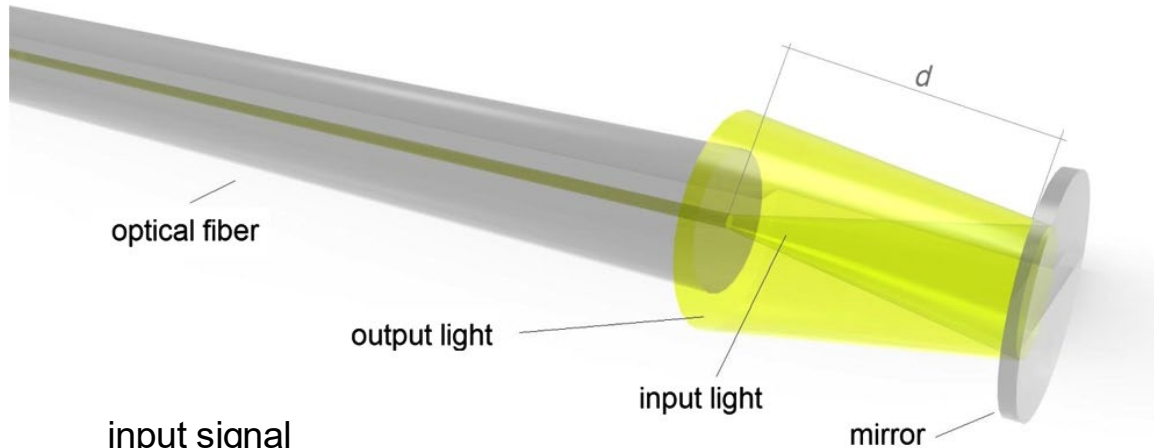
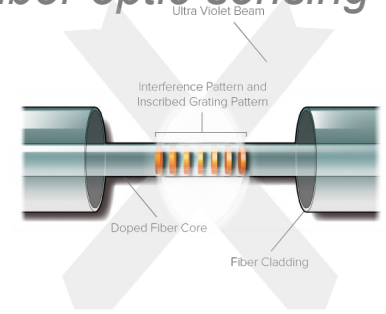
# *Fibre optic sensing principles*

# Types of Fibre Optic Sensors

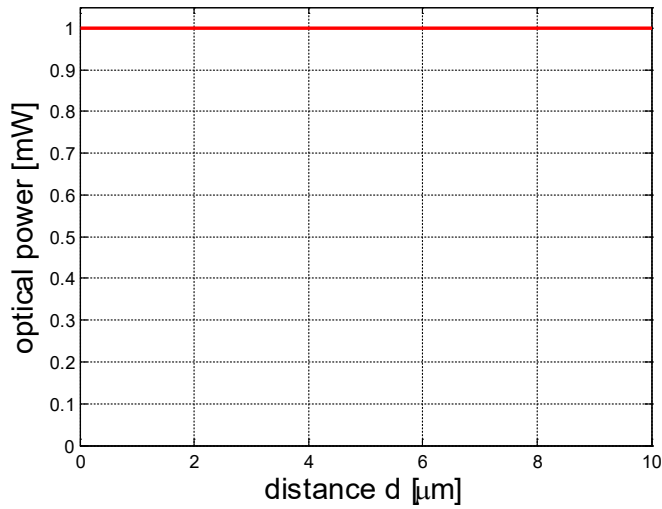


# Optical fiber intensity sensor

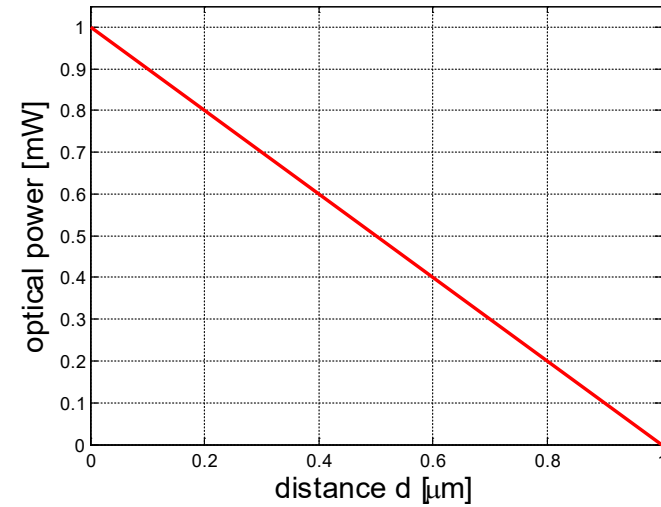
fiber optic sensing



input signal



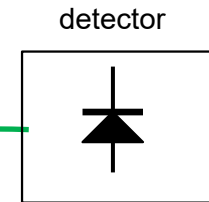
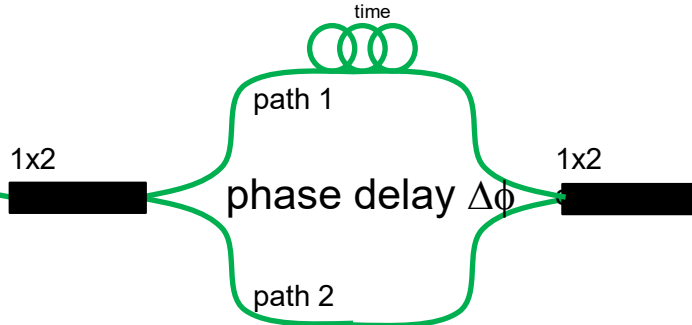
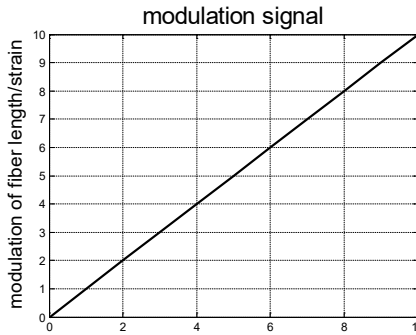
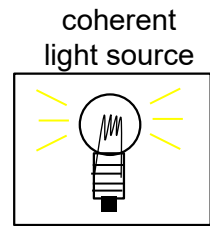
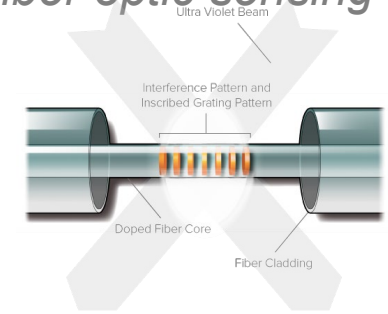
output signal





# Optical fiber phase sensor

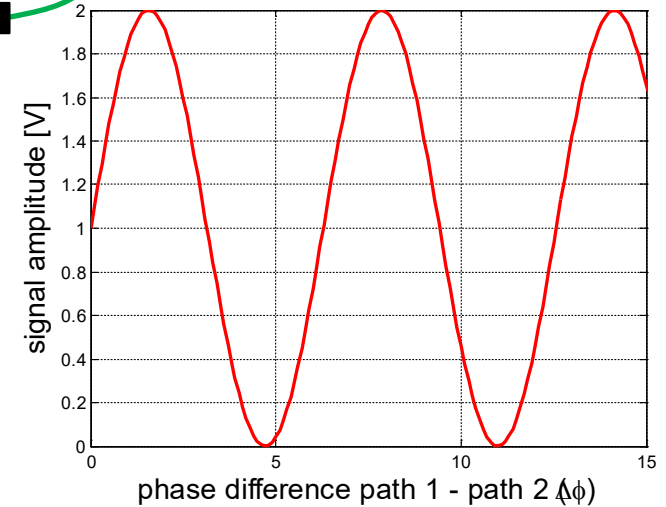
*fiber optic sensing*

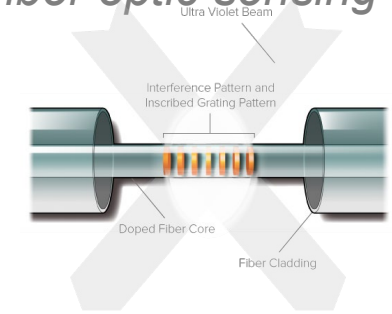


$$\phi = \frac{2\pi \cdot n \cdot L}{\lambda}$$

$$\delta\phi = \frac{2\pi}{\lambda} \delta(n \cdot L)$$

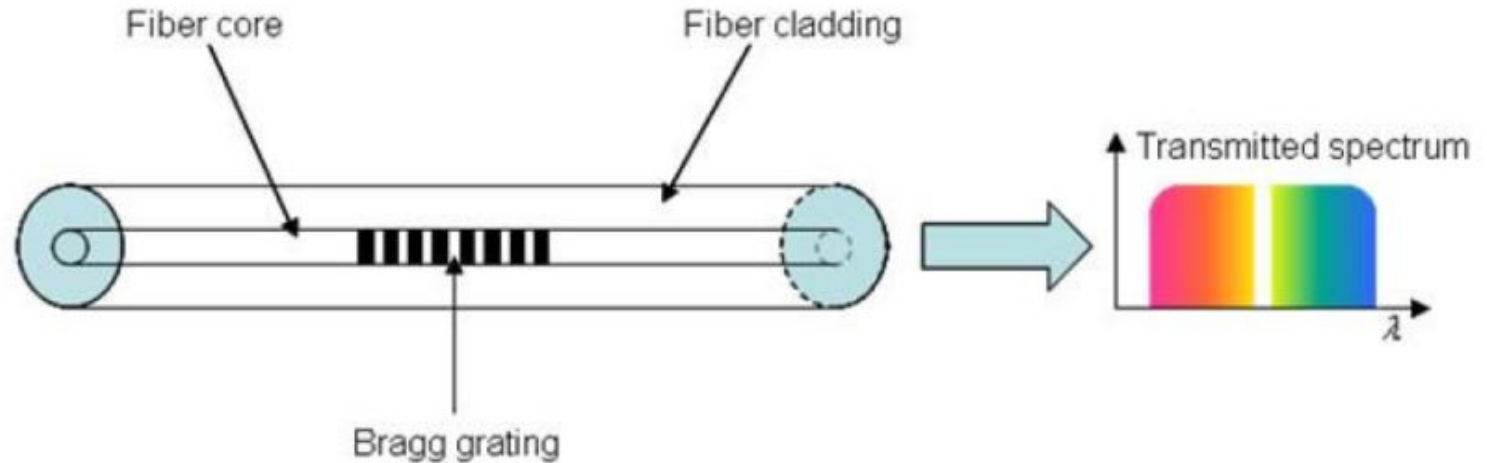
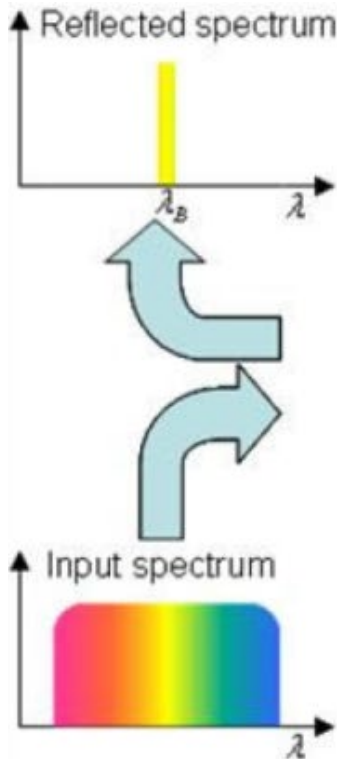
$$L = |\text{path1} - \text{path2}|$$





# Optical fiber wavelength sensor

## Fiber Bragg Grating (FBG)



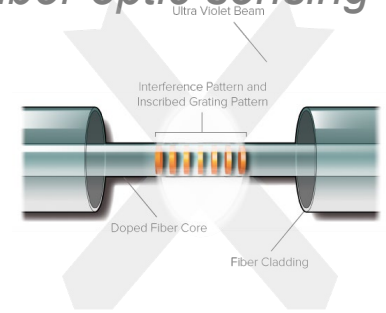
**Benefits:**

- insensitive for intensity variations
- multiplexing capabilities

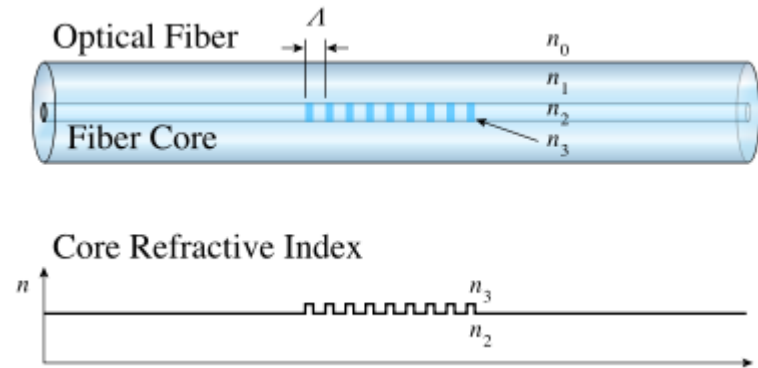
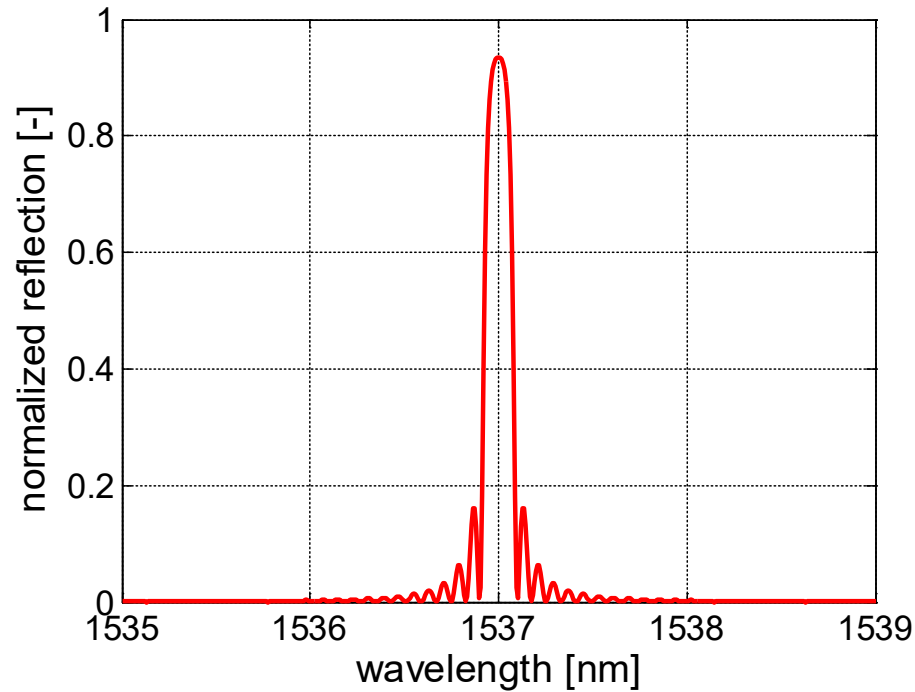
**Drawbacks:**

- expensive read out equipment

# Optical fibre sensor – focus on FBG's

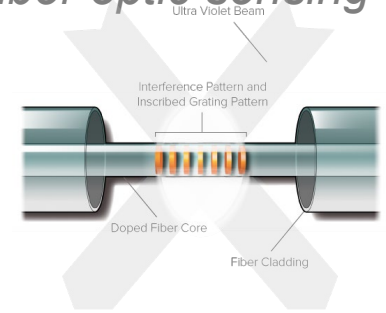


$$\lambda_B = 2 \cdot n_{\text{eff}} \cdot \Lambda$$



# Optical fibre sensor – focus on FBG's

fiber optic sensing



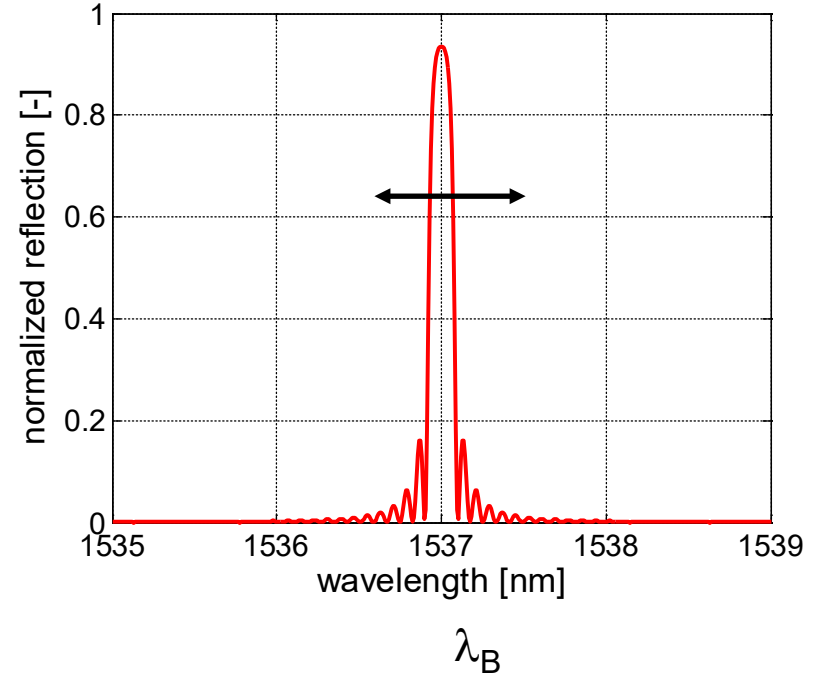
$$\lambda_B = 2 \cdot n_{\text{eff}} \cdot \Lambda$$

strain ( $\varepsilon$ ) sensitivity :

- $\frac{\Delta L}{L} = \varepsilon \rightarrow \frac{\delta \lambda_B}{\delta \varepsilon} = 1.2 \text{ pm} / \mu \varepsilon$

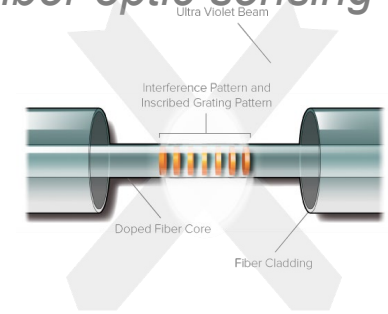
temperature (K) sensitivity:

- $\frac{\delta \lambda_B}{\delta T} \approx 10 \text{ pm} / \text{K}$

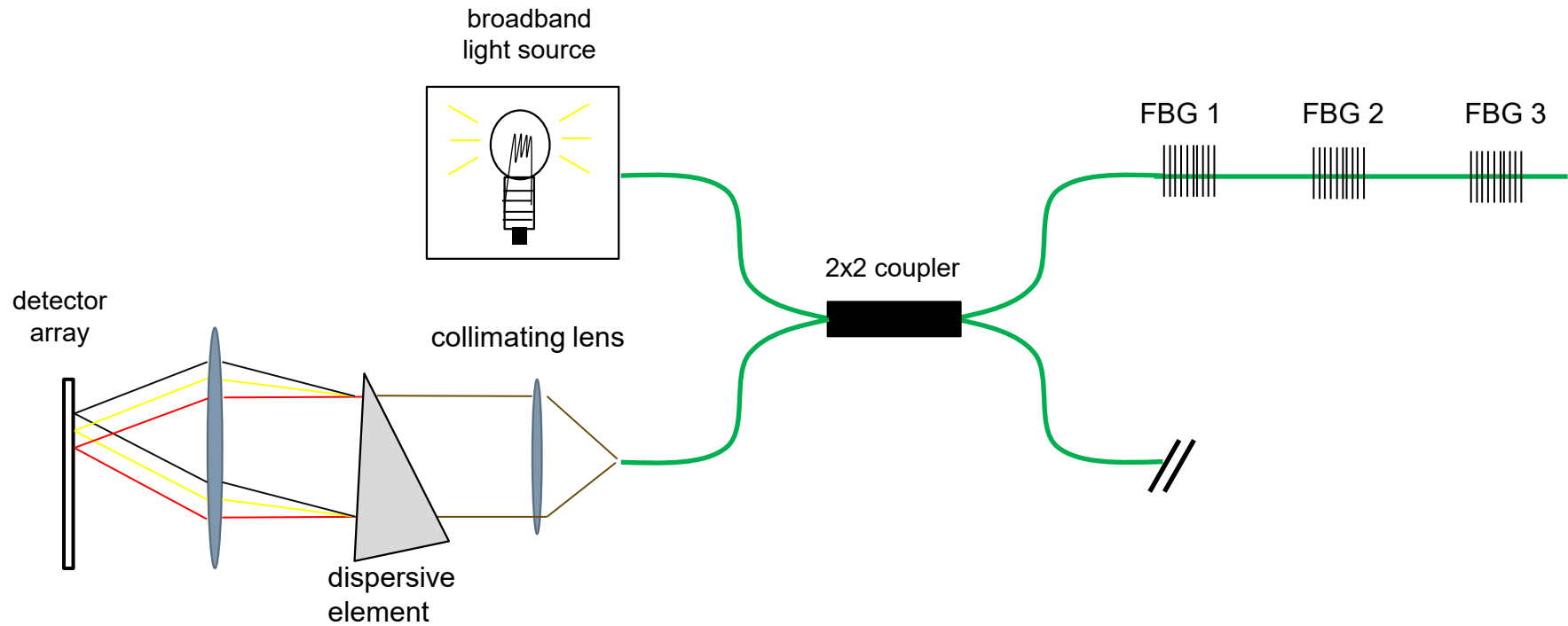


# Optical fibre sensor – Wavelength detection

*fiber optic sensing*

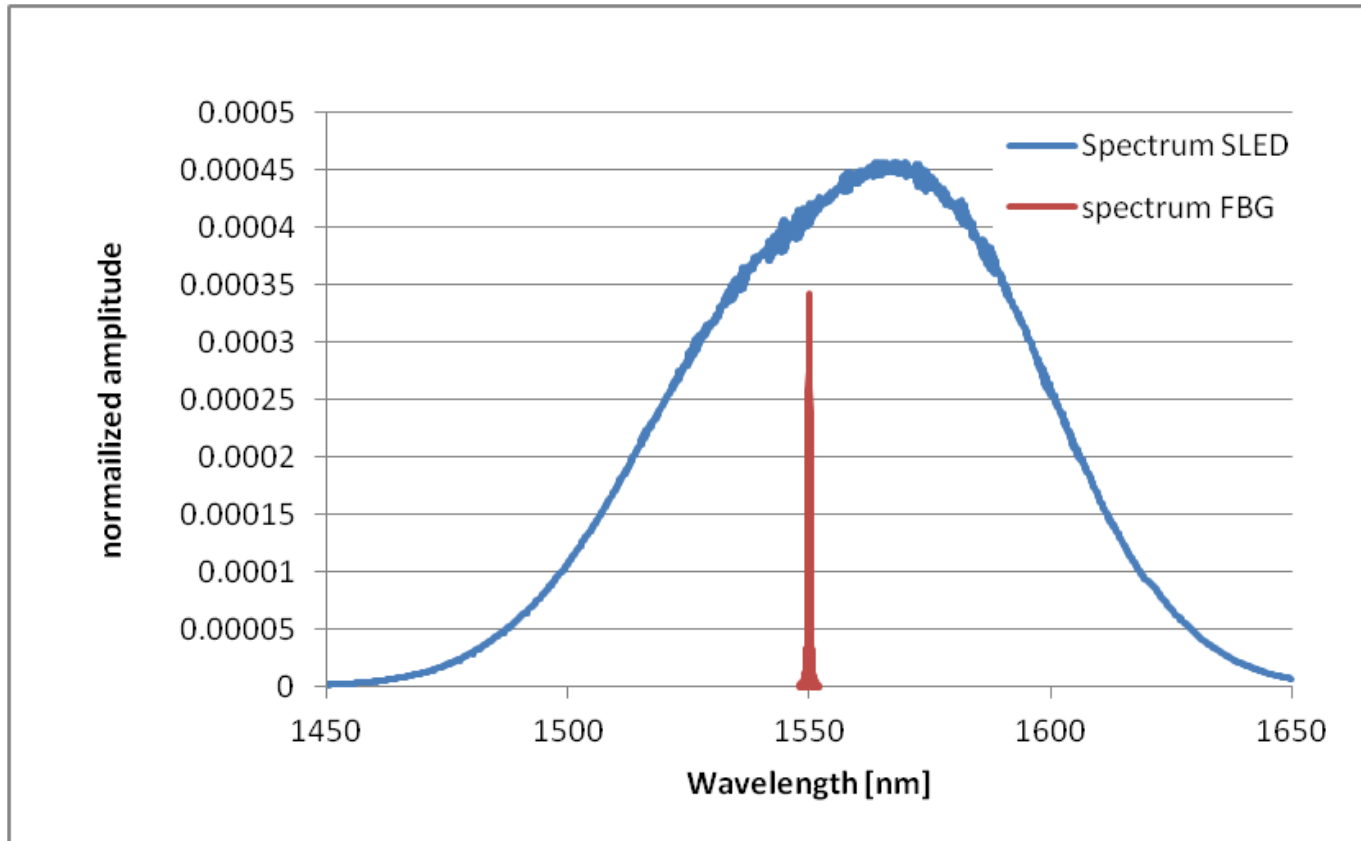
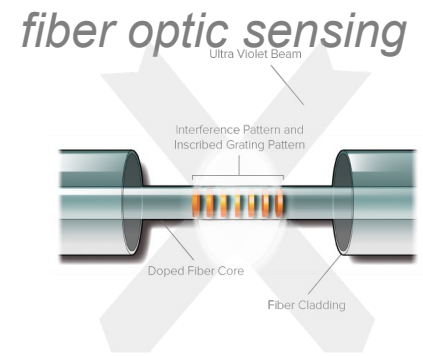


interrogator concept 1: *spectrometer design*



# Optical fibre sensor – Wavelength detection

*spectrometer design*



## **Benefits:**

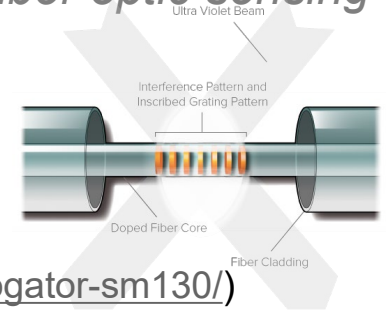
- all FBG's interrogated simultaneously

## **Drawbacks:**

- >99% of the light is lost

# Optical fibre sensor – Wavelength detection

fiber optic sensing



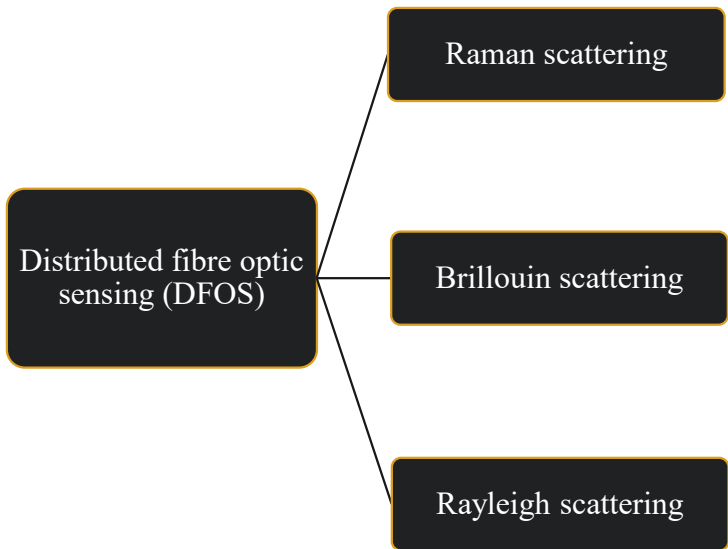
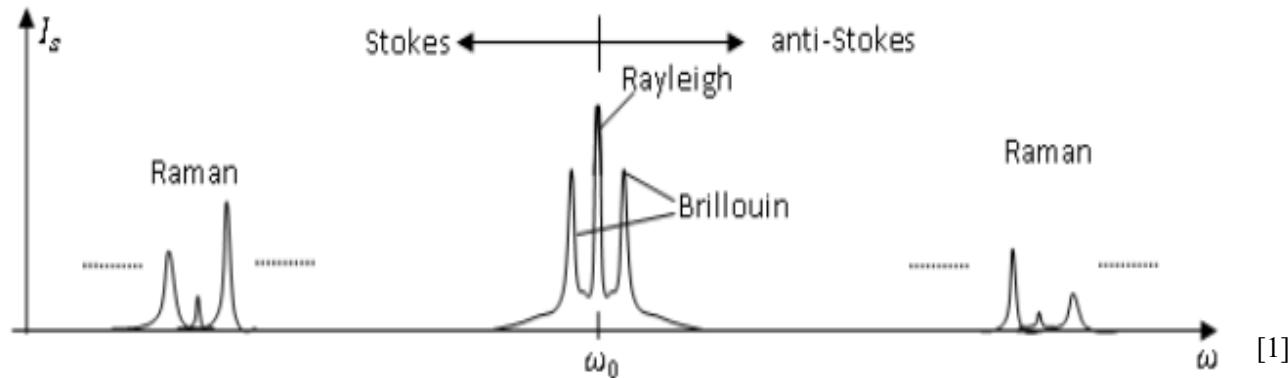
Many different commercial interrogators available:

- MicronOptics (<http://www.micronoptics.com/product/dynamic-optical-sensing-interrogator-sm130/>)
- SmartFibres (<https://www.smartfibres.com/docs/SmartScan.pdf>)
- HBM FiberSensing (<https://www.hbm.com/en/2322/optical-interrogators-from-hbm-fibersensing/>)
- Redondo ([http://www.redondooptics.com/FBGT\\_060209.pdf](http://www.redondooptics.com/FBGT_060209.pdf))
- National Instruments (<http://sine.ni.com/nips/cds/view/p/lang/nl/nid/209012>)
- FAZtechnology (<http://www.faztechnology.com/products/interrogators/fazt-v4/>)
- Technobis (<http://www.technobis.com/index.php/products/extreme-fiber-sensing/gator-basic-fbg-interrogator/>)
- ATgrating (<http://www.atgrating.com/en/productview.asp?id=87>)
- Bayspec (<http://www.bayspec.com/telecom-fiber-sensing/fbg-interrogation-analyzer/>)
- Proximion (<http://www.proximion.com/fiber-optic-sensors/>)
- Epsilonoptics (<http://www.epsilonoptics.com/interrogators.html>)
- and many more ....

Note: >95% of the interrogators are based on concept 2 – scanning laser



# Rayleigh, Raman and Brillouin Scattering



$$\frac{I_{AS}}{I_S} = \left(\frac{\lambda_S}{\lambda_{AS}}\right)^4 e^{-\frac{\hbar\omega_M}{k_B T}} \quad [1]$$

$$\Delta\nu_B = C_T \Delta T + C_\varepsilon \Delta\varepsilon \quad [1]$$

$$\frac{\Delta\lambda}{\lambda} = K_T \Delta T + K_\varepsilon \Delta\varepsilon \quad [2]$$

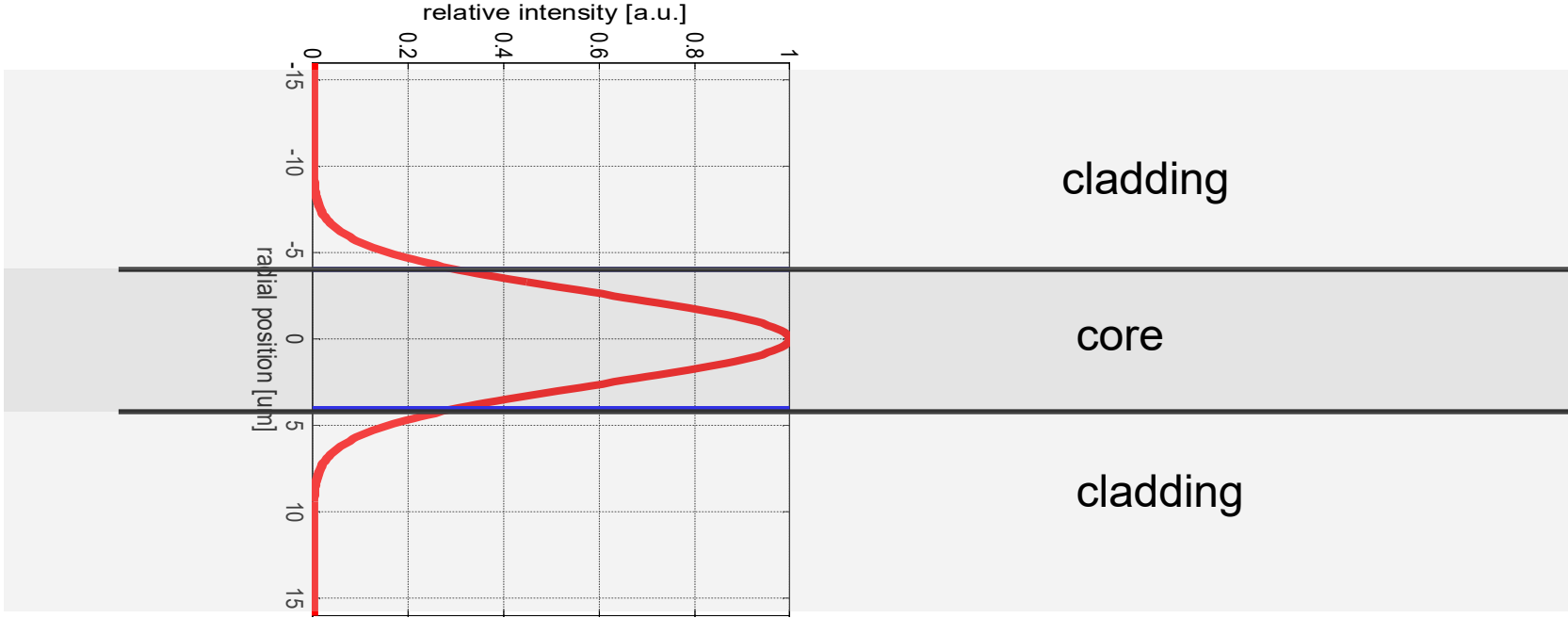
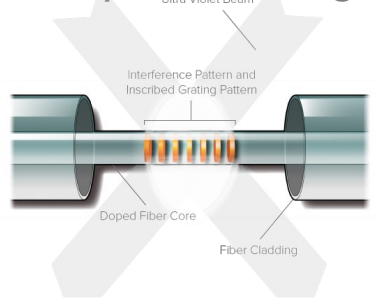
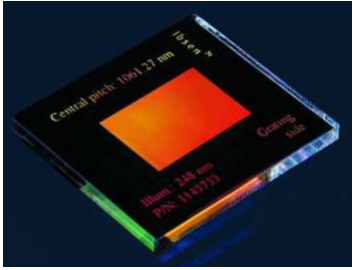
[1] X. Bao and L. Chen, "Recent Progress in Distributed Fiber Optic Sensors," *Sensors (Switzerland)*, vol. 12, no. 7, pp. 8601–8639, 2012.

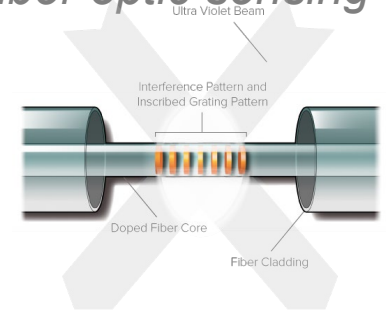
[2] S. T. Kreger, A. K. Sang, D. K. Gifford, and M. E. Froggatt, "Distributed strain and temperature sensing in plastic optical fiber using Rayleigh scatter," *Fiber Opt. Sensors Appl. VI*, vol. 7316, no. April 2009, p. 73160A, 2009.



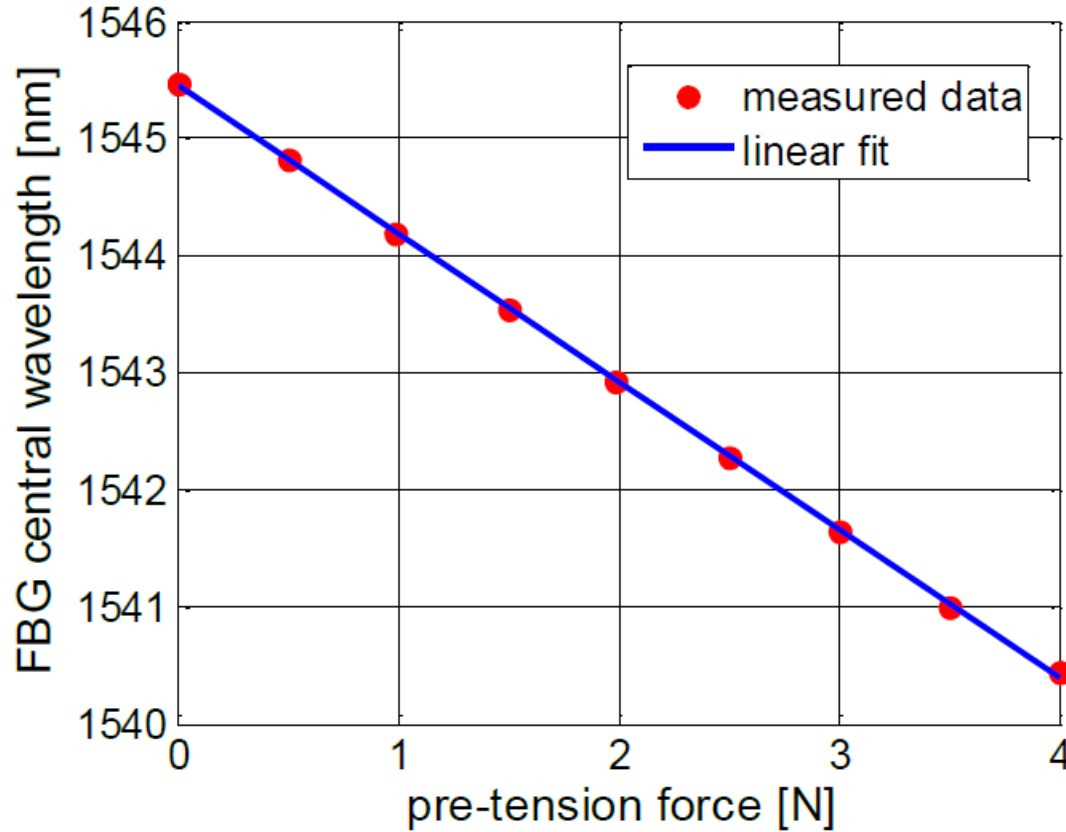
# RI modulation

$$\lambda_B = n_{\text{eff}}(\lambda) \cdot \Lambda_{\text{pm}}$$





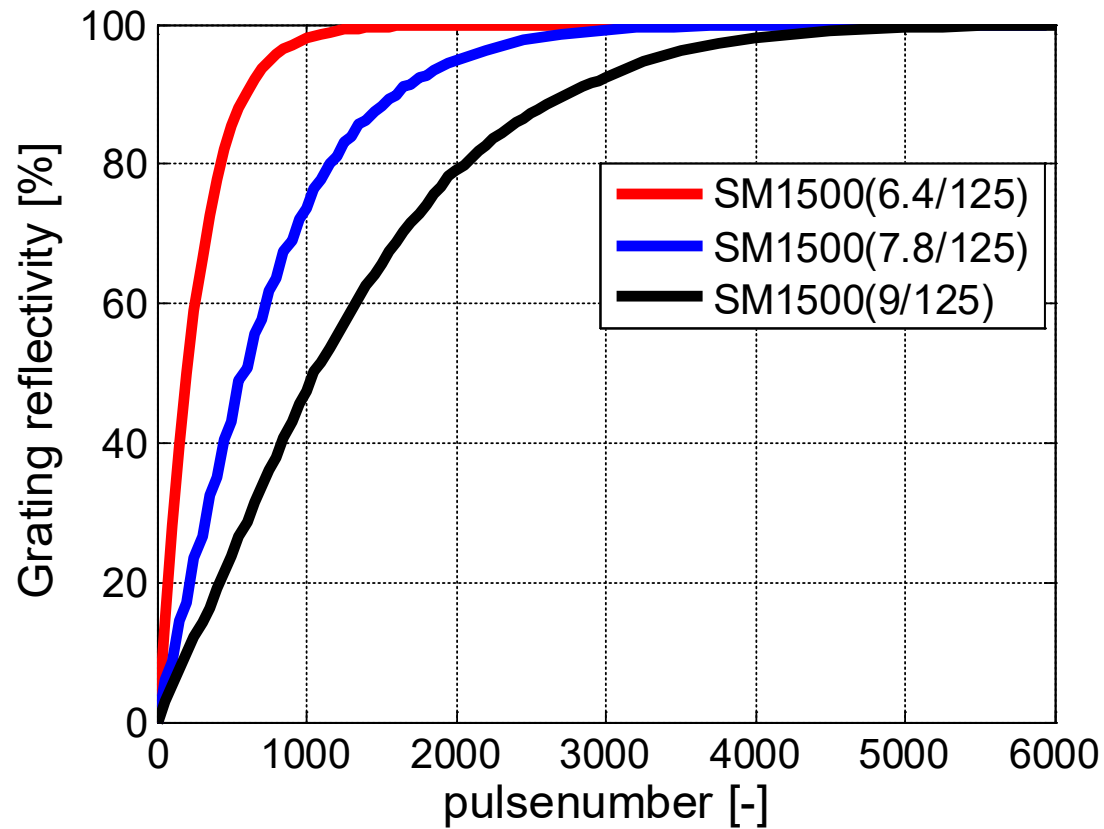
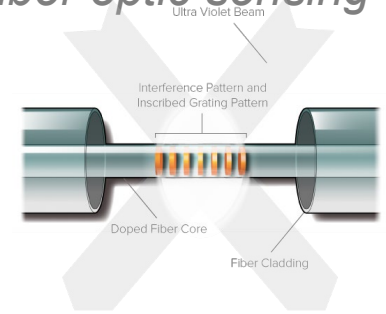
# Fibre pretension



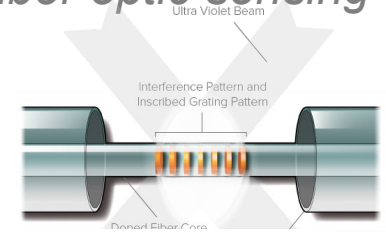
~5nm  $\lambda_B$  correction

# Reflectivity

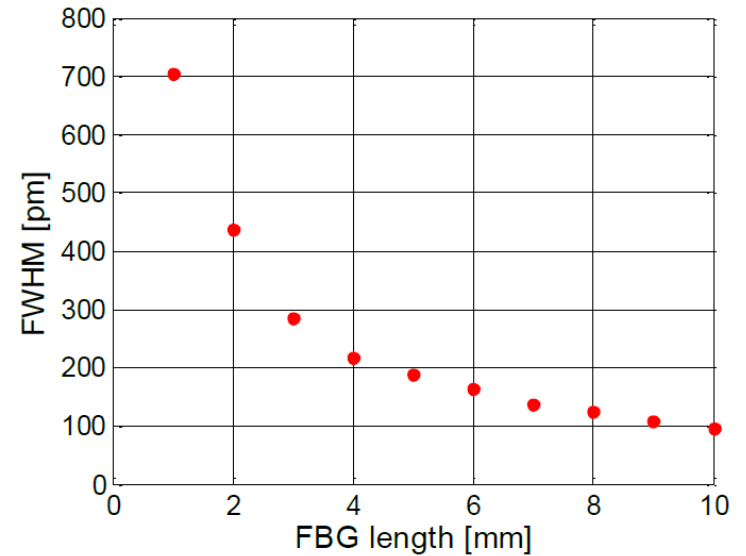
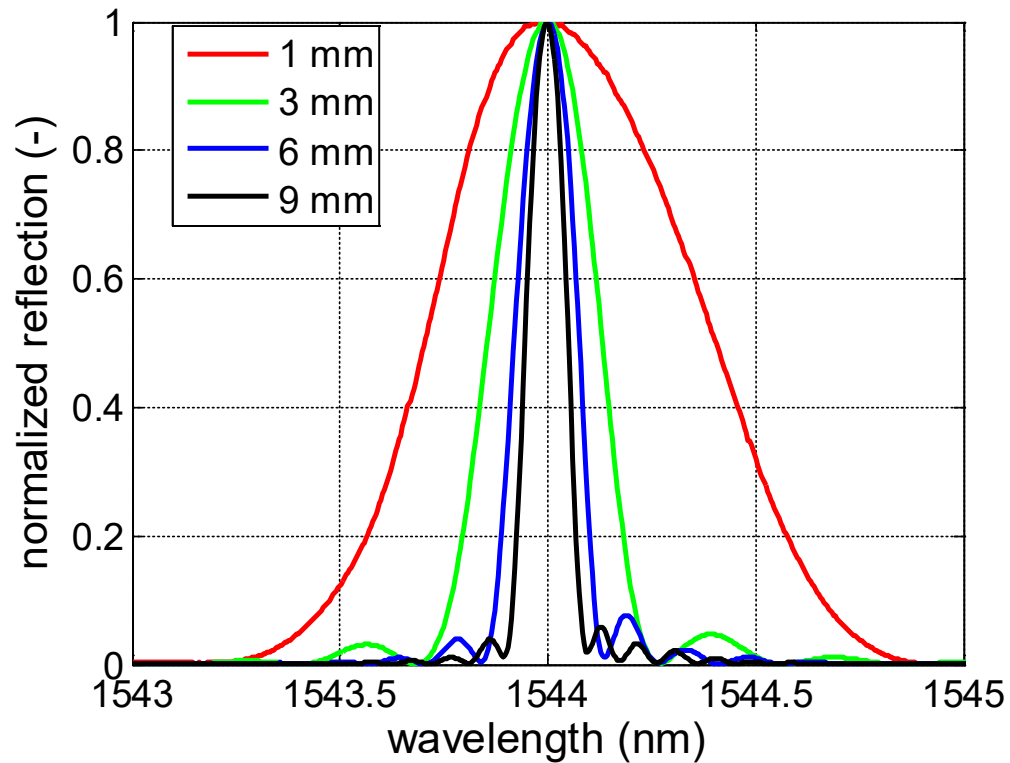
## fiber optic sensing

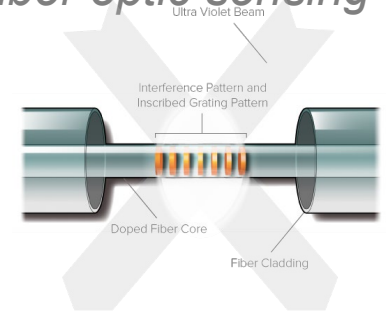


- Repetition rate of UV laser is 500 Hz



# Grating length



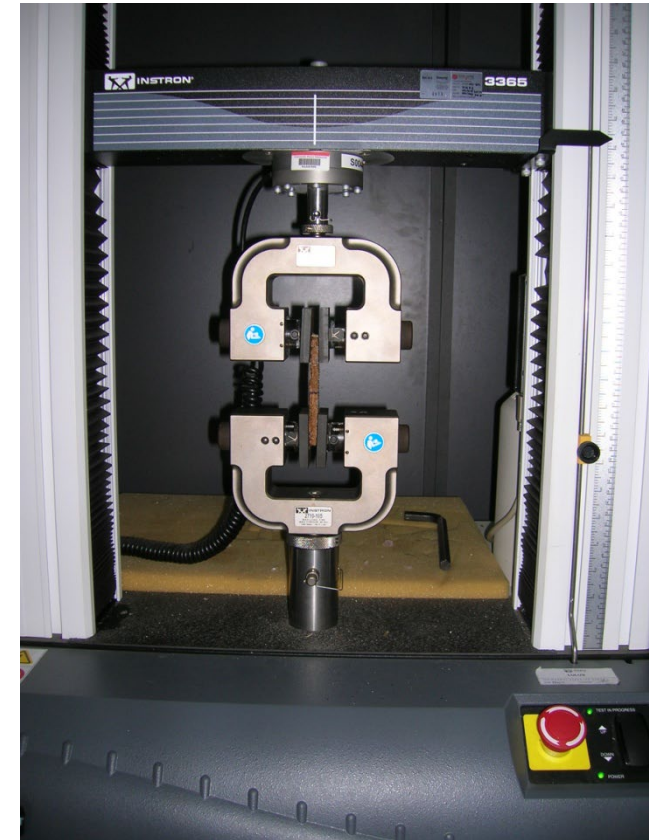


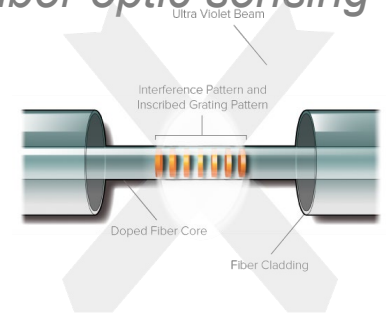
# Fibre break strength

- Break strength of pristine fiber ~60N
- Stripping and recoating reduces fiber strength to ~10-15 N

$$\epsilon = \frac{F}{E \cdot A}$$

fiber strain  $\leftarrow \epsilon$   
 force on fiber  $\leftarrow F$   
 Youngs modulus (72GPa)  $\leftarrow E$   
 fiber surface =  $(\pi/4) \cdot \text{diameter}^2$   $\leftarrow A$

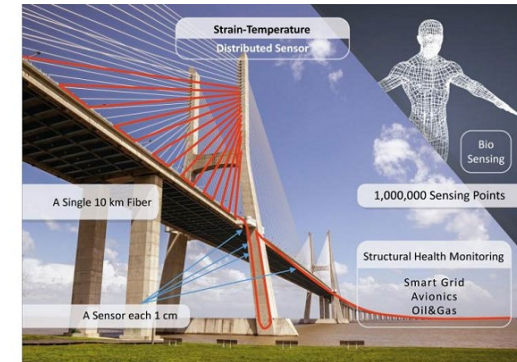


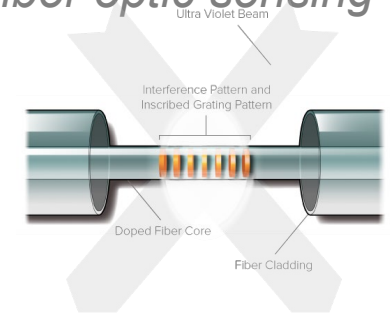


# *Fibre optic sensing applications*

# Introduction

Fibre optic sensing can obtain parameters such as strain, temperature, etc. for Structural Health Monitoring.





# *Research of PhD Nakash Nazeer*

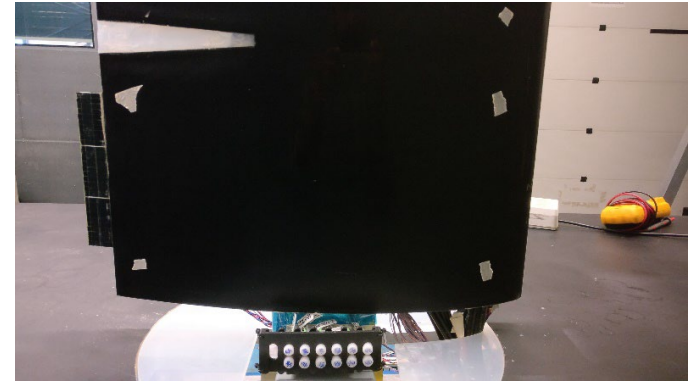


# SmartX Morphing Wing



6 individual morphing sections

Upper wing section view  
Morphing section #1



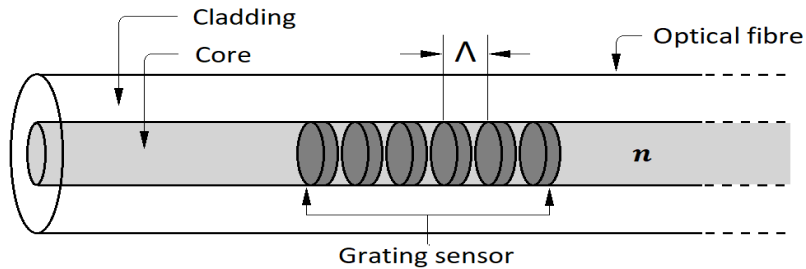
Section #1

Lower wing section view  
Morphing section #1

# Sensor Principles

## Bragg Grating

$$\lambda_B = 2n_{eff}\Lambda$$



Input



Reflected



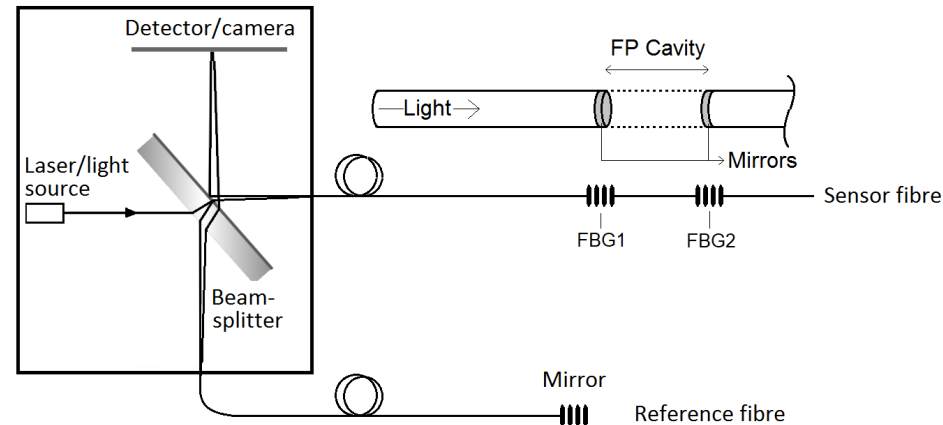
Output

$\Lambda$ : Periodic spacing  
 $\lambda_B$ : Grating wavelength  
 $n_{eff}$ : Core refractive index

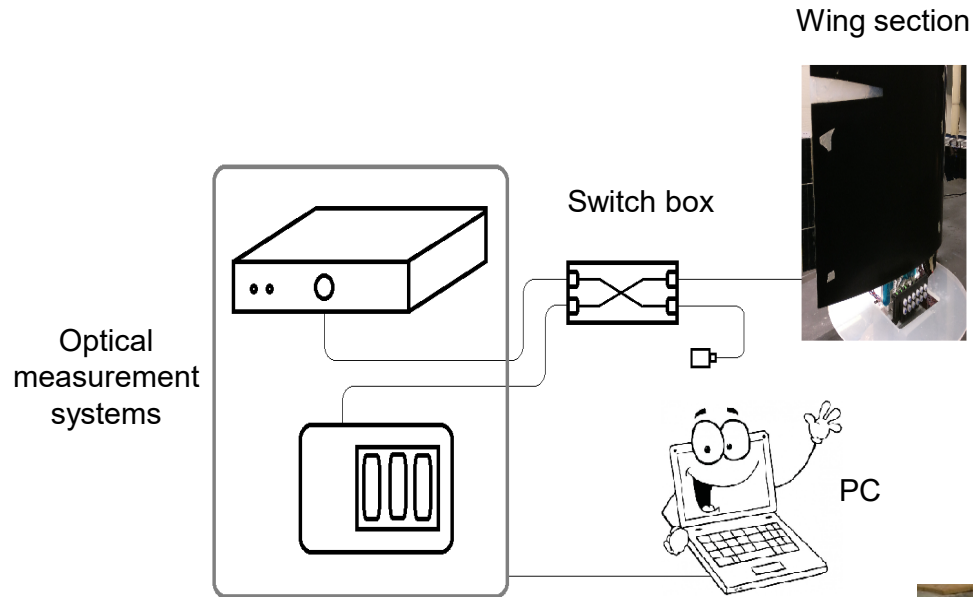
## Fabry-Pérot

$$\Delta\varepsilon = \frac{\Delta\lambda_{BS}}{(1 - \rho_a)\lambda_B}$$

$$\varepsilon = \frac{\Delta d}{L}$$

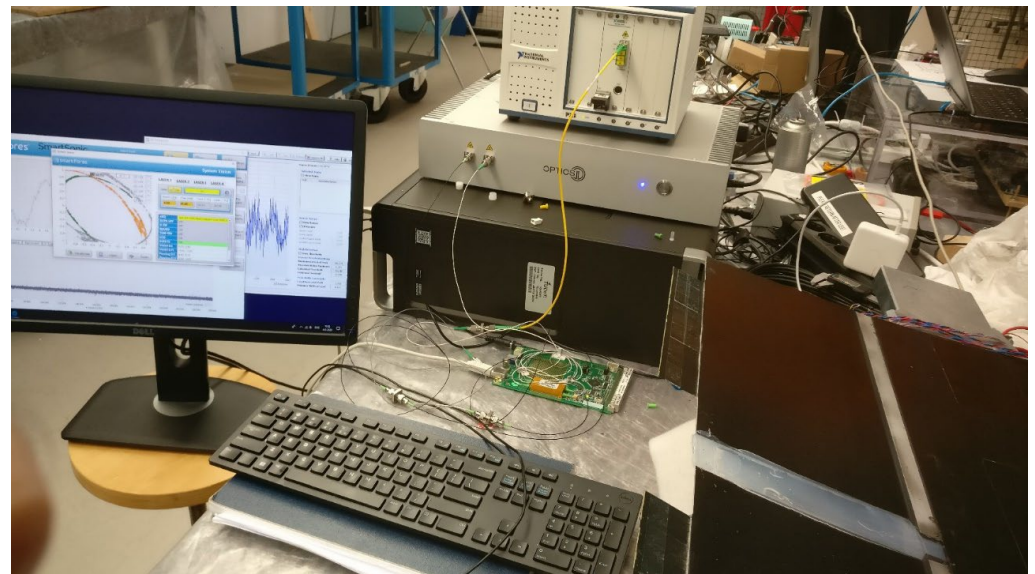


# Experimental Setup



## Test conditions

- Static tests
- Only morphing section #1 considered
- Offline measurement (Not in the wind tunnel)



# Bend up and bend down

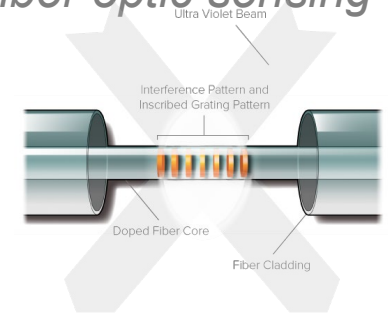
Bend up	(NI) $\epsilon$ FBG		(O11) $\Delta L$		Tip deflection (mm)	Estimated tip deflection (mm)	Error (mm)
	FBG_2 ( $\mu$ )	FBG_3 ( $\mu$ )	$\Delta L$ FP_1-2 ( $\mu$ m)	$\Delta L$ FP_3-4 ( $\mu$ m)			
Actuator input (deg)	FBG_2 ( $\mu$ )	FBG_3 ( $\mu$ )	$\Delta L$ FP_1-2 ( $\mu$ m)	$\Delta L$ FP_3-4 ( $\mu$ m)	Tip deflection (mm)	Estimated tip deflection (mm)	Error (mm)
5	143,17	144,00	-7,6	-7,598	2	2,1	0,1
10	300,31	306,72	-25,2	-25,414	6	1,93	-4,07
15	441,64	443,60	-78,4	-79,386	9	8,48	-1,69

Bend down	(NI) $\epsilon$ FBG		(O11) $\Delta L$		Tip deflection (mm)	Estimated tip deflection (mm)	Error (mm)
	FBG_2 ( $\mu$ )	FBG_3 ( $\mu$ )	$\Delta L$ FP_1-2 ( $\mu$ m)	$\Delta L$ FP_3-4 ( $\mu$ m)			
Actuator input (deg)	FBG_2 ( $\mu$ )	FBG_3 ( $\mu$ )	$\Delta L$ FP_1-2 ( $\mu$ m)	$\Delta L$ FP_3-4 ( $\mu$ m)	Tip deflection (mm)	Estimated tip deflection (mm)	Error (mm)
5	-138,00	-137,00	8,4	8,346	5	3,16	-1,84
10	-287,32	-280,00	29,0	27,178	10	11,58	1,58
15	-427,14	-423,00	86	85,6	15	13,31	-1,69

# Twist

<b>Right</b>	<b>(NI) <math>\epsilon</math> FBG</b>		<b>(O11) <math>\Delta L</math></b>				
Actuator input (deg)	FBG_1 ( $\mu$ )	FBG_4 ( $\mu$ )	$\Delta L$ FP_1-2 ( $\mu$ )	$\Delta L$ FP_3-4 ( $\mu$ )	Tip deflection (mm)	Estimated tip deflection (mm)	Error (mm)
5	-24,05	23,8	-5	6	<b>2</b>	<b>0.66</b>	-1.34
10	-53,65	51,3	-8,5	16	<b>4</b>	<b>5.18</b>	1.18
15	-101,75	100	-11	25	<b>6</b>	<b>5,98</b>	-0.02

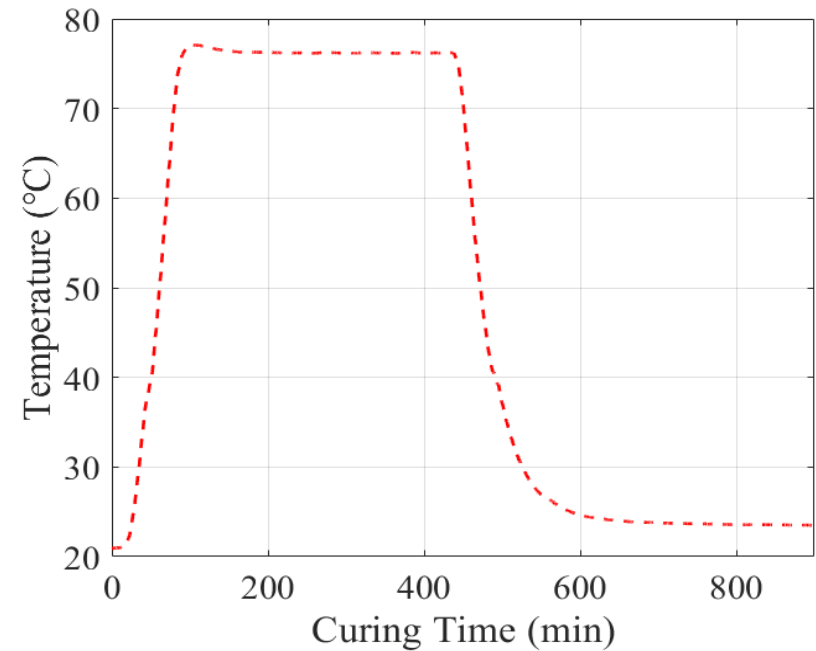
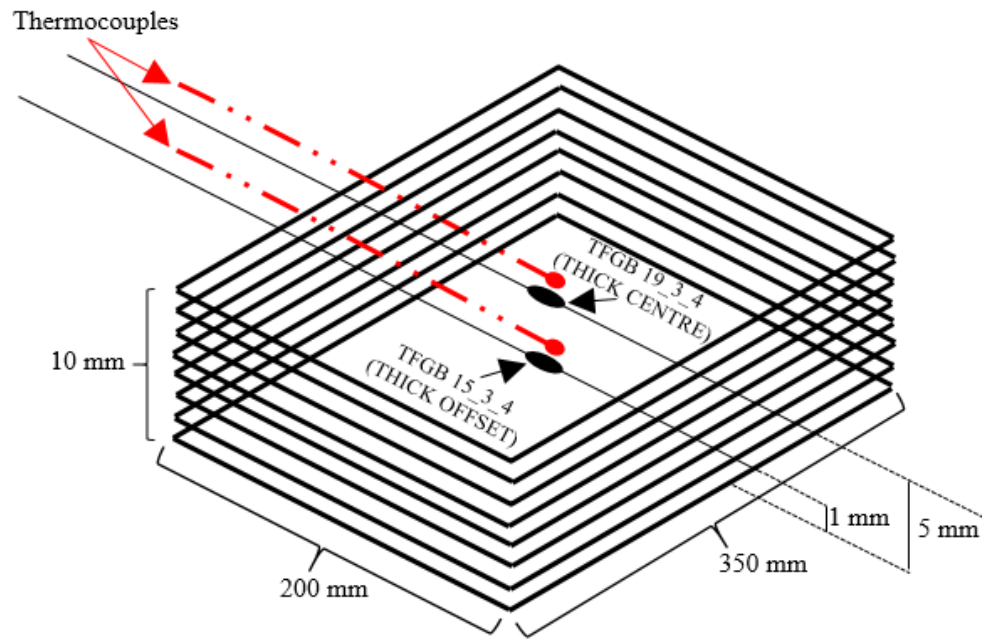
<b>Left</b>	<b>(NI) <math>\epsilon</math> FBG</b>		<b>(O11) <math>\Delta L</math></b>				
Actuator input (deg)	FBG_1 ( $\mu$ )	FBG_4 ( $\mu$ )	$\Delta L$ FP_1-2 ( $\mu$ )	$\Delta L$ FP_3-4 ( $\mu$ )	Tip deflection (mm)	Estimated tip deflection (mm)	Error (mm)
5	-24,05	23,8	-5	6	<b>2</b>	<b>1.25</b>	-0.75
10	-53,65	51,3	-8,5	16	<b>4</b>	<b>4.65</b>	0.65
15	-101,75	100	-11	25	<b>6</b>	<b>5.97</b>	-0.03



# *Research of PhD*

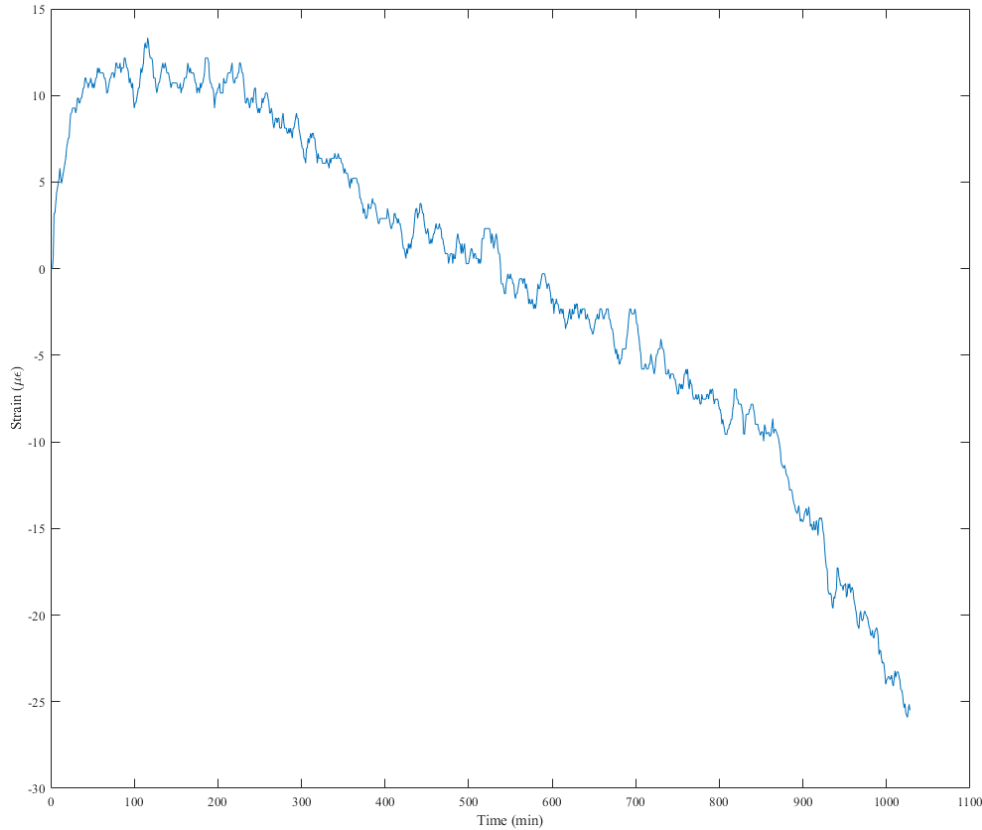
## *Luigi Fazzi*

# Thermoset composites curing with tilted FBG sensors

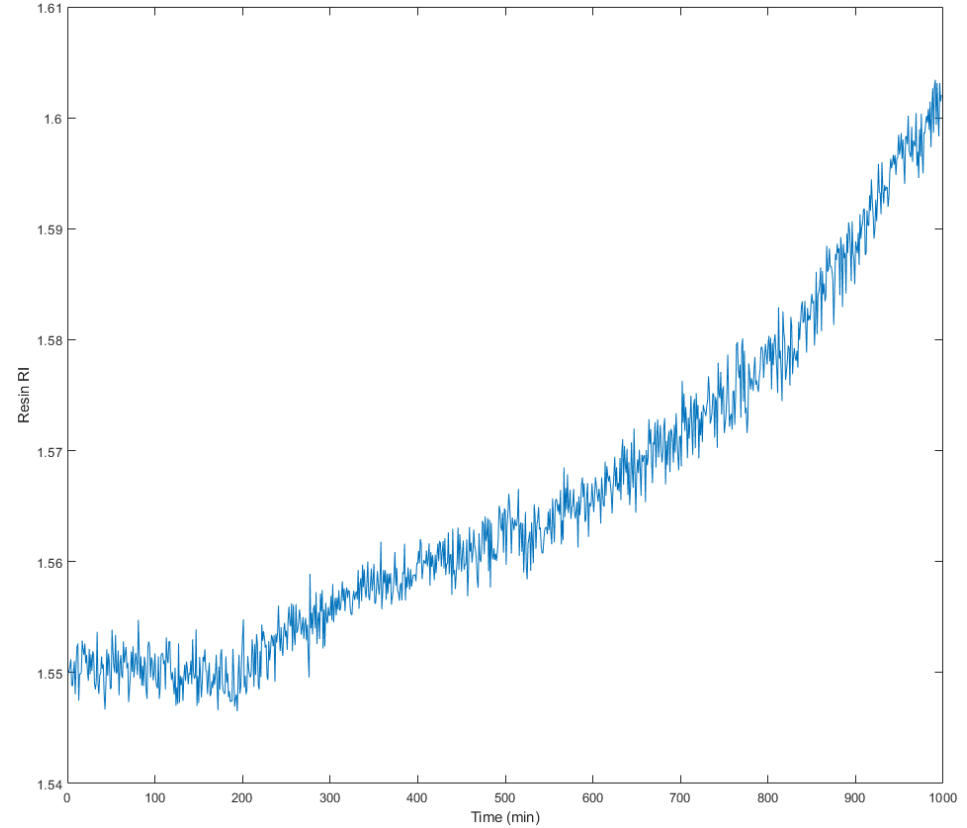




# 5 mm GFRP (curing at room temperature)



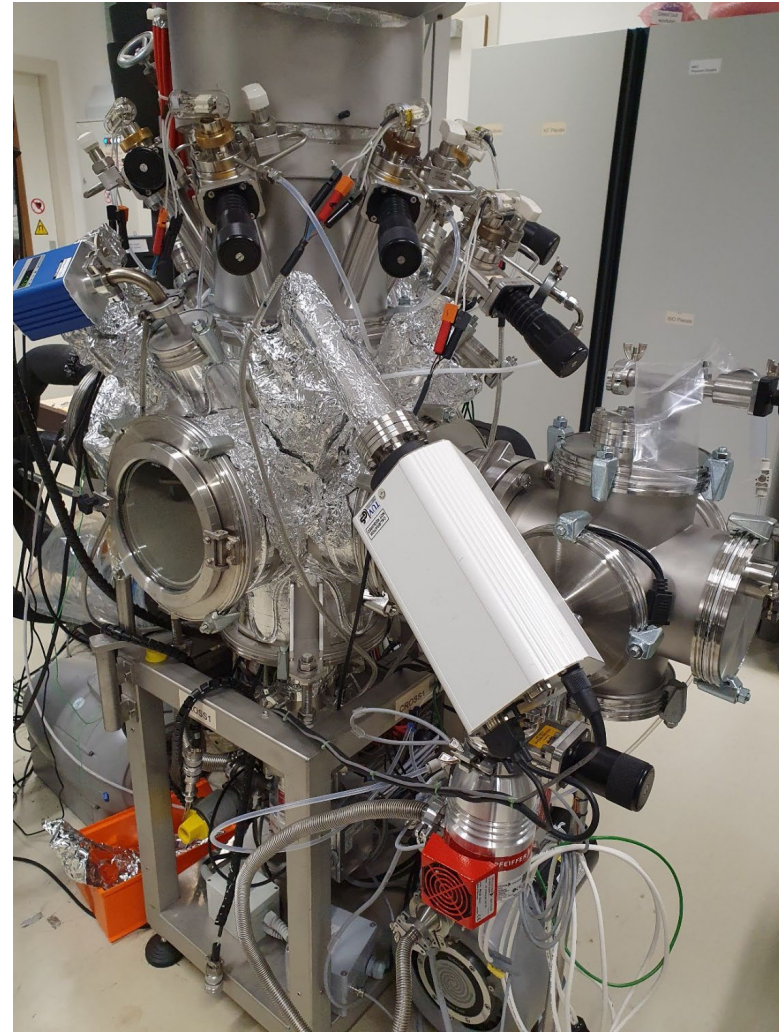
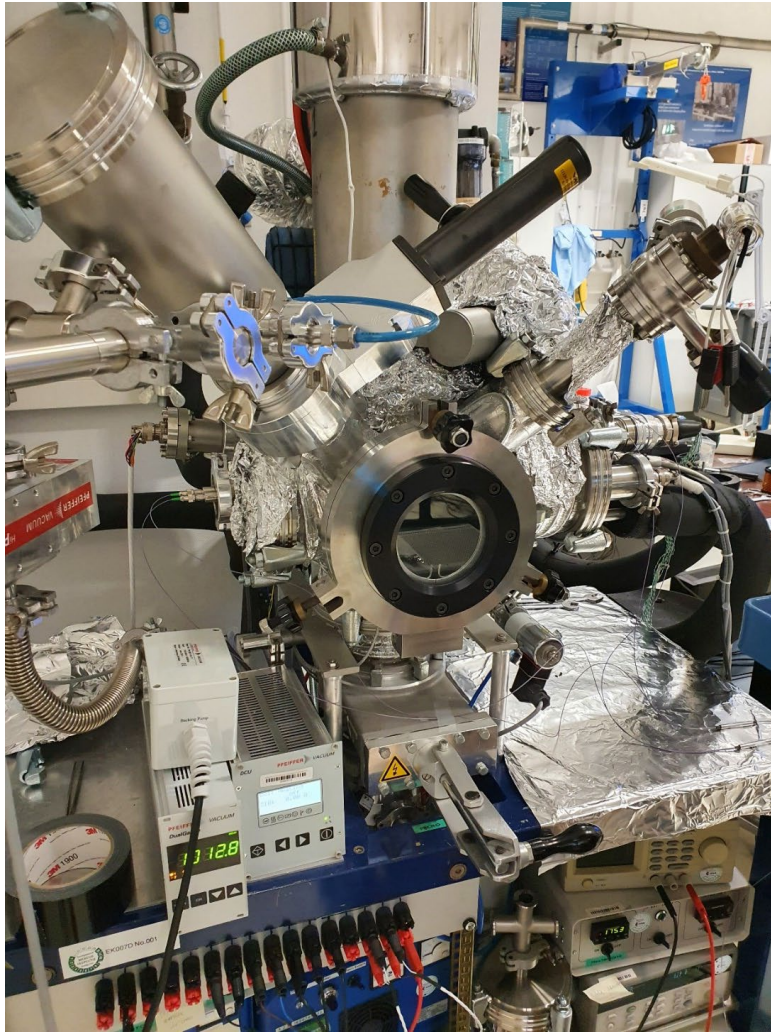
**Strain vs time**



**Resin RI vs time**

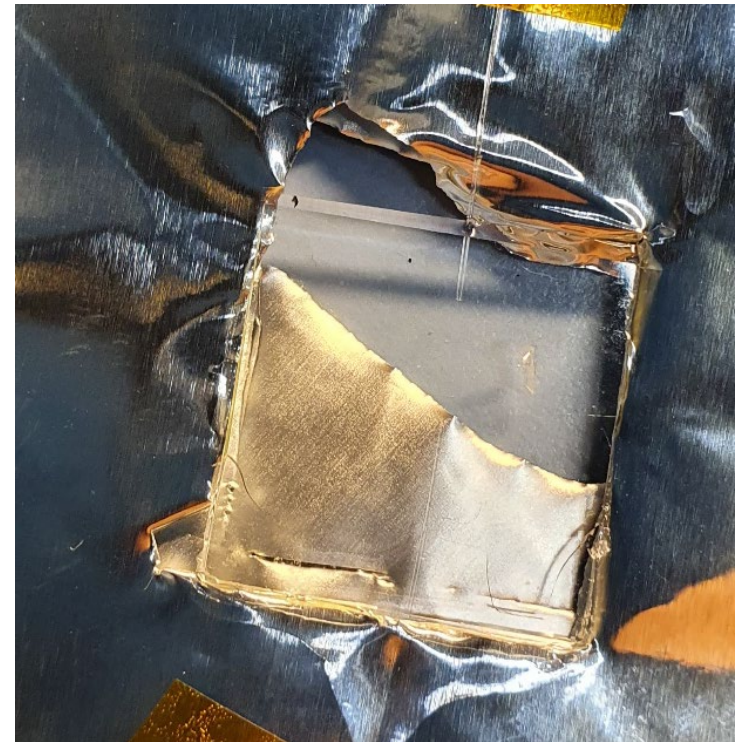
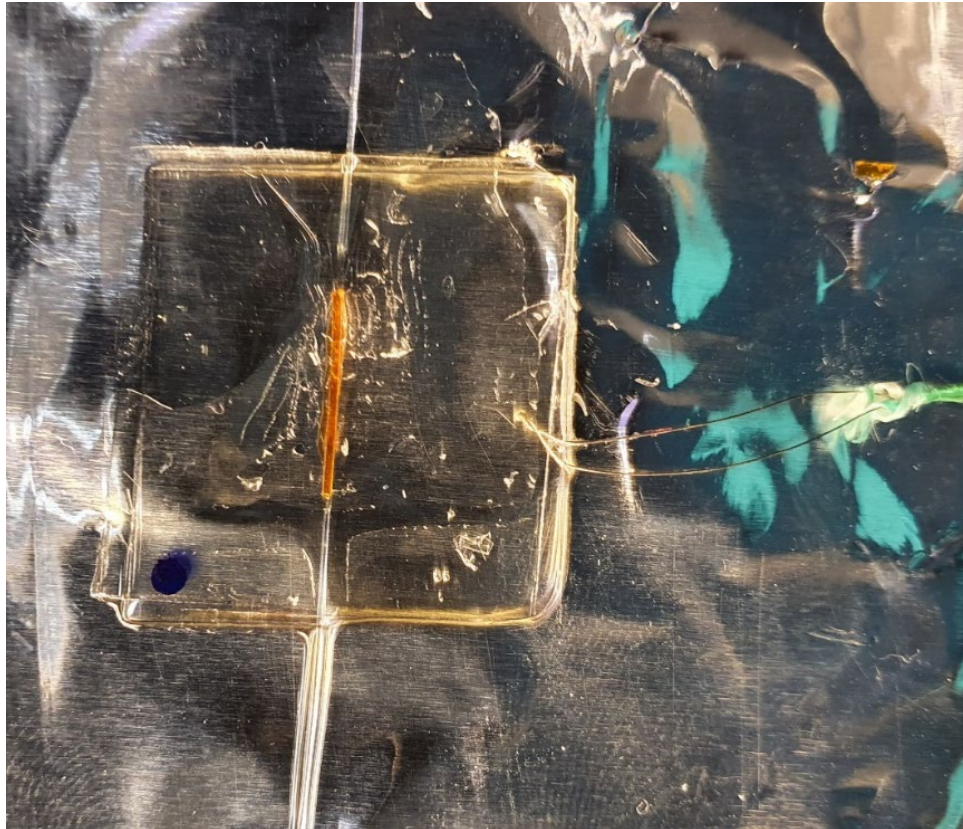


# Simulated space environment



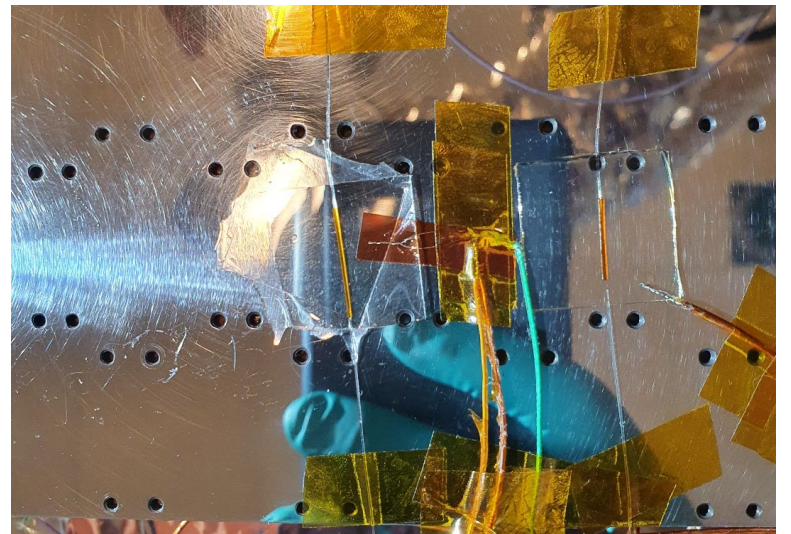
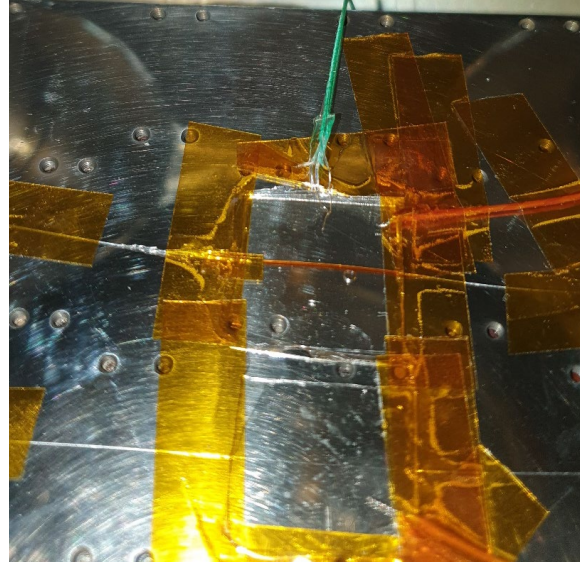
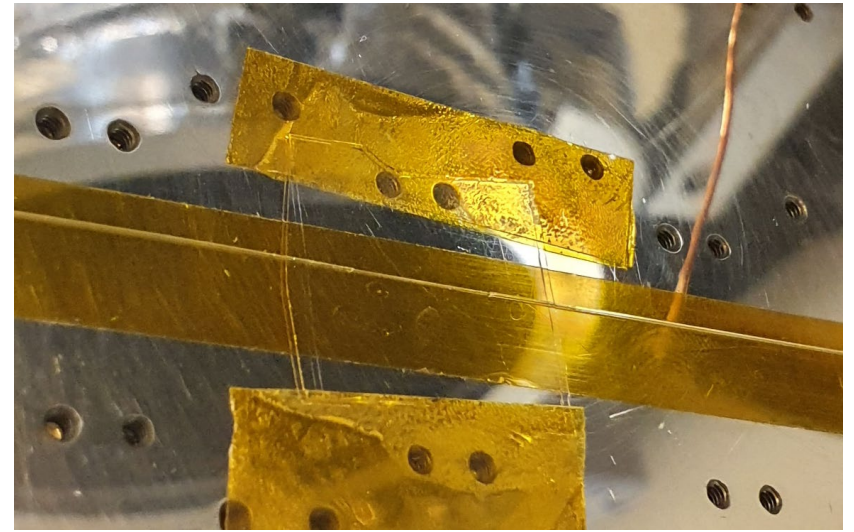
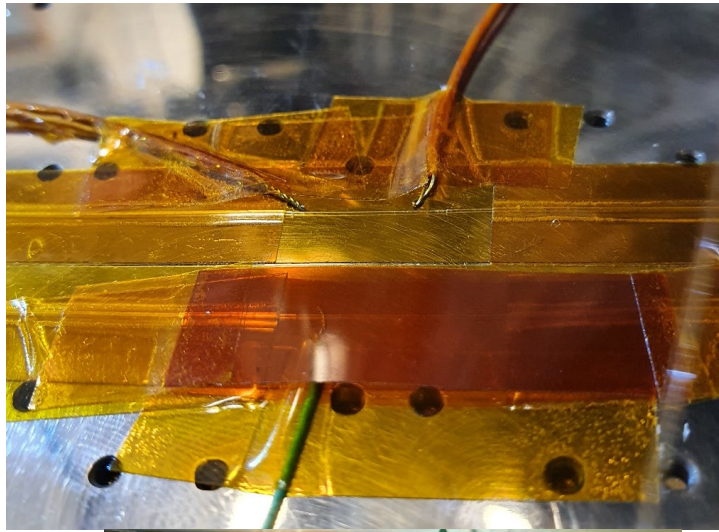


# Solar cell samples

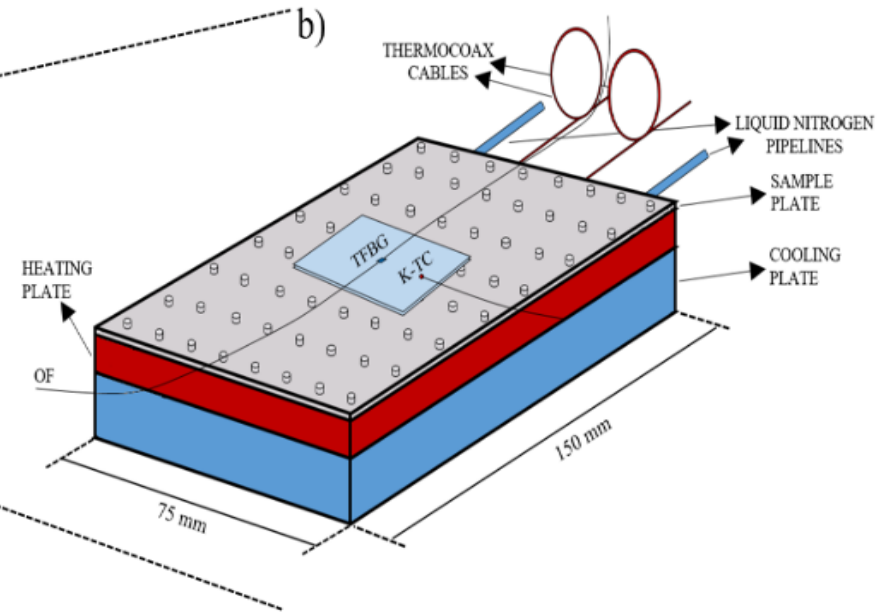
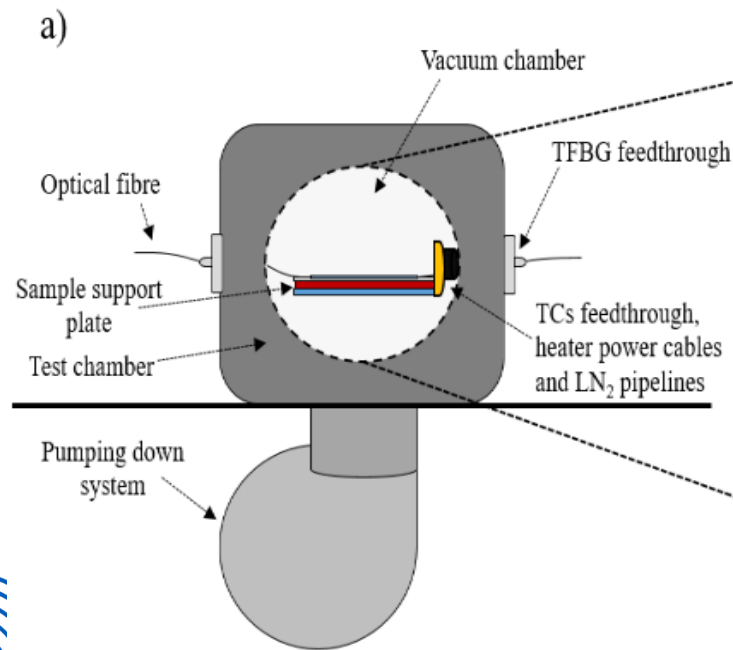
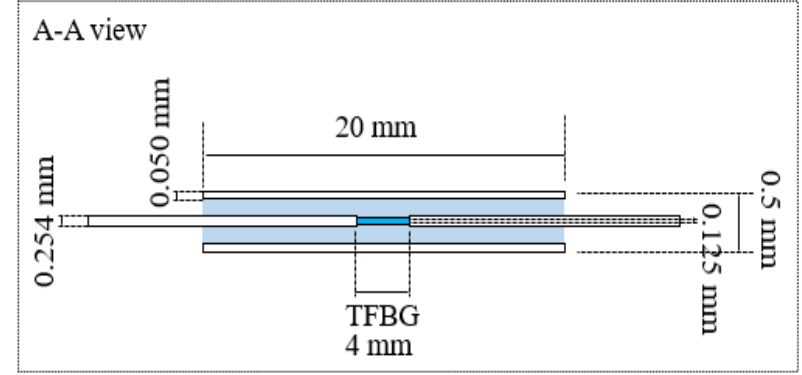
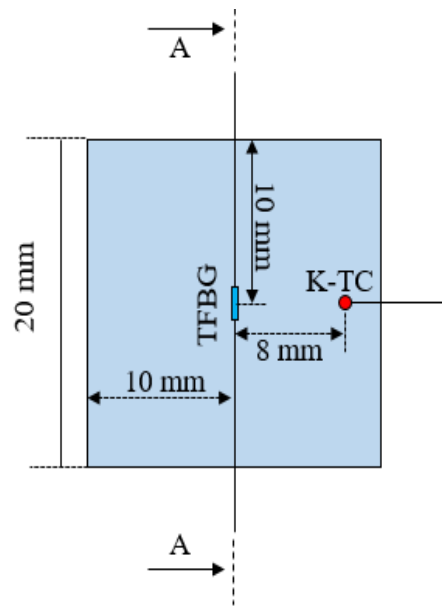




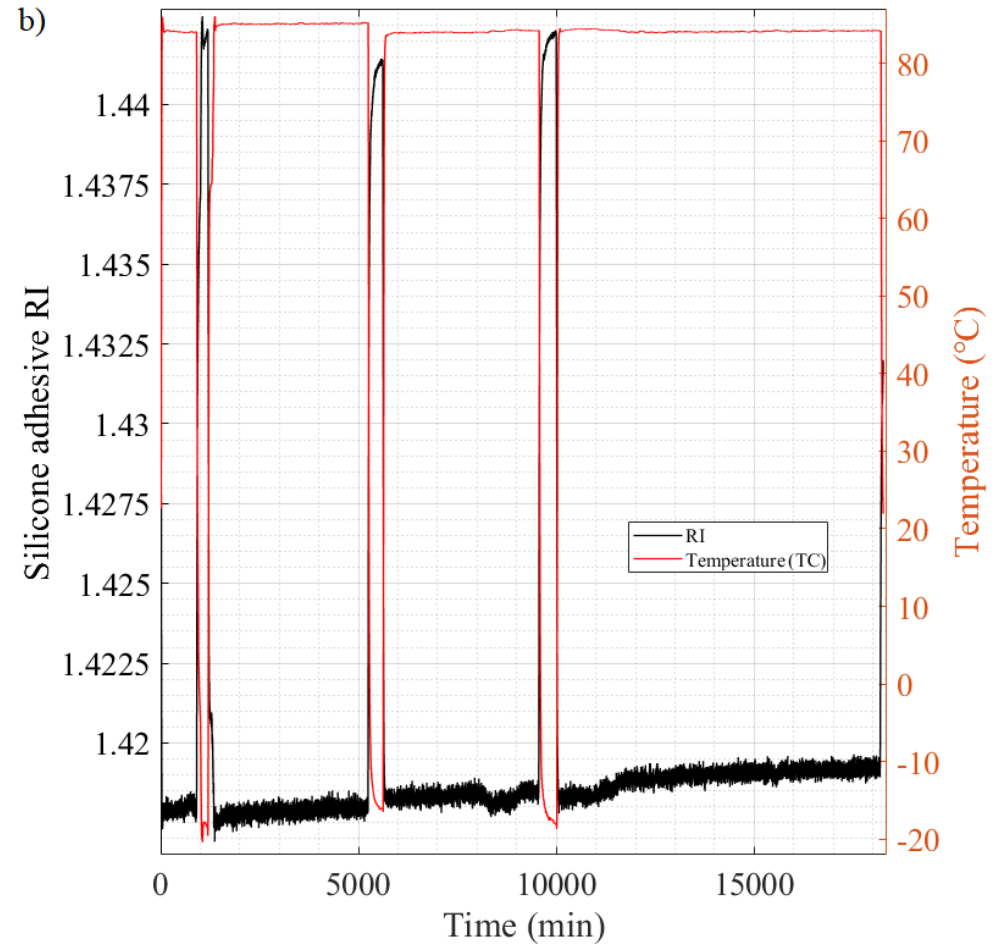
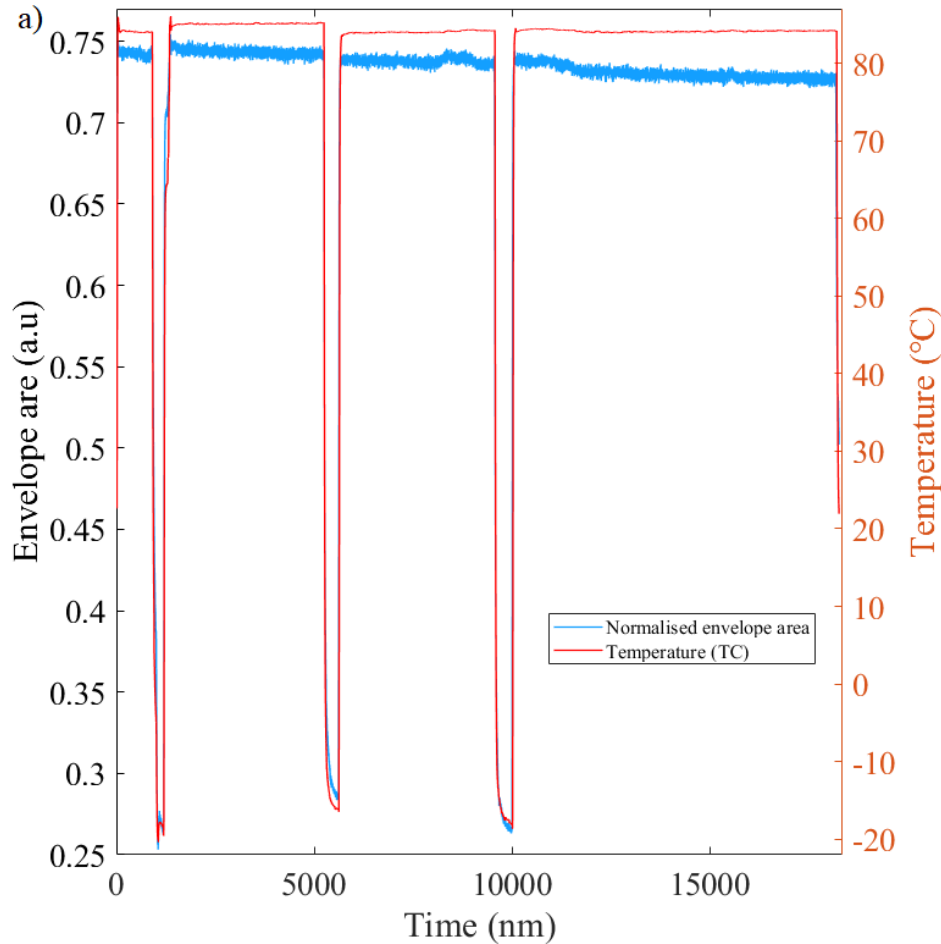
# *Samples inside vacuum test chamber*



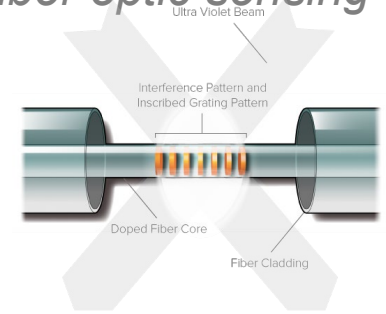
# Experimental setup



# Results



The starting RI was  $\sim 1,43$ . The final RI is  $\sim 1,432$ .

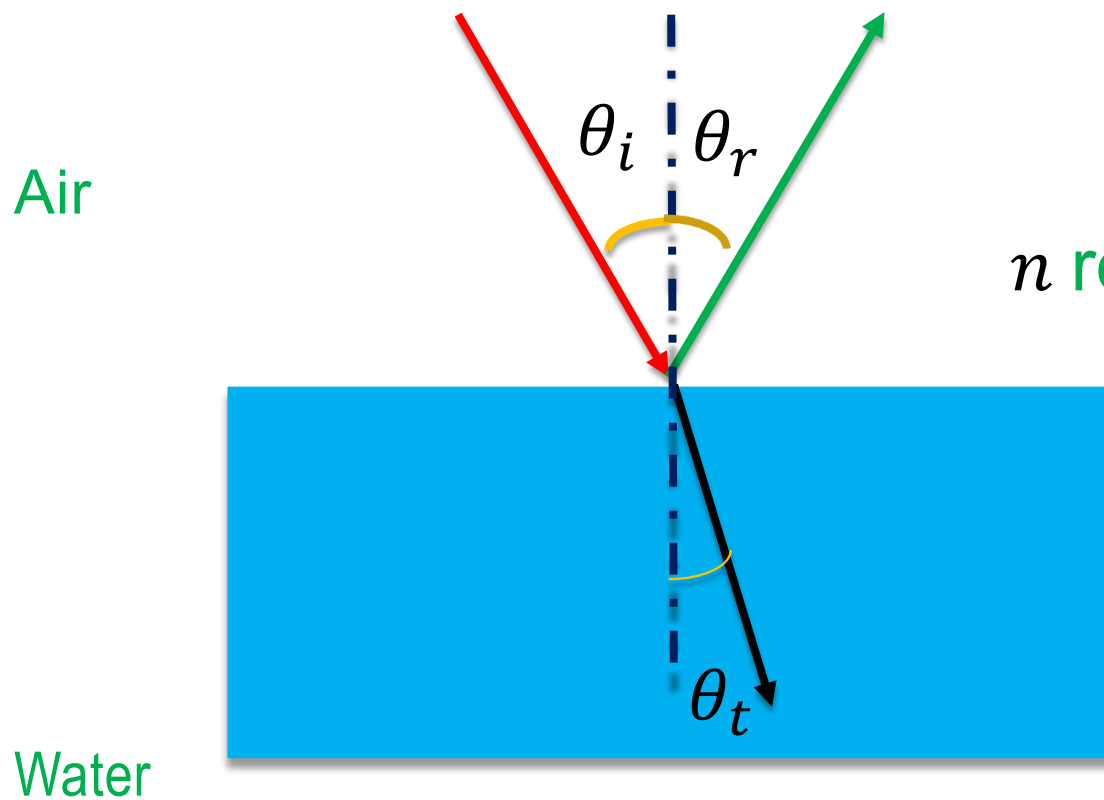


# *End of Part 1 - Fibre optic sensing for smart structures*

- Fibre optic sensing theory
- Research of PhD Nakash Nazeer on fibre optic shape sensing of morphing aircraft wing
- Research of PhD Luigi Fazzi on fibre optic sensing during composite manufacturing and in a simulated space environment

# Part 2: Ultrasonic wave propagation

# How to visualize waves in two different media?



Snel's Law:

$$\frac{\sin\theta_i}{\sin\theta_t} = \frac{n_t}{n_i} = \frac{c_i}{c_t}$$

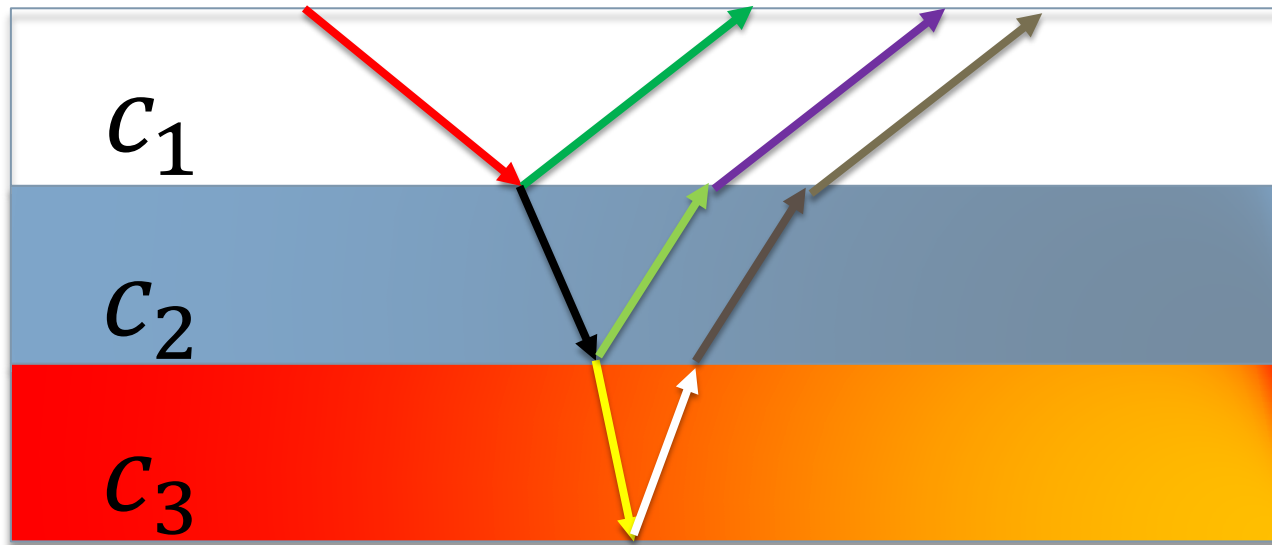
$n$  refractive index



# 'Multiple reflection scenario?'

3 layers

1<sup>st</sup> reflections



Transmission

$$c_1 > c_2 > c_3$$

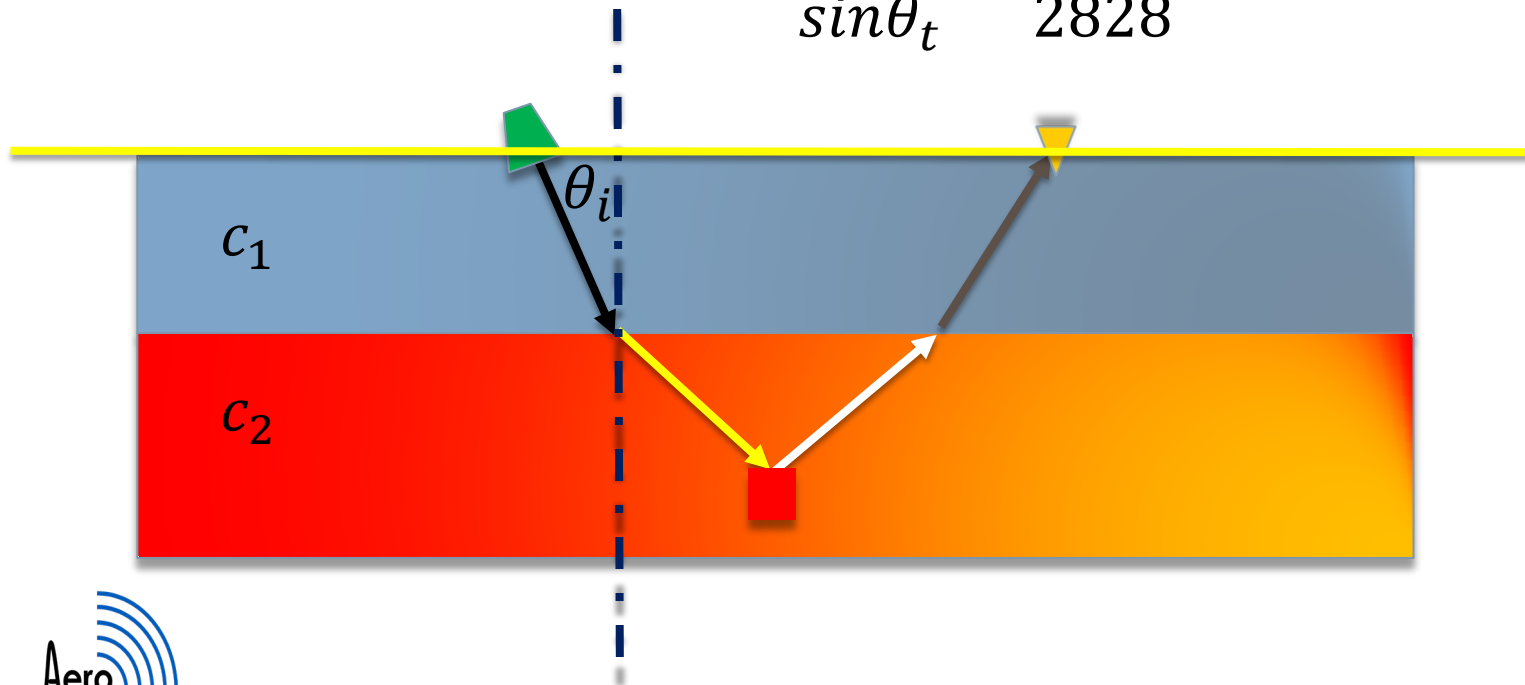
# Q1 Can we detect this damage at the surface?

$$c_1 = 2000\text{m/s}$$

$$c_2 = 2828\text{m/s}$$

YES!

$$\theta_i = 30^\circ \rightarrow \frac{\sin 30}{\sin \theta_t} = \frac{2000}{2828} \rightarrow \theta_t = 45^\circ$$



# Can we detect this damage at the surface (note different materials!)?

$$c_1 = 2000 \text{ m/s}$$

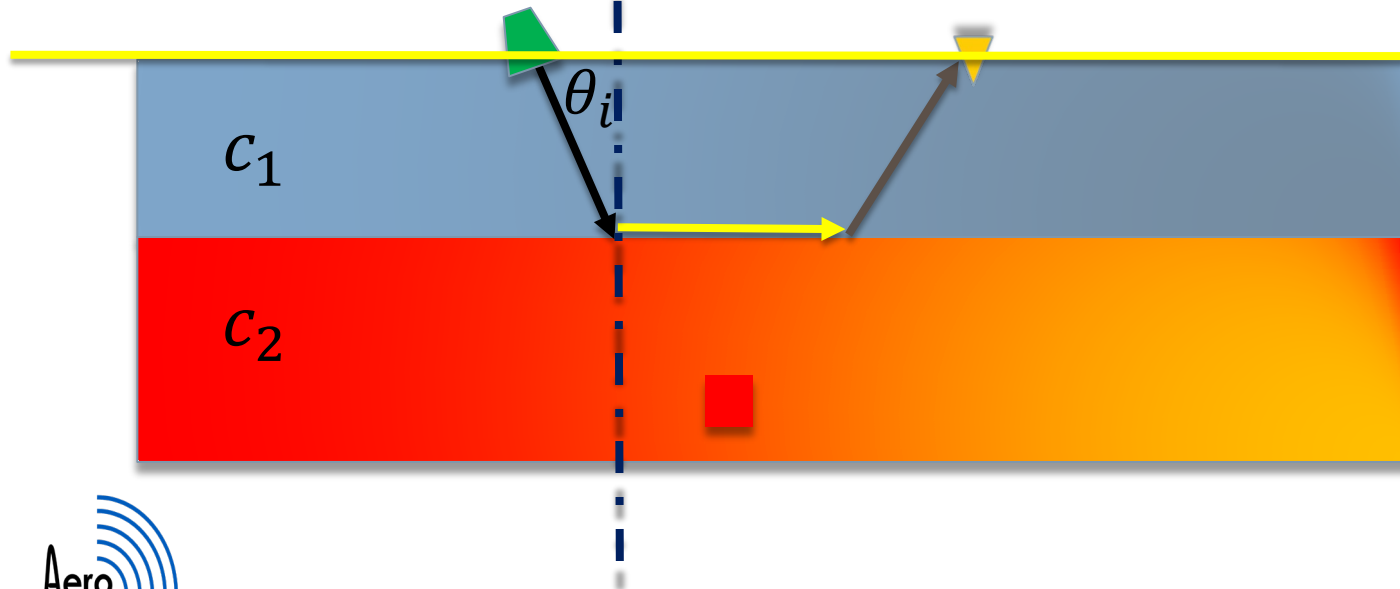
$$c_2 = 4000 \text{ m/s}$$

No!

$$\theta_i = 30^\circ$$

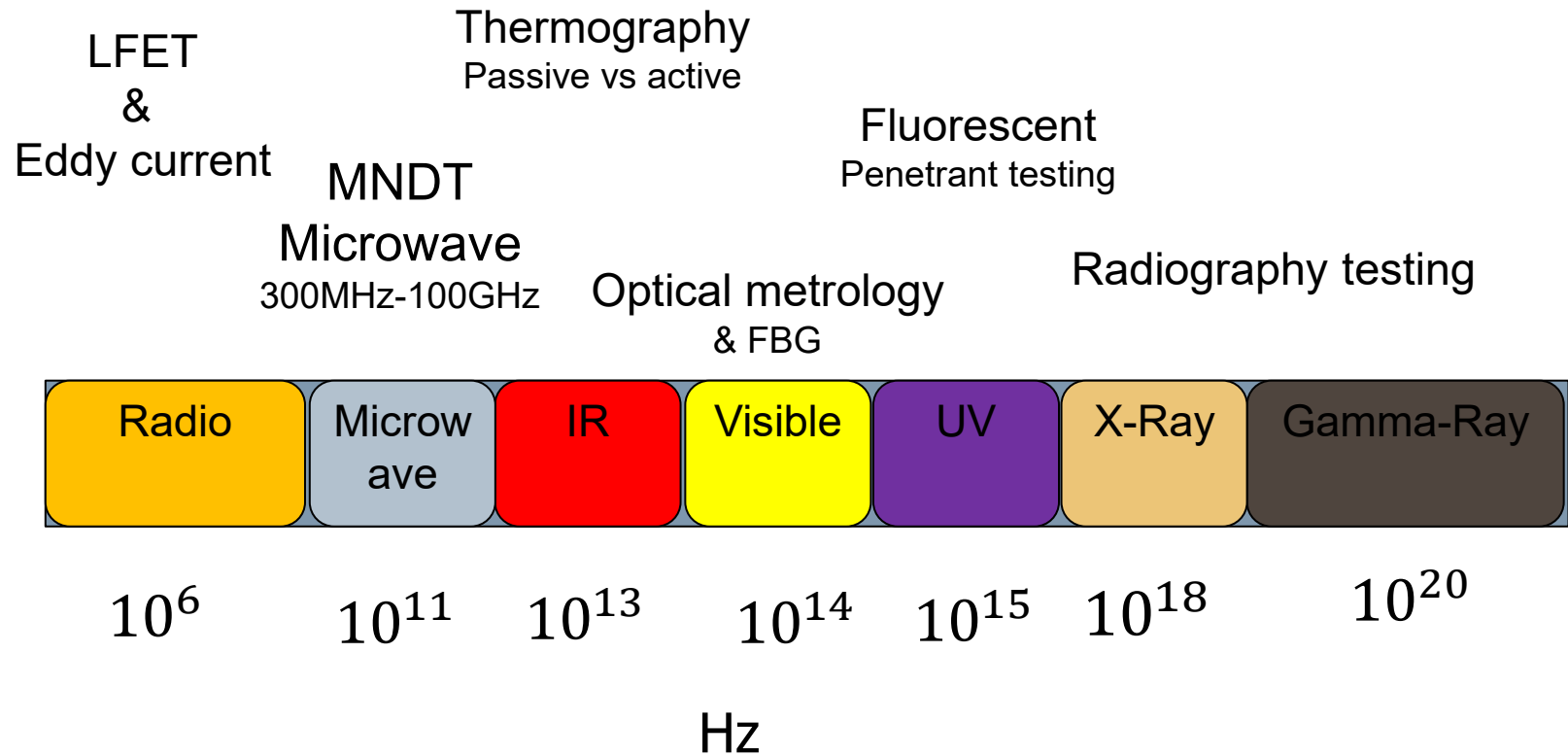
$$\frac{\sin 30^\circ}{\sin \theta_t} = \frac{2000}{4000} \rightarrow \theta_t = 90^\circ$$

Critical reflection angle

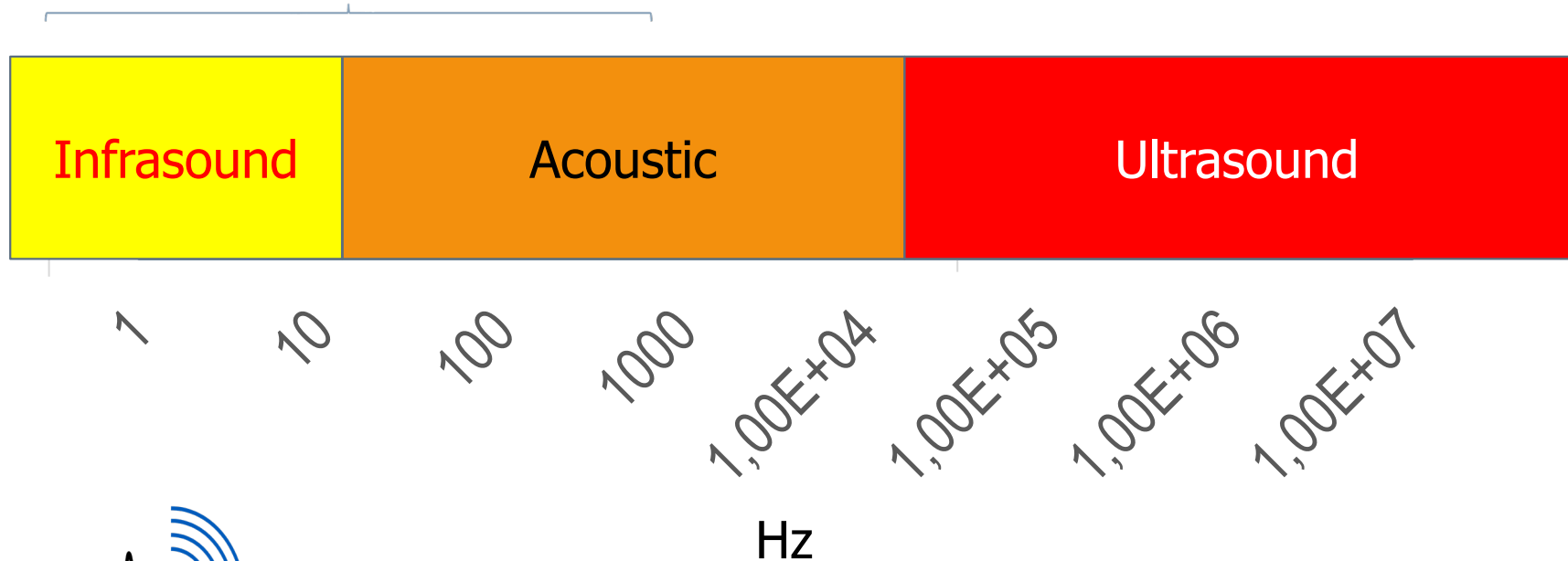
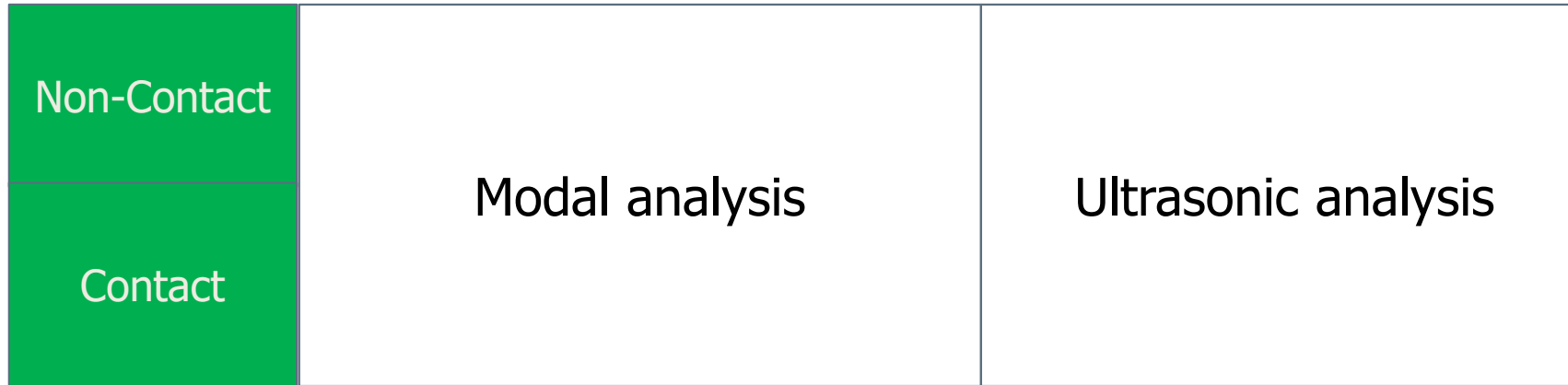


# Ultrasonic wave modes

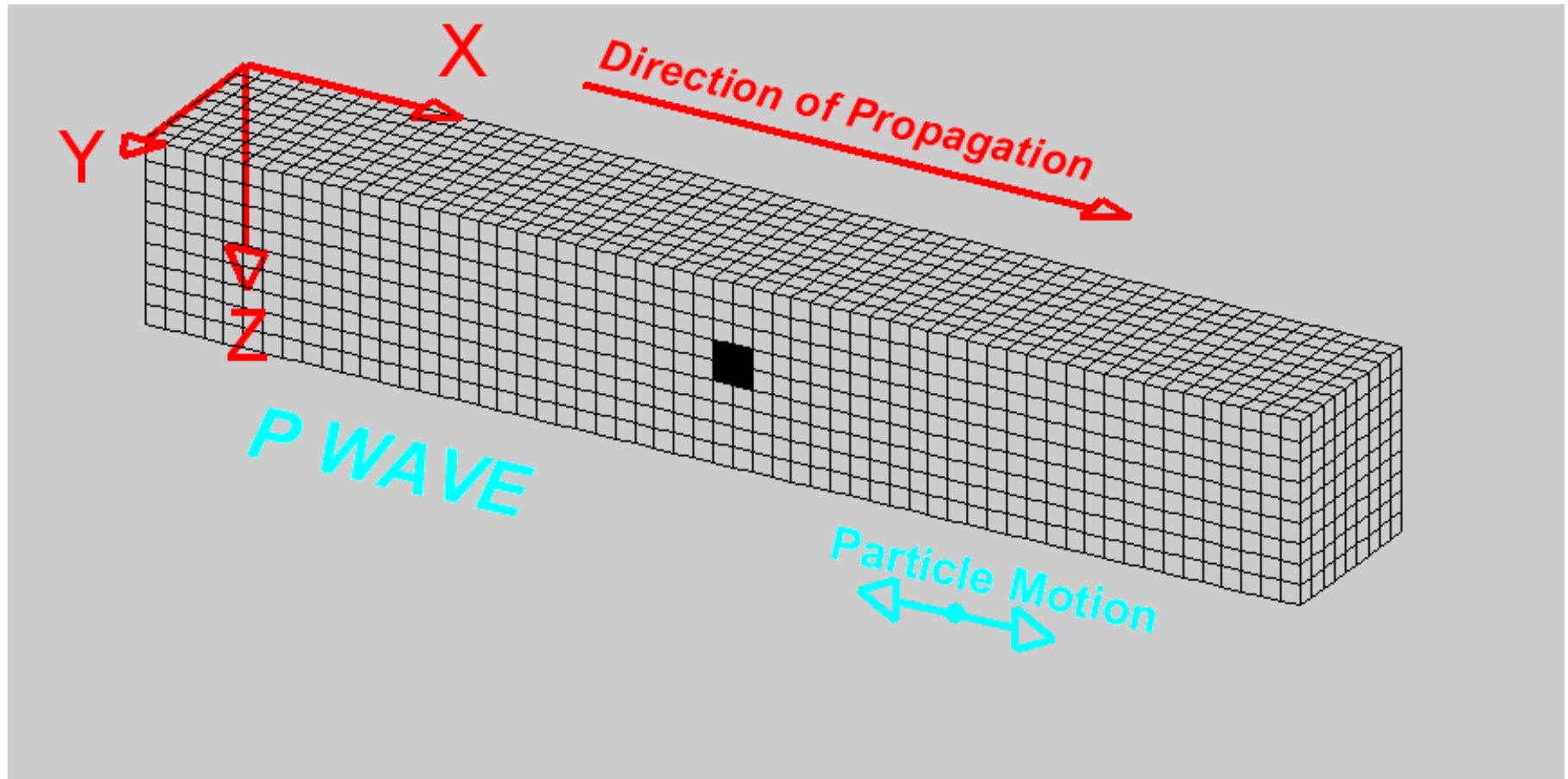
# Electromagnetic wave spectrum



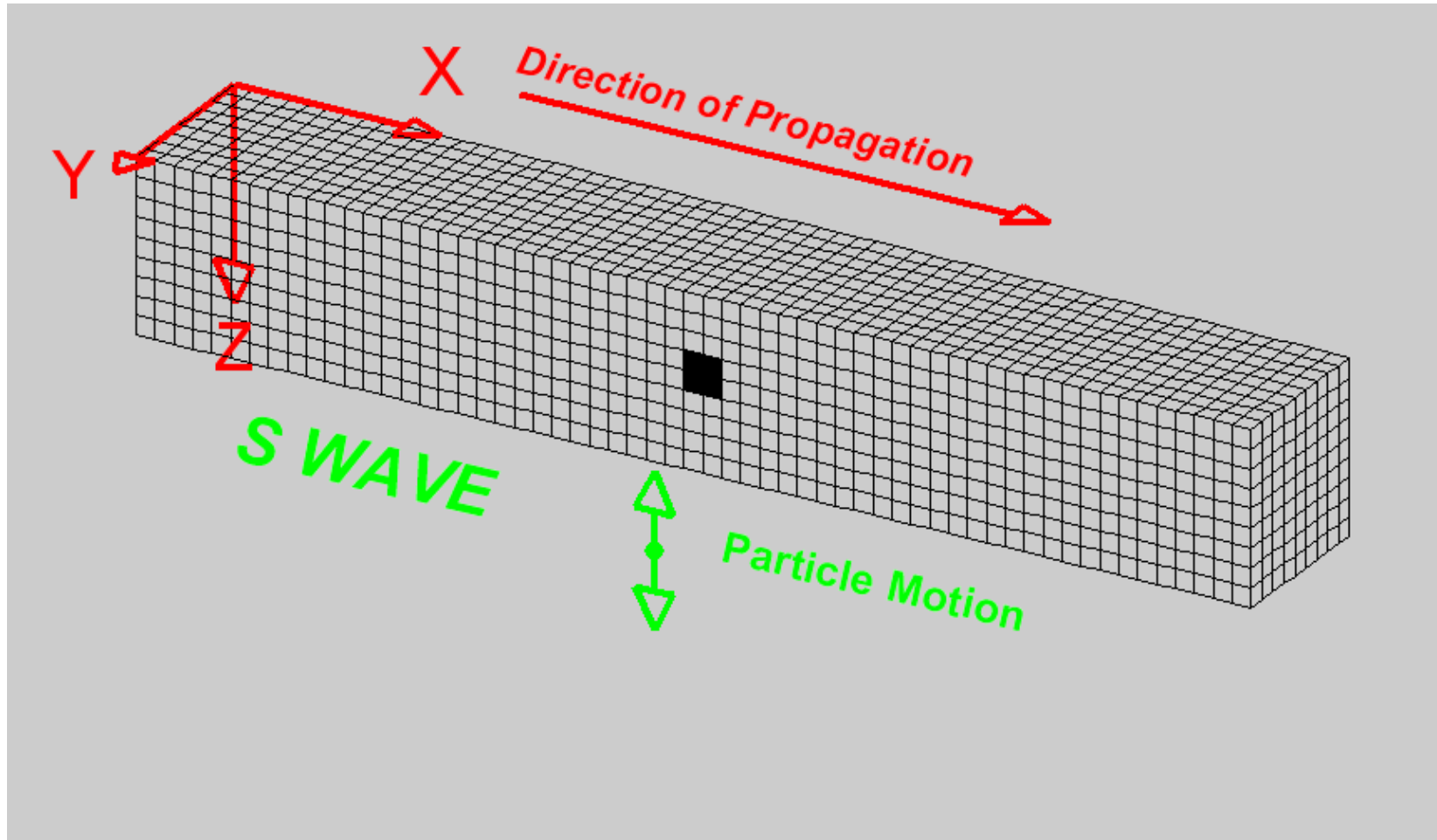
# Mechanical wave spectrum



# Longitudinal aka P-waves

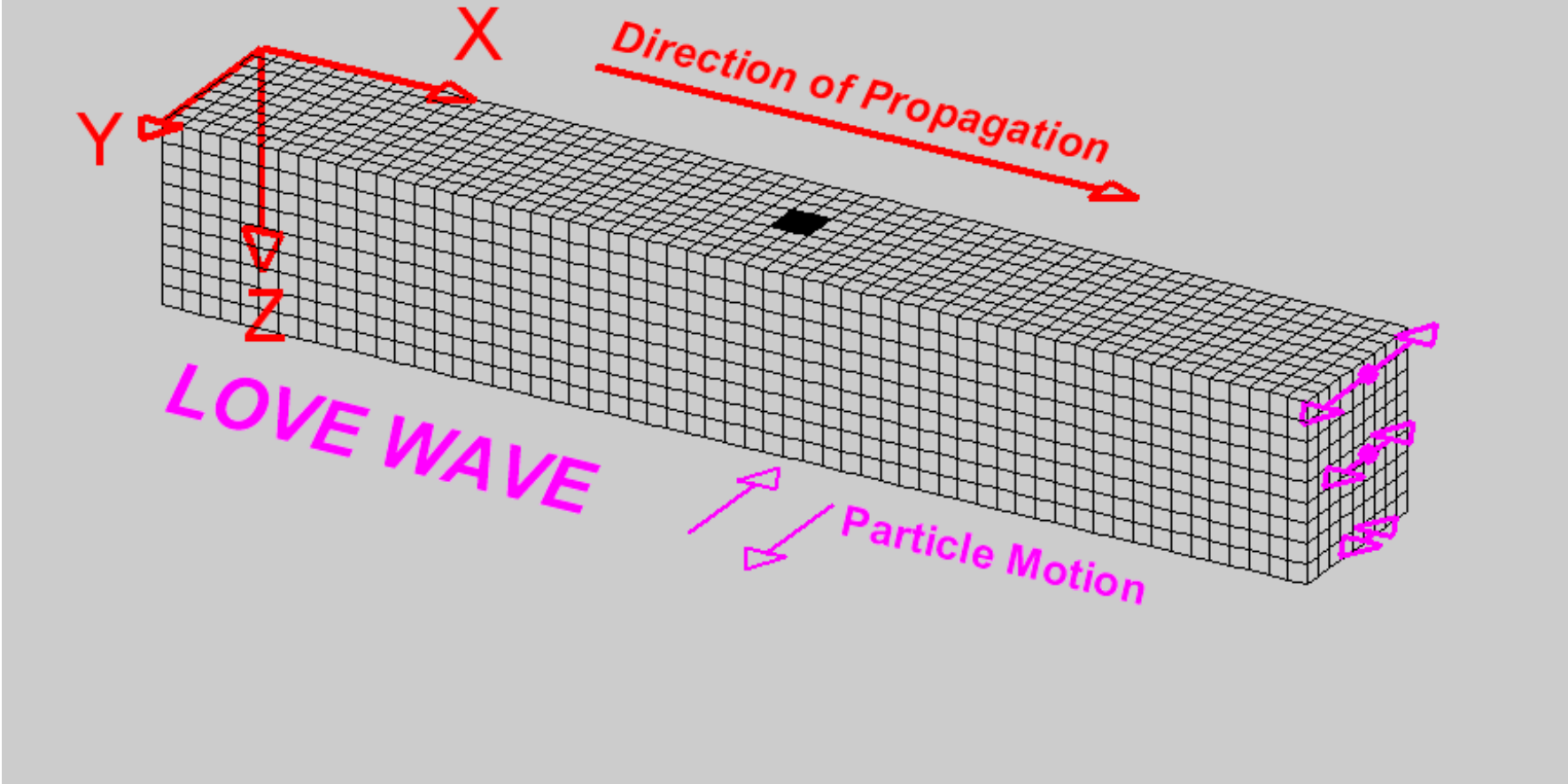


# Shear, $S_y$ - and $S_z$ -waves

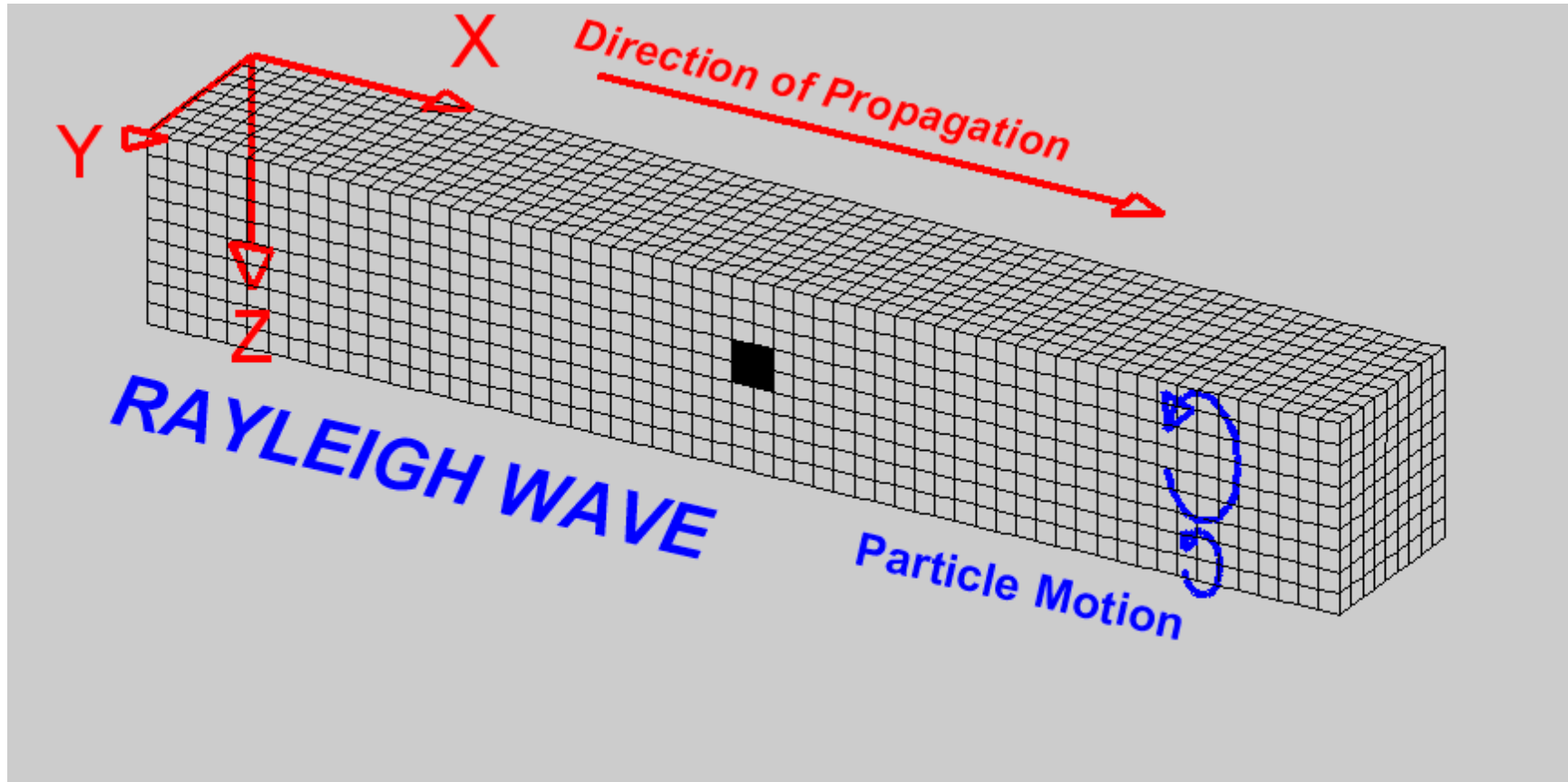




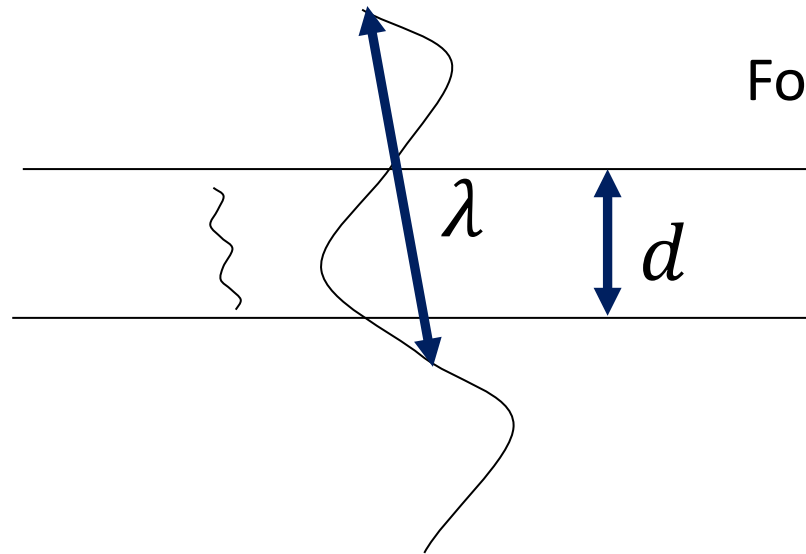
# Surface Love waves



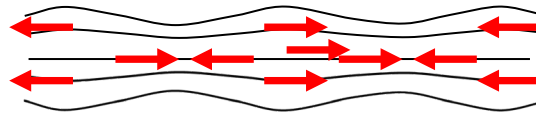
# Surface Rayleigh waves



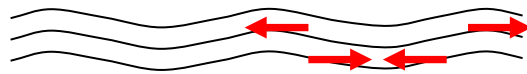
# Plate waves – Lamb waves



For  $\frac{d}{\lambda} \leq 1$  Lamb waves occur



Symmetric,  $S_0, S_1, \dots$



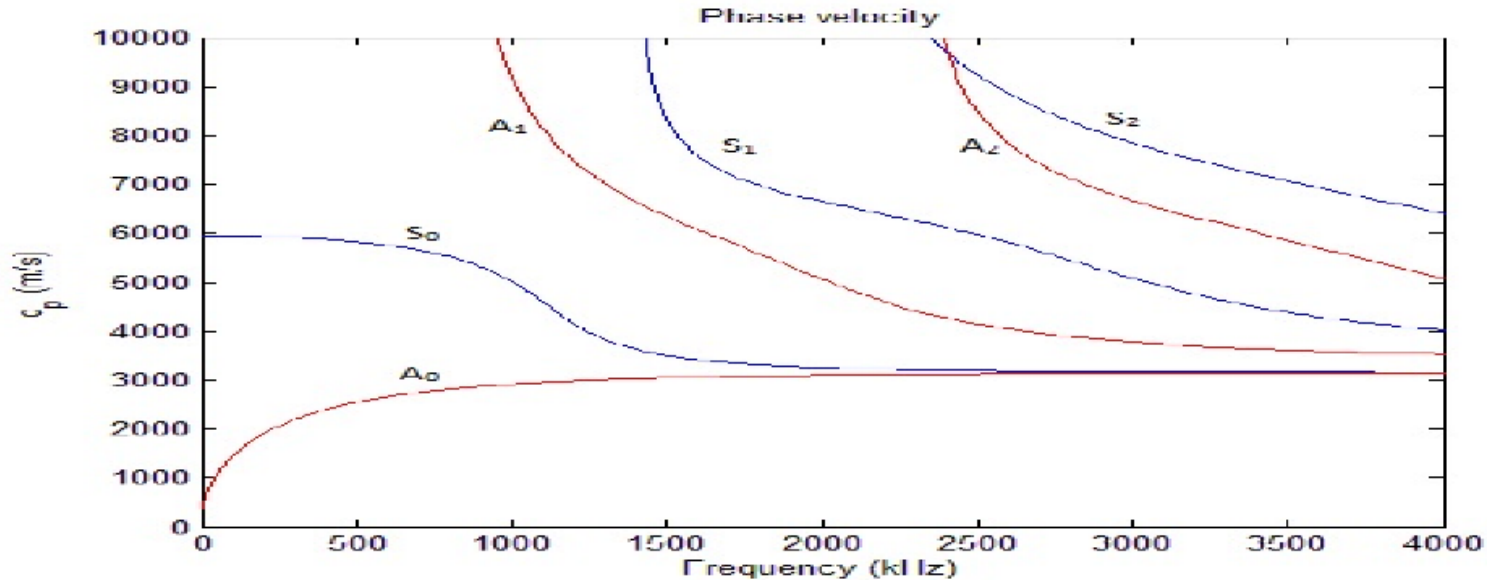
Asymmetric  $A_0, A_1, \dots$

# Phase and group velocity

Phase velocity  $C_P$  : Velocity of the carrier wave

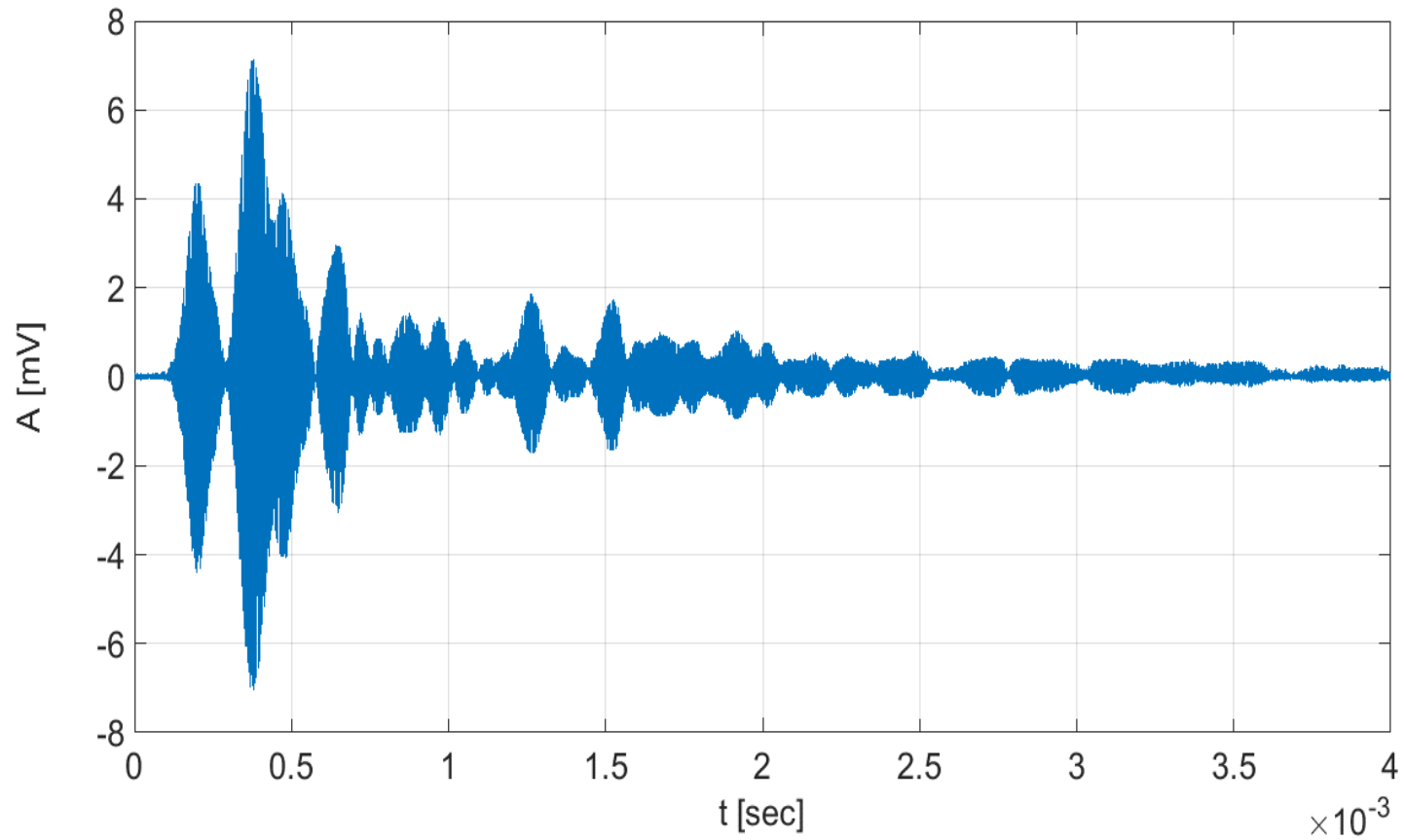
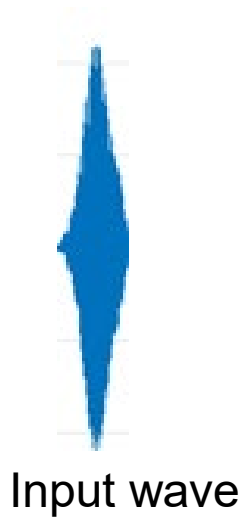
Group velocity  $C_G$ : Velocity of the wavepacket

- Phase = Group velocity for isotropic material

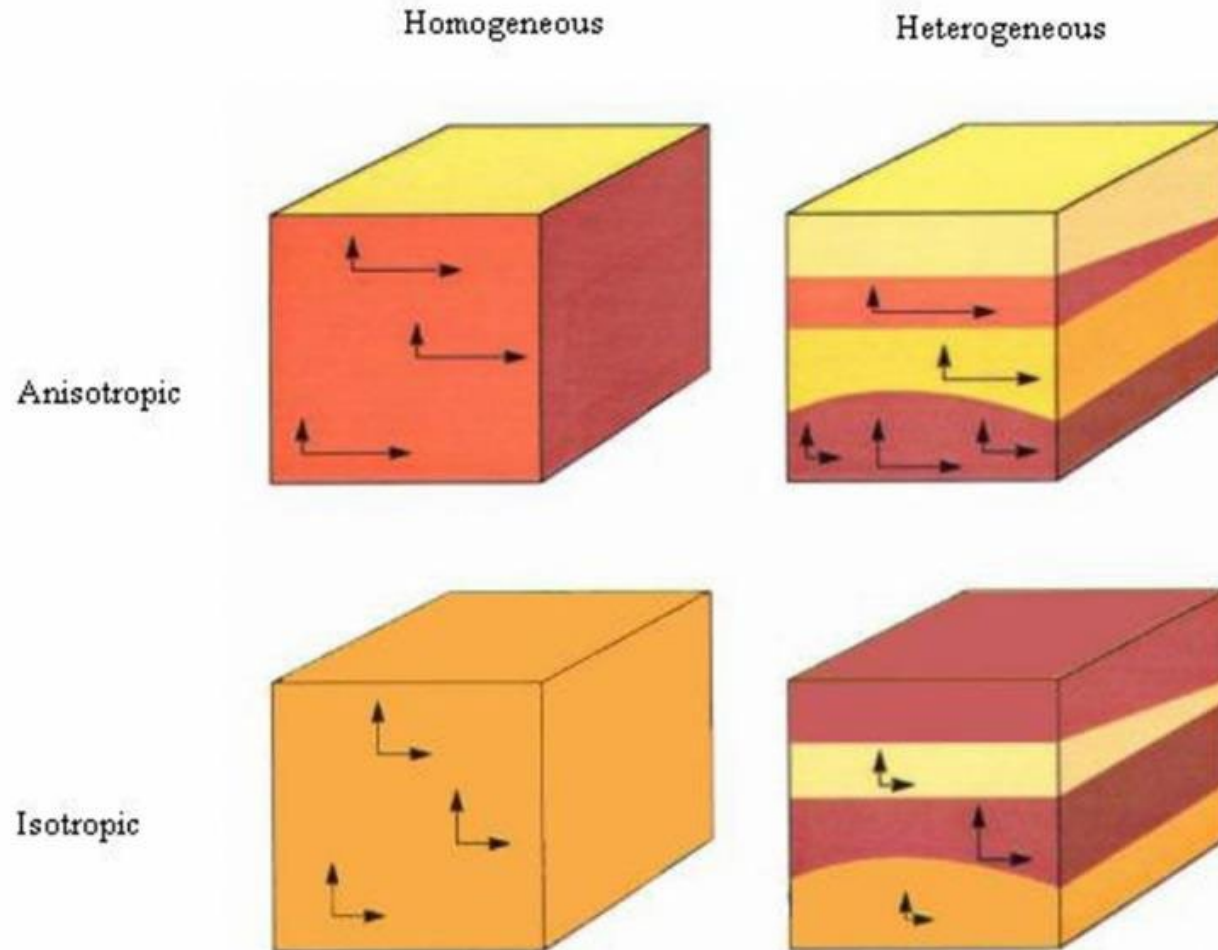


- Wave velocity can change as function of frequency, known as 'dispersion'

# Time of flight of waves

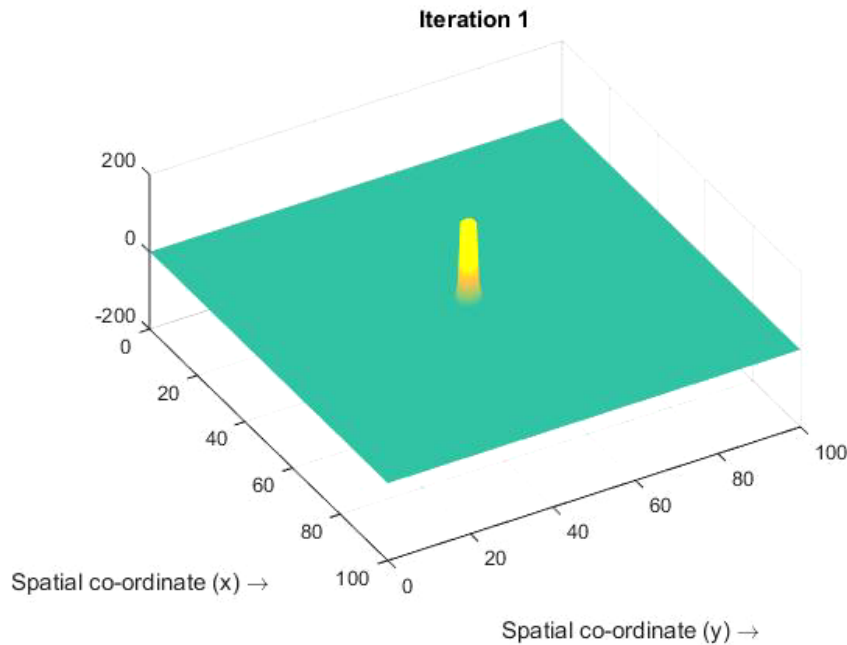


# Homogeneous/ heterogeneous & anisotropic/ isotropic

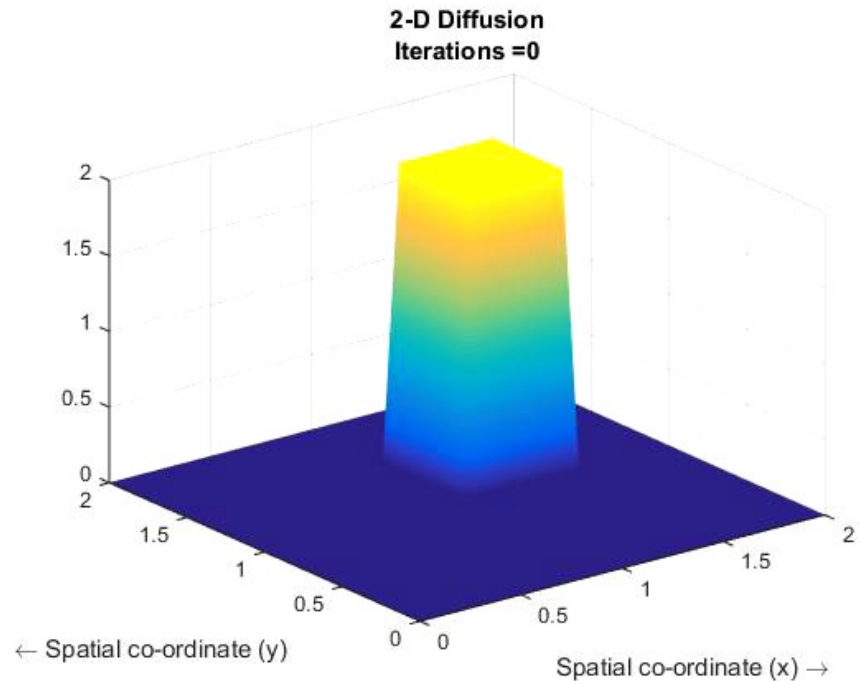


# Ultrasonic wave properties

# Wave propagation vs diffusion



Like rock in water



Heating an object with a torch  
(temporarily)



# Properties of waves

$$\frac{\partial^2 U}{\partial t^2} = c^2 \frac{\partial^2 U}{\partial x^2} \quad \frac{\partial U}{\partial t} = \alpha \frac{\partial^2 U}{\partial x^2}$$

Property	Wave	Diffusion
Velocity	Finite $c=??$ m/s	Infinite
Well posed $t>0$	Yes	Yes
Well posed $t<0$	Yes	No
Behavior for $t \rightarrow \infty$	Does not decay	Decays to zero
Information	Transported	Decays gradually

# Wave velocities in homogeneous isotropic materials -1

$$c_s = \sqrt{\frac{G}{\rho}}$$

$c_s$  shear wave velocity,  $\rho$  the solid density

&

$$\nu = \frac{c_p^2 - 2c_s^2}{2(c_p^2 - c_s^2)}$$

$c_p$  compressional velocity

# Wave velocities in homogeneous isotropic materials -2

$$E = 2G(1 + \nu)$$

With  $E$  the Elasticity modulus

Alternative

$$c_p = \sqrt{\frac{K + \frac{4}{3}G}{\rho}}$$

where  $K = \frac{E}{3(1-2\nu)}$  bulk modulus, &  $\nu$  Poisson ratio

# Acoustic Impedance

$$Z = \rho \cdot c$$

Reflection :

$$R = \frac{Z_2 - Z_1}{Z_2 + Z_1}$$

$Z_2$  Impedance material 2

$Z_1$  Impedance material 1 [ $kg/(m^2 \cdot s)$ ]  $\rightarrow$  [ $Pa \cdot s/m$ ]

$R$  Reflection coefficient [%]

Transmission :

$$T = 1 - R$$

# *Ultrasonic sensing technology*

# Frequency and accuracy

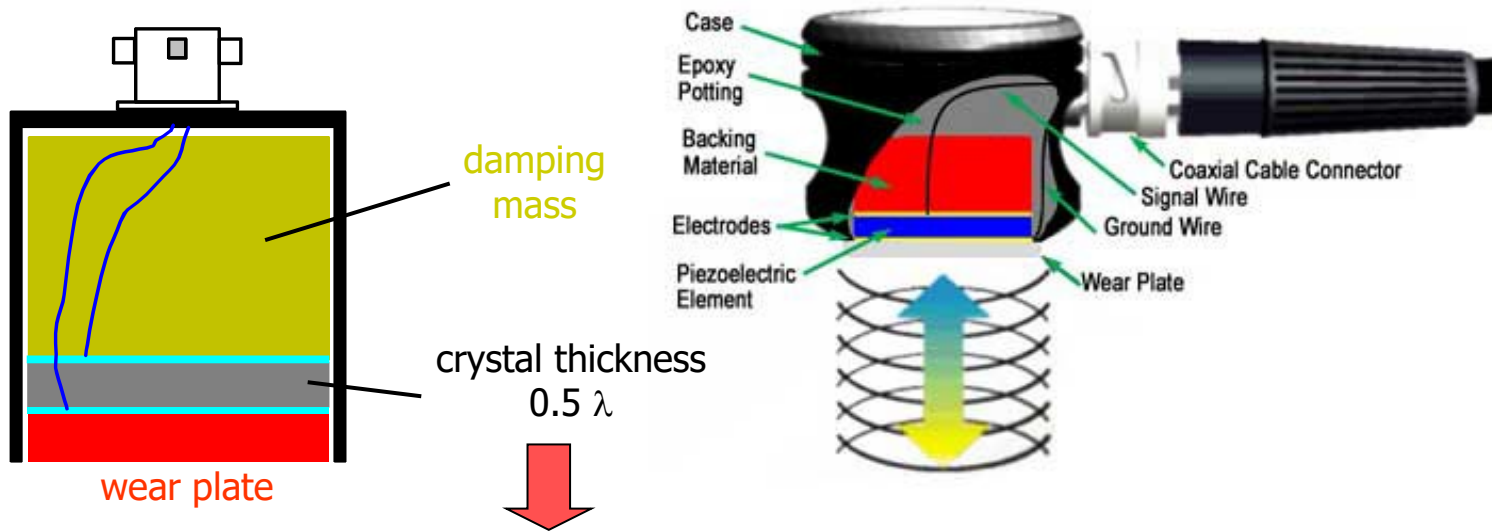
Wave measurements are in general more accurate, but also more time consuming.

Lower 'frequencies' also means deeper penetration of materials (music through a wall, you mainly will hear the lower frequencies).

# Acoustic Wave PZT

Excitation pulse requires  
25 V to 600 V

Available up to 150 MHz centre  
frequency

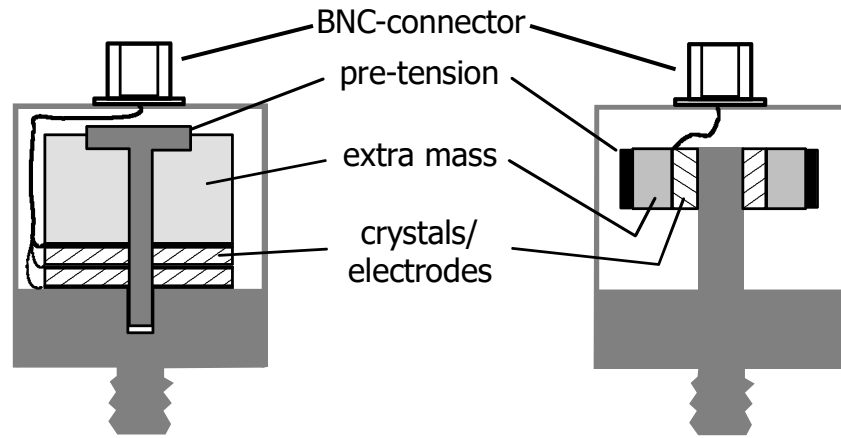


For example made of lead zirconate niobate (PZN) or lead titanate (PT)  
These man-made materials are more sensitive and also cheaper than quartz

# Shear and Pressure transducers

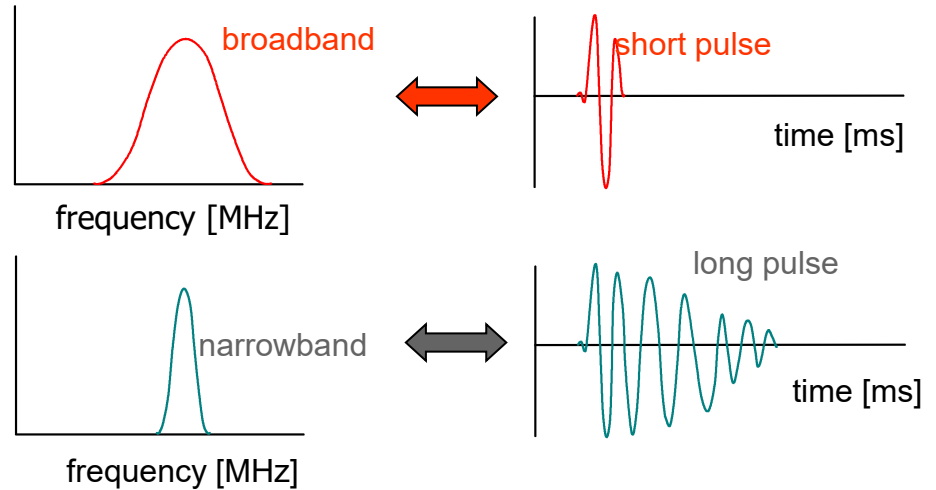
**pressure-type**

**shear-type**

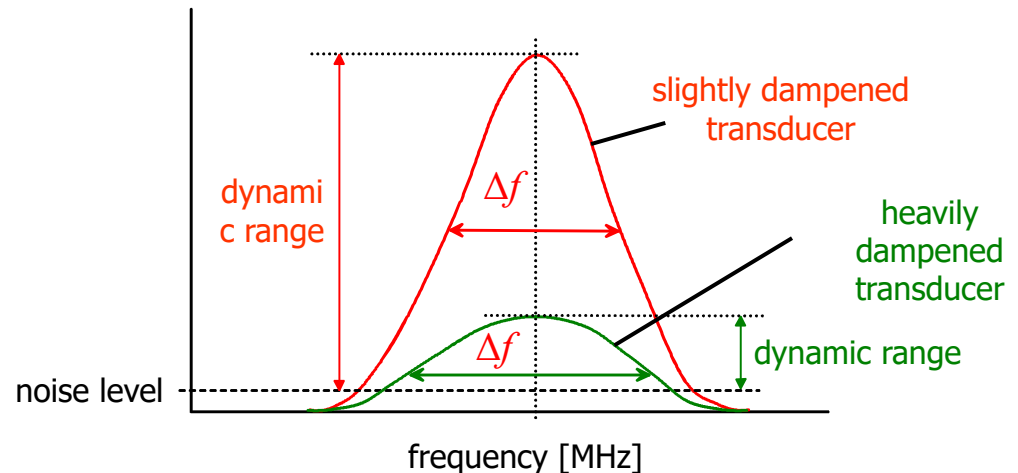


Increased damping (more attenuating mass) increases transducer bandwidth at the cost of dynamic range

## Bandwidth vs Pulse Time

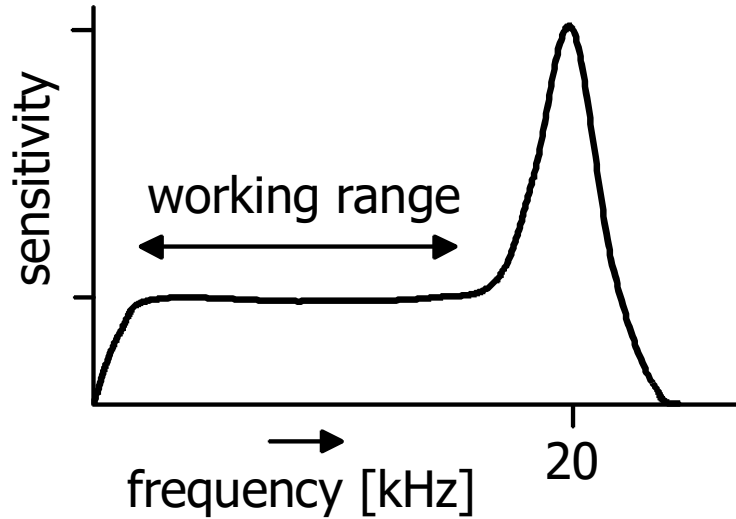


## Damping of PZTs

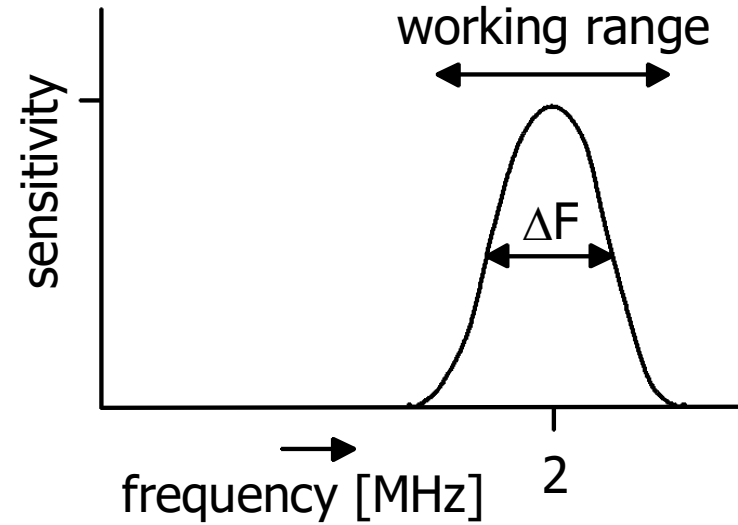




# Accelerometer vs wave transducer

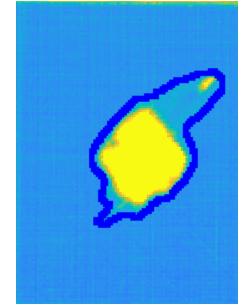
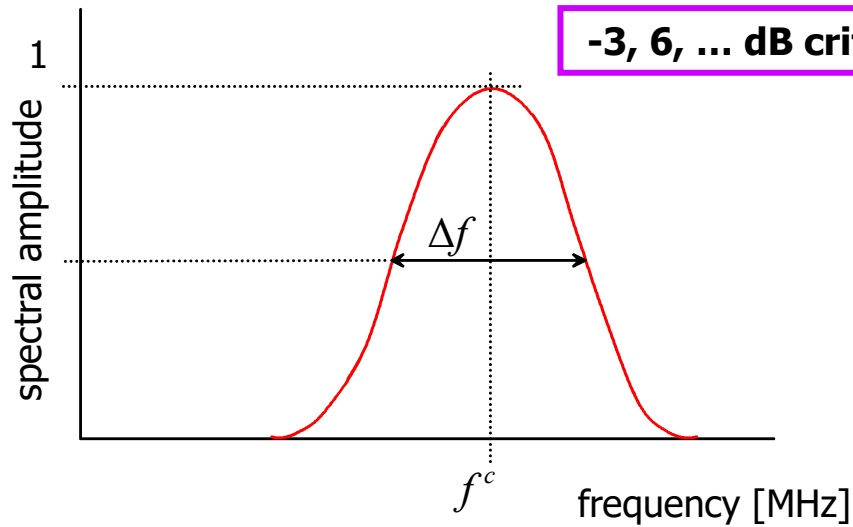


Accelerometer

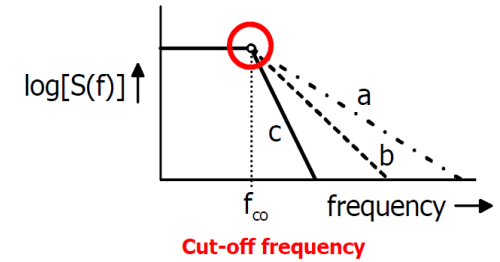


Wave transducer

# Bandwidth of Acoustic Wave PZTs



Ultrasonics



**Relative bandwidth:**  $\frac{\Delta f}{f^c} 100\%$

Bandwidths of commercial transducers between 5% - 150%

Study Hall Supported By audio-technica

## +/-3 dB or -6 dB: What's the Difference?

March 6, 2012  
Gerry Tschetter

The meaning of both specs and a basis for comparing loudspeakers

The terms +/-3 dB and -6 dB are frequently (and erroneously) used interchangeably to characterize the frequency response of a loudspeaker system.

This has led to understandable confusion among consumers who may believe that a +/-3 dB specification is more rigorous than a -6 dB specification.

The purpose of this document is to explain the meaning of both specifications as they are commonly used (or misused) in pro audio today, and to provide a basis for comparing loudspeakers with differing stated specifications.

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Cyrl Robinson Azariah John Chelliah  
13.83 · Saveetha University

Please tell me, Why the cutoff frequency is taken for 3dB and not other values like 1 or 2 db?

Question

Asked February 7, 2012

Please tell me, Why the cutoff frequency is taken for 3db and not other values like 1 or 2 db?

Answer this question

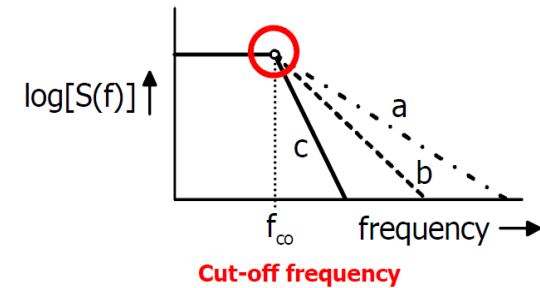
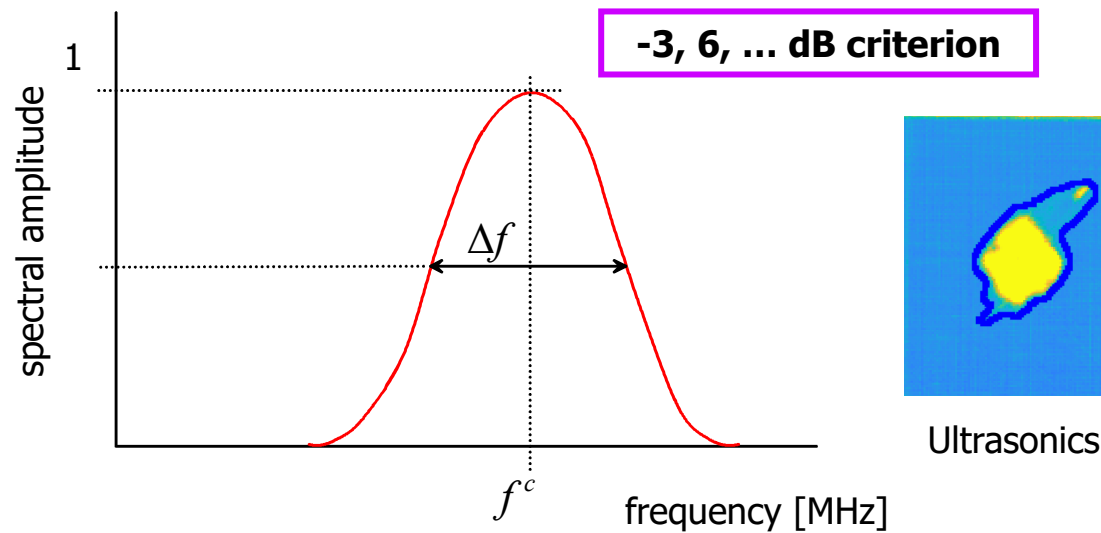
Electrical Engineering Advanced Control Systems  
Control Systems Engineering Applied Electronics  
Analog Electronics Electronics and Communication Engineering  
Advanced Communication Systems

Recommend Follow Share

# 3/6 dB

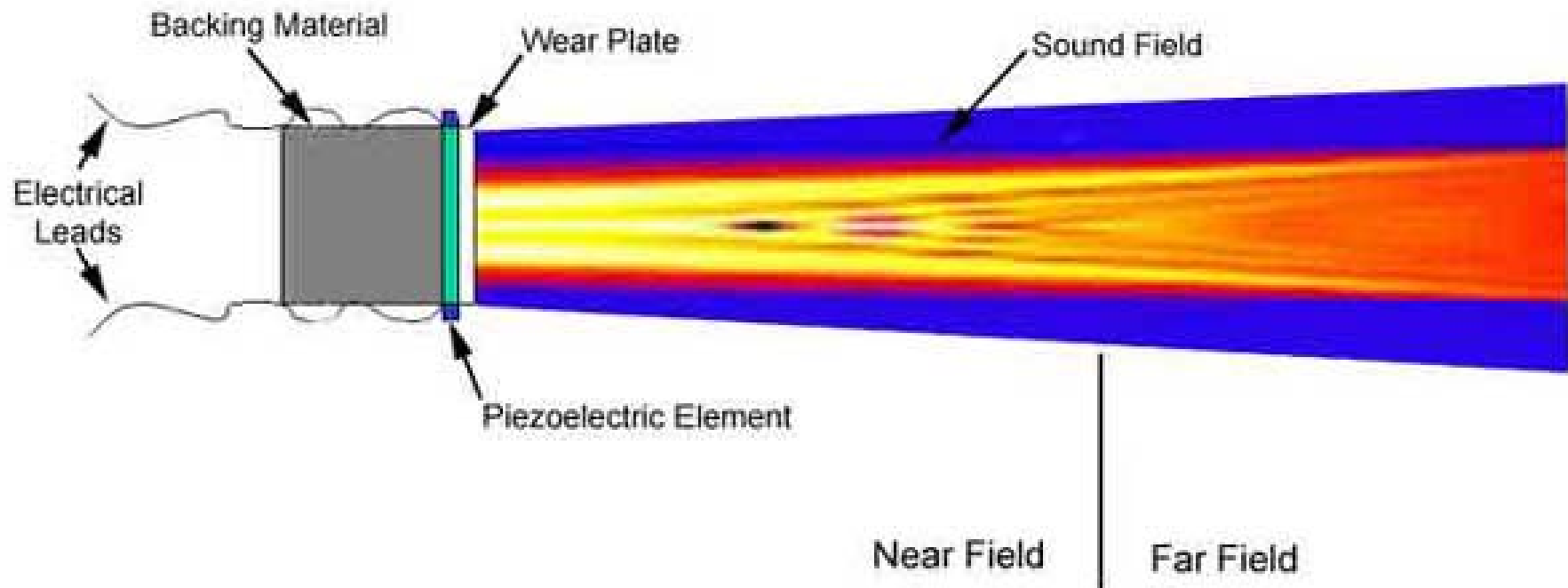
- What is the physical meaning of -3 dB?
- What is the physical meaning of -6 dB?
- Which one to use for the bandwidth?

- In groups
- 4 minutes



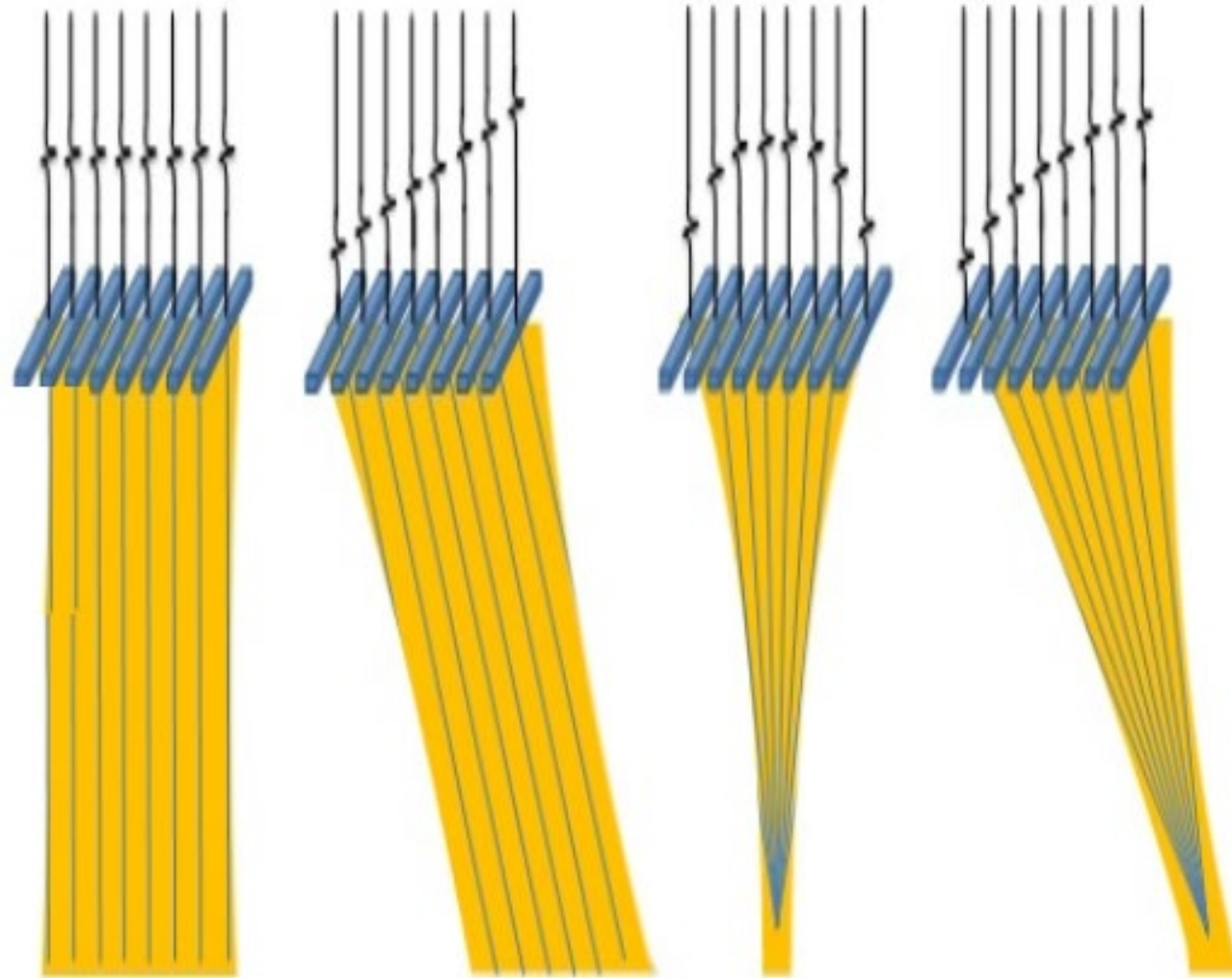
# Phased array ultrasonics

# Visualising an ultrasonic beam

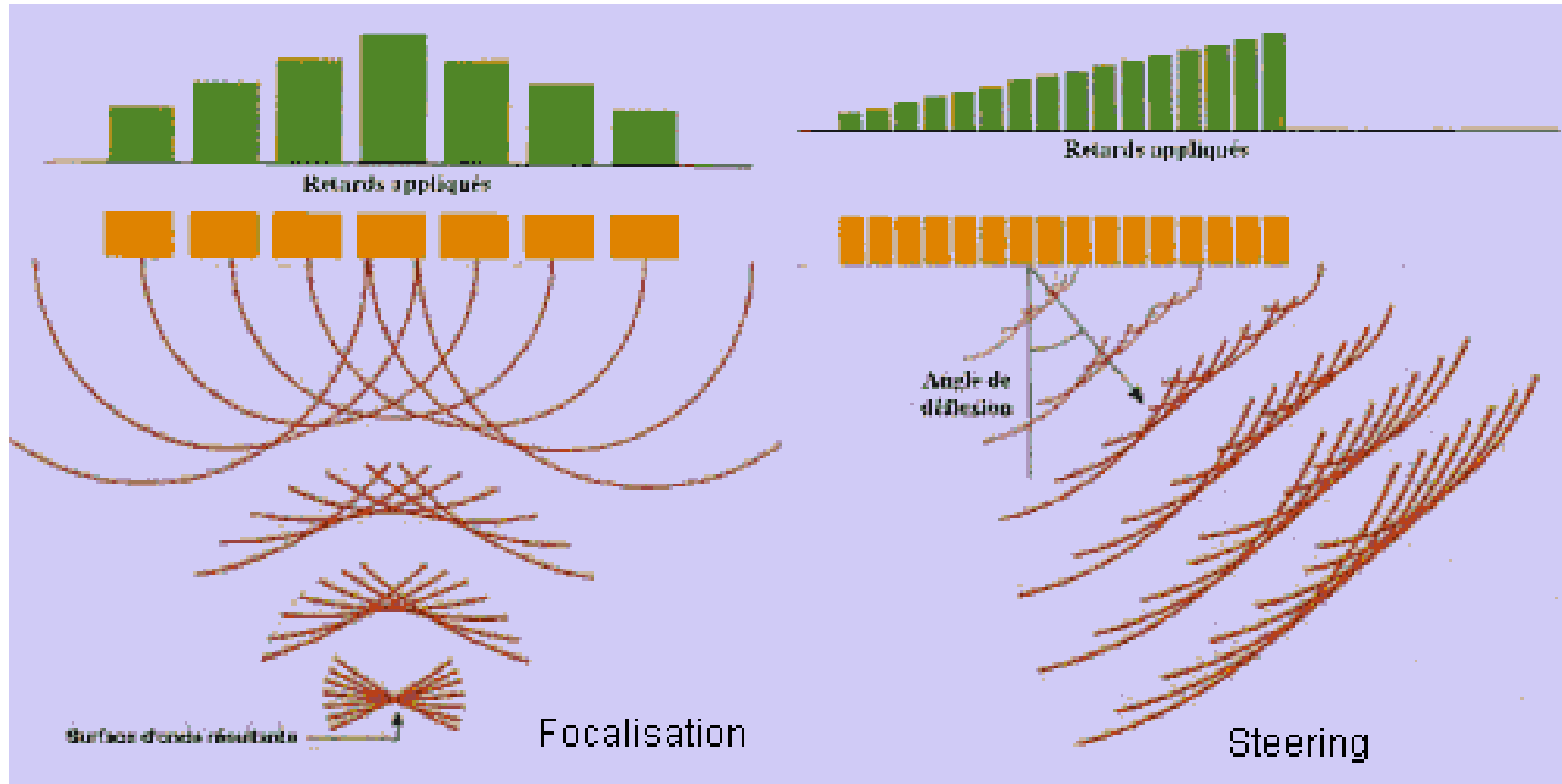


*Near field distance  
= 2x wavelength*

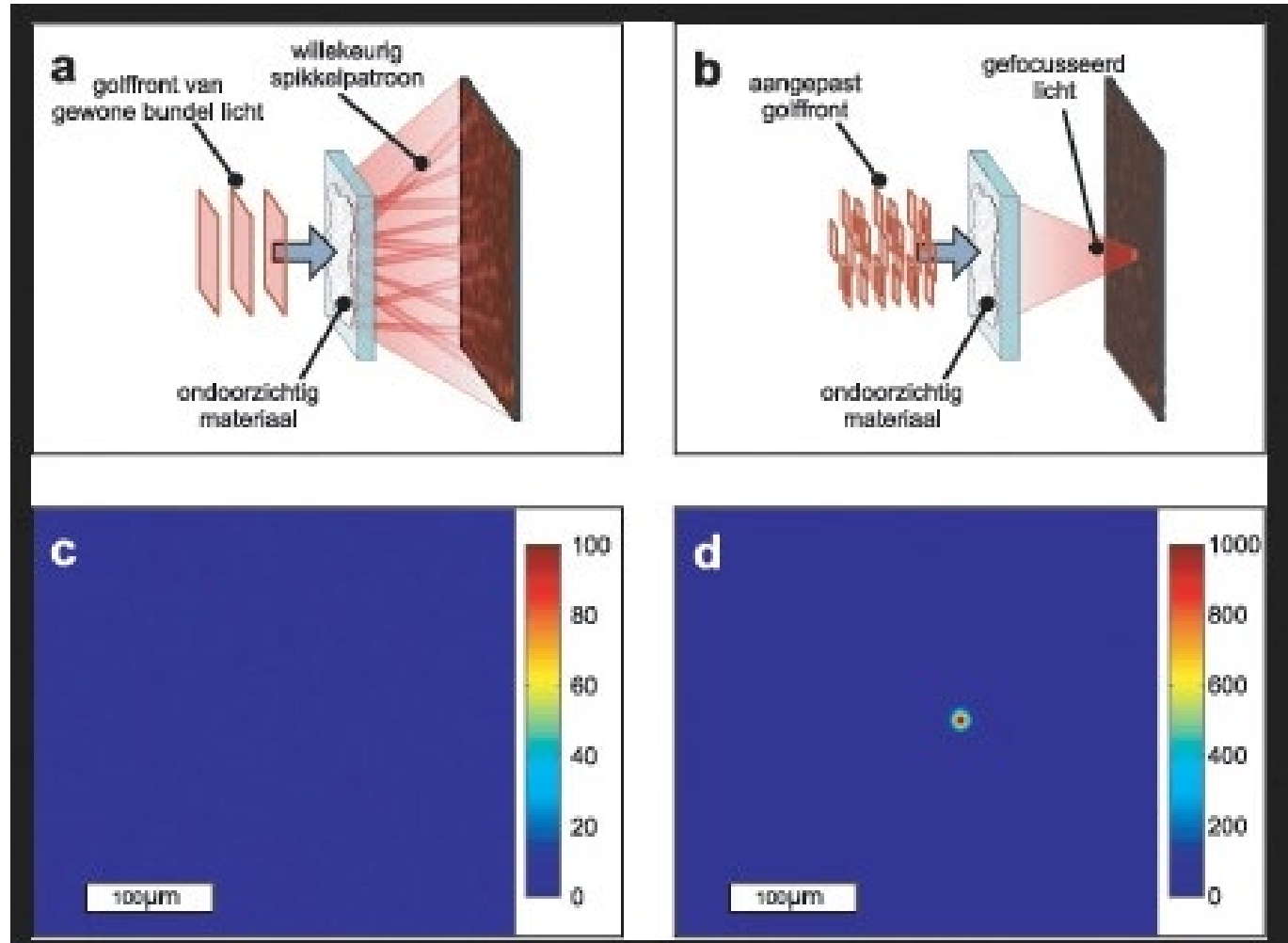
# Phased array ultrasonic beams



# Focusing and steering PAUT beams

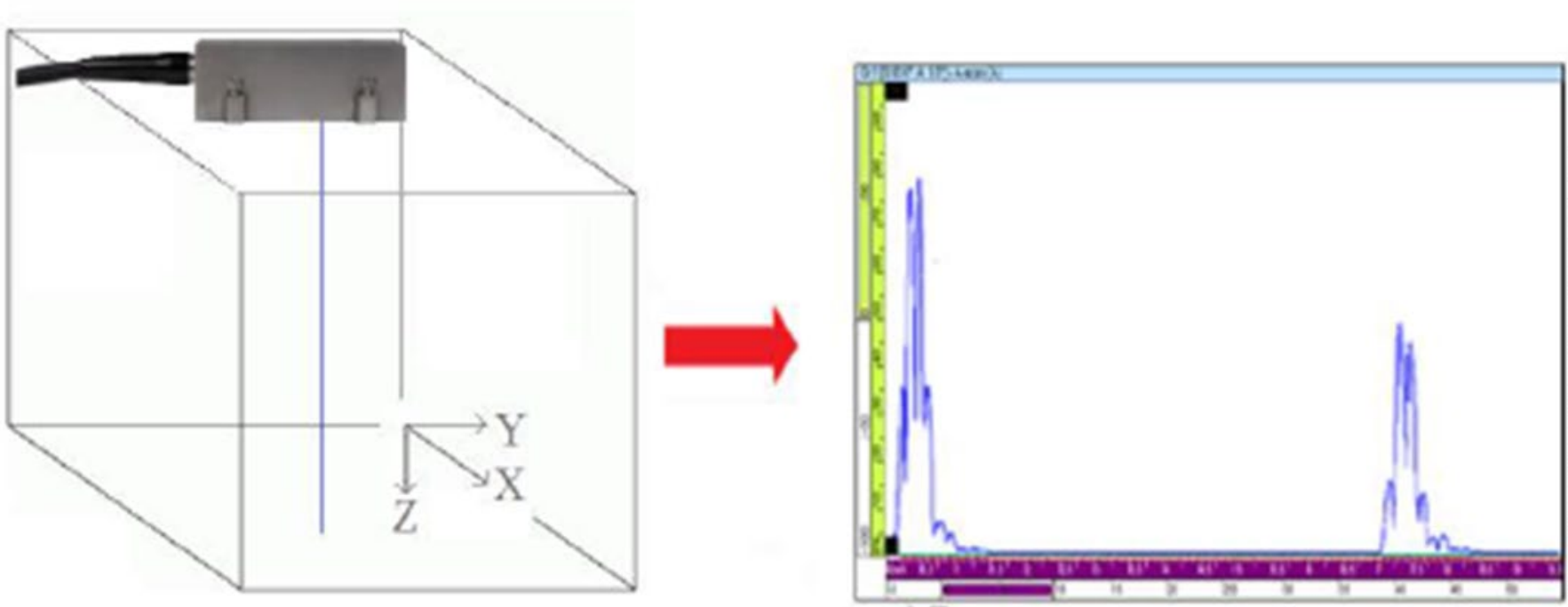


# Adapting the waveform for the material under test

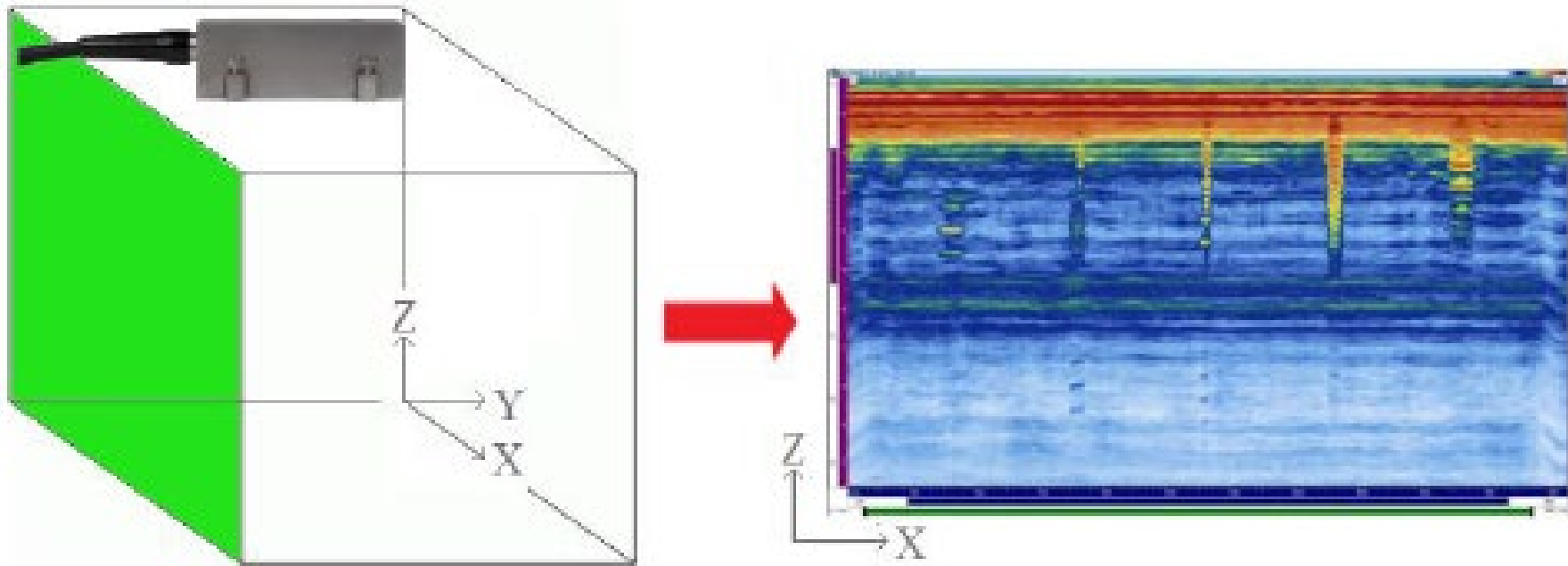




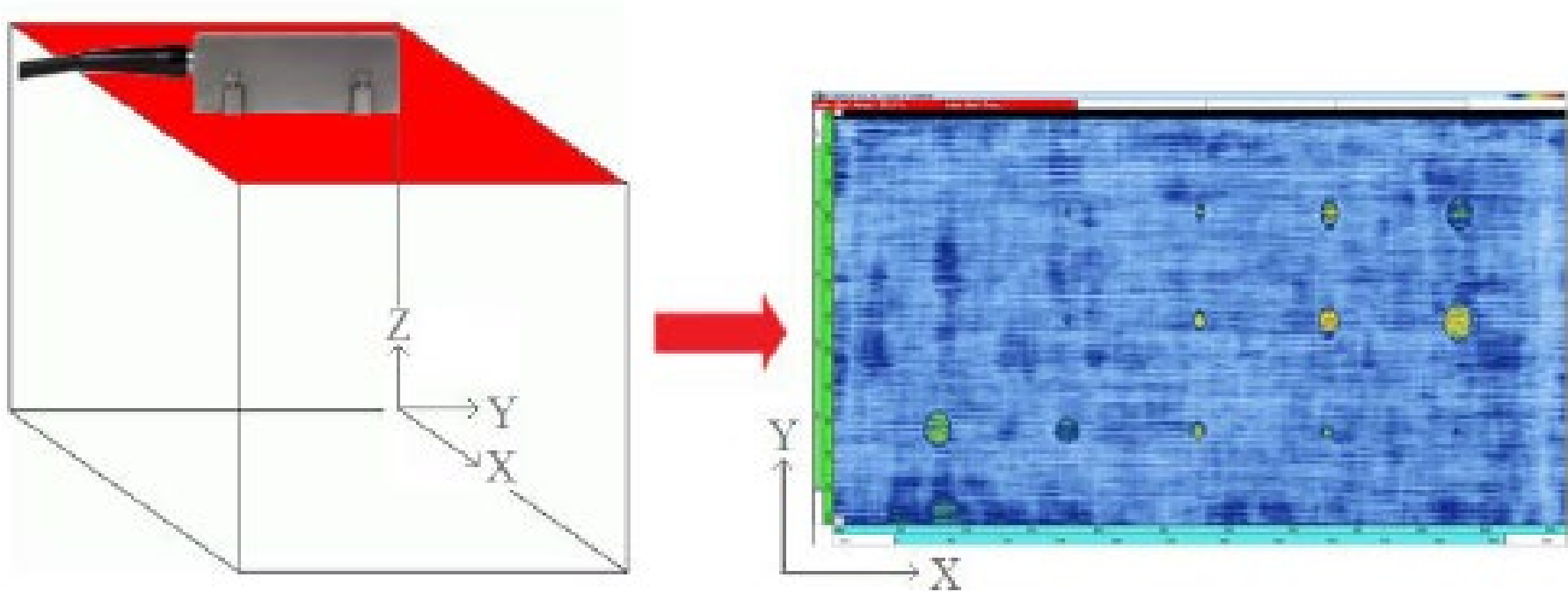
# A-Scan



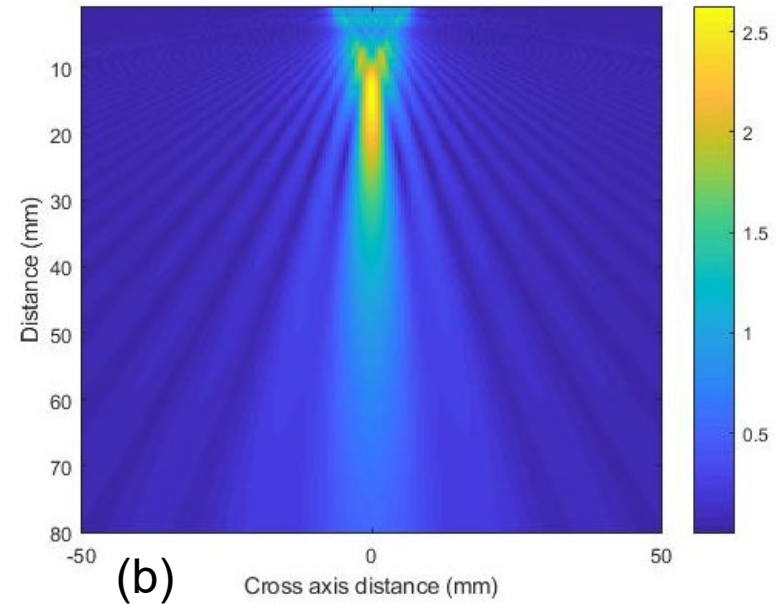
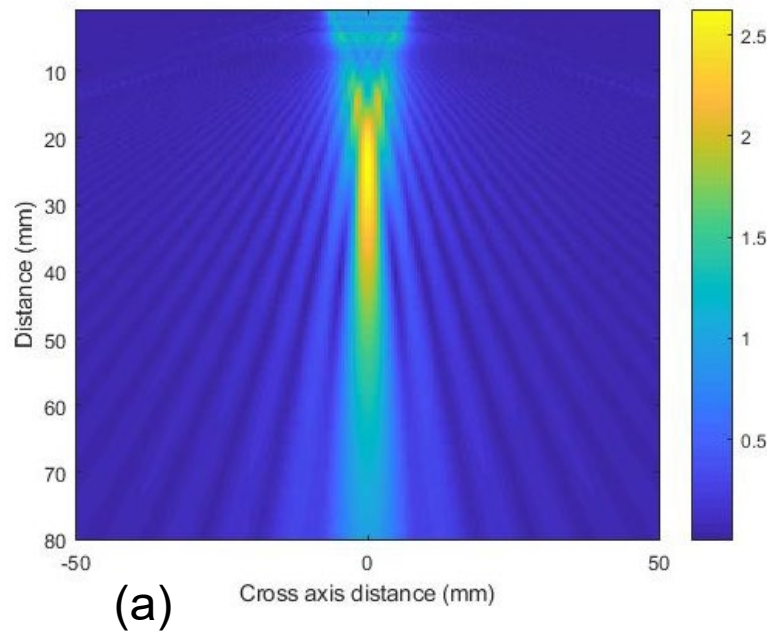
# B-Scan



# C-Scan

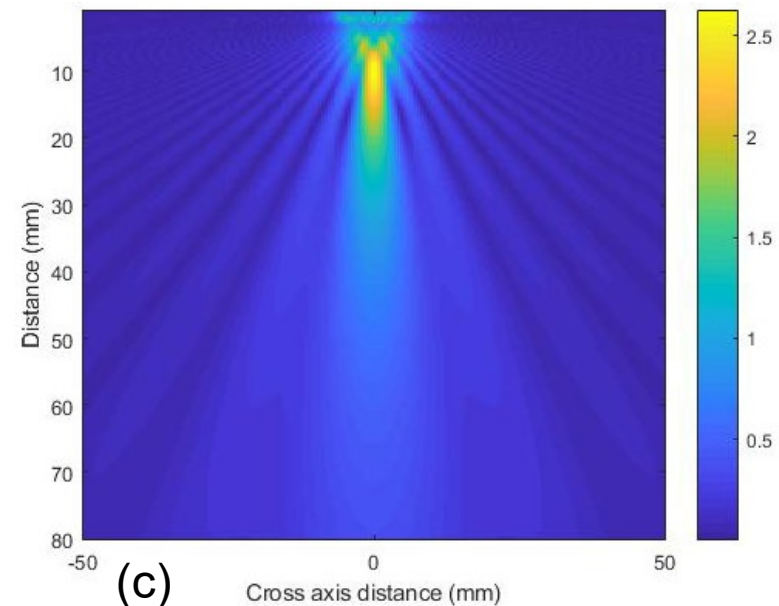


# Beam focusing in anisotropic materials



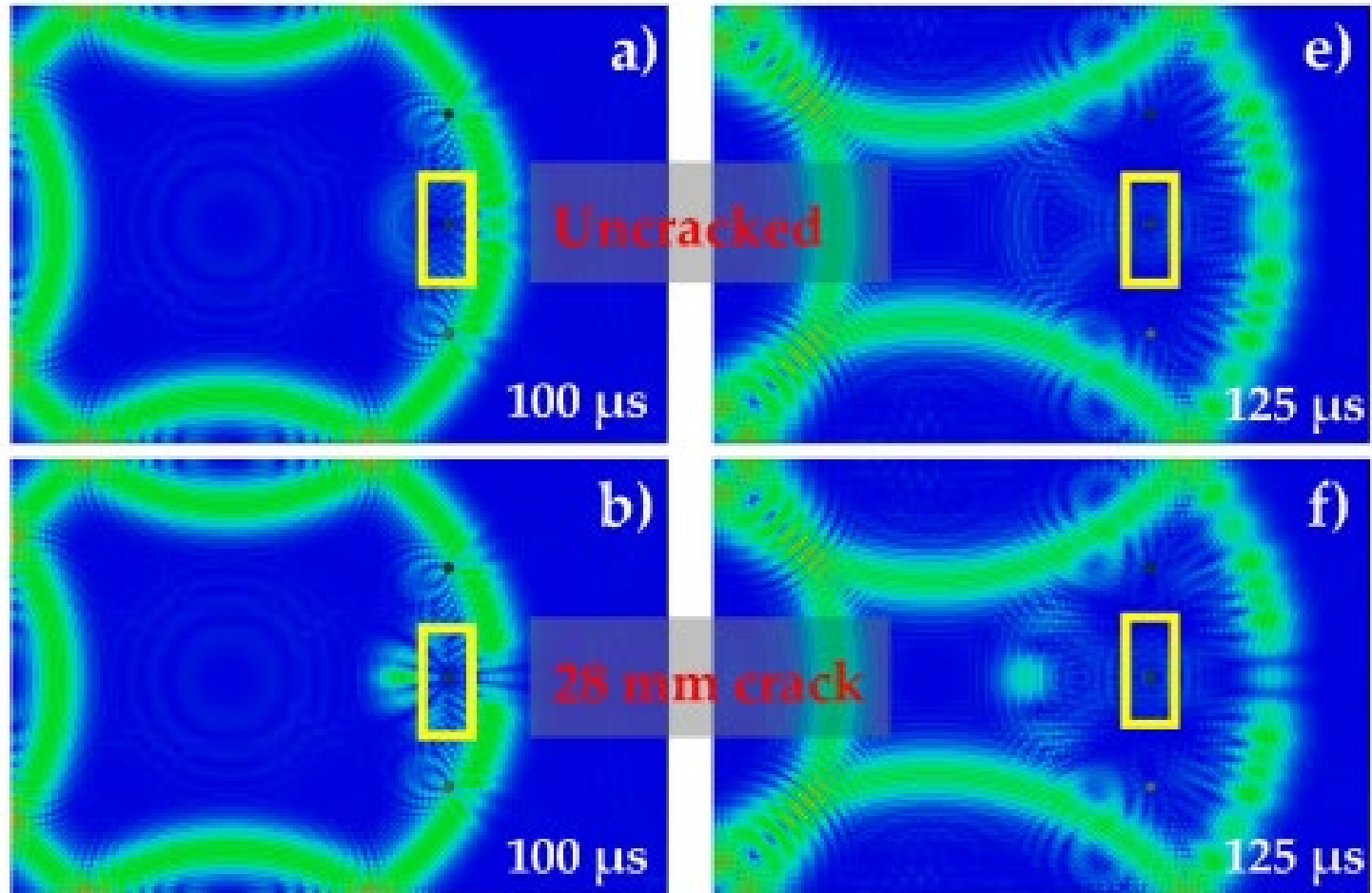
Beam field: (a)  $C = E = 0$ , (b)  $C = E = -2.5 \text{ mm}/\mu\text{s}$ , and (c)  $C = E = -4.9 \text{ mm}/\mu\text{s}$ .

Anand C, Delrue S, Jeong H, Shroff S, Groves RM, Benedictus R. Simulation of Ultrasonic Beam Propagation from Phased Arrays in Anisotropic Media using Linearly Phased Multi Gaussian beams. IEEE Transactions on Ultrasonics, Ferroelectrics, and Frequency Control, 67(1), pp. 106 – 116, 2020.

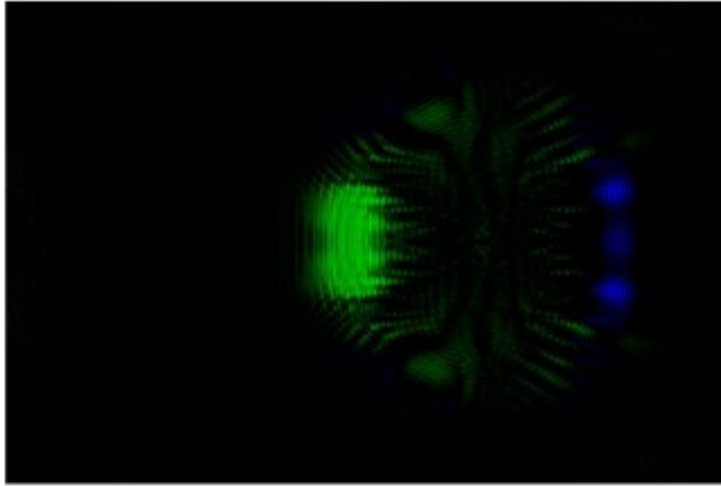


# Guided wave ultrasonics for SHM

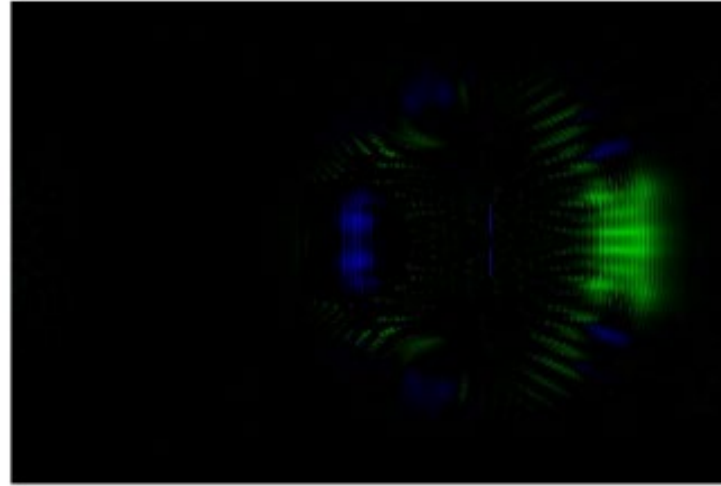
# Guided waves for no defect and 38 mm crack



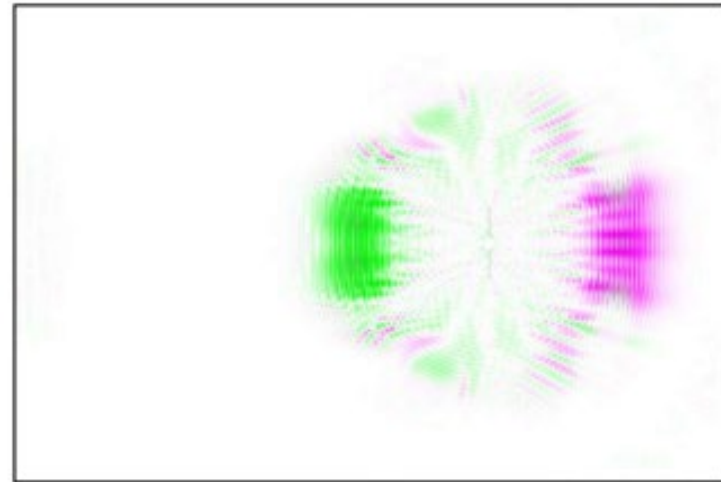
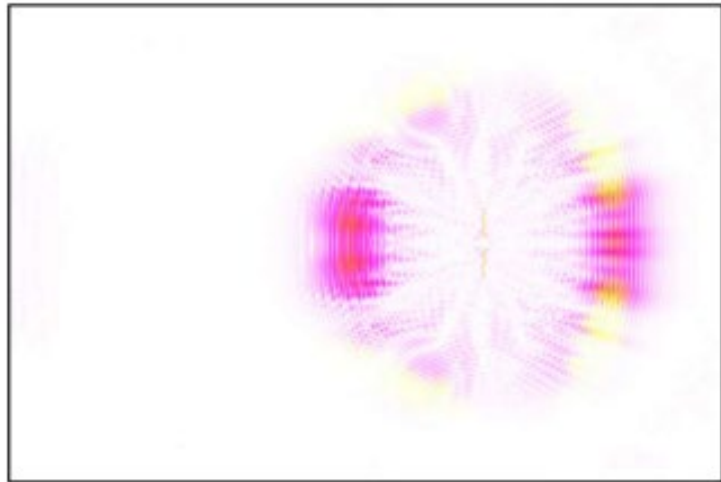
# Difference between defect / no defect images



(a)

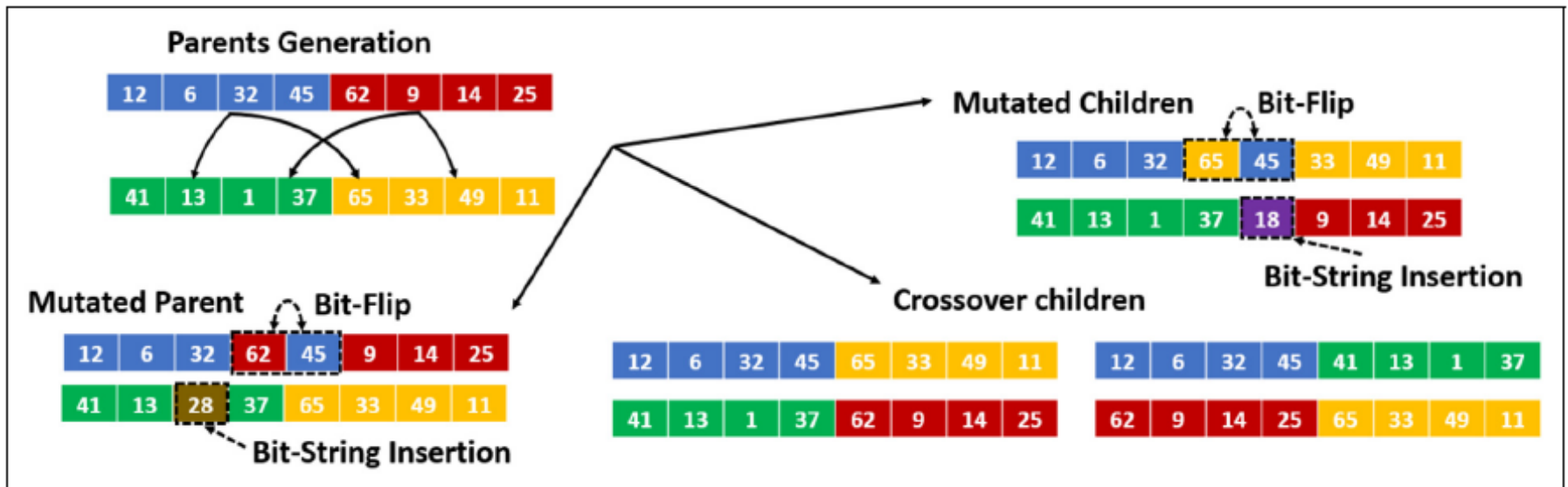


(b)



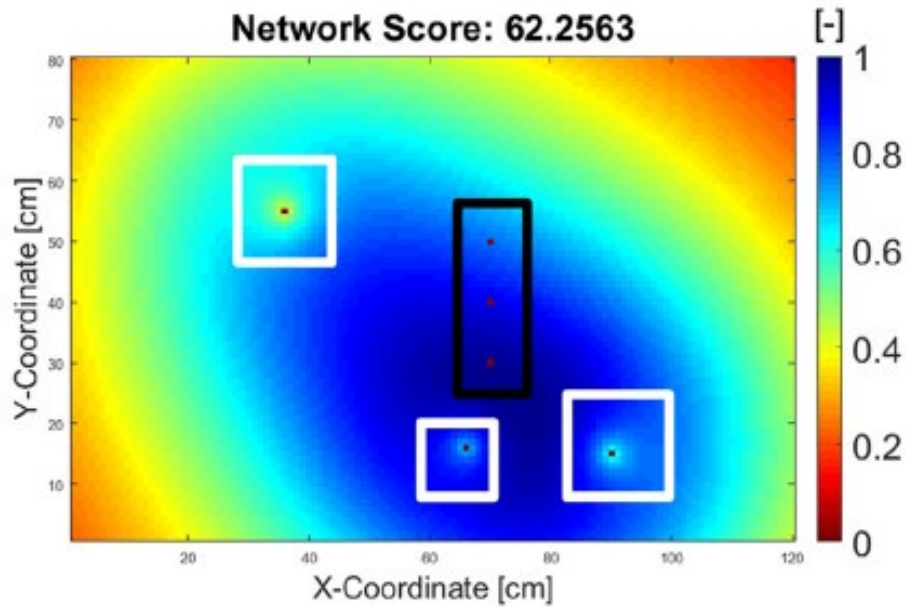
# AI Methods

1. Random algorithm
2. Greedy algorithm
3. Genetic algorithm

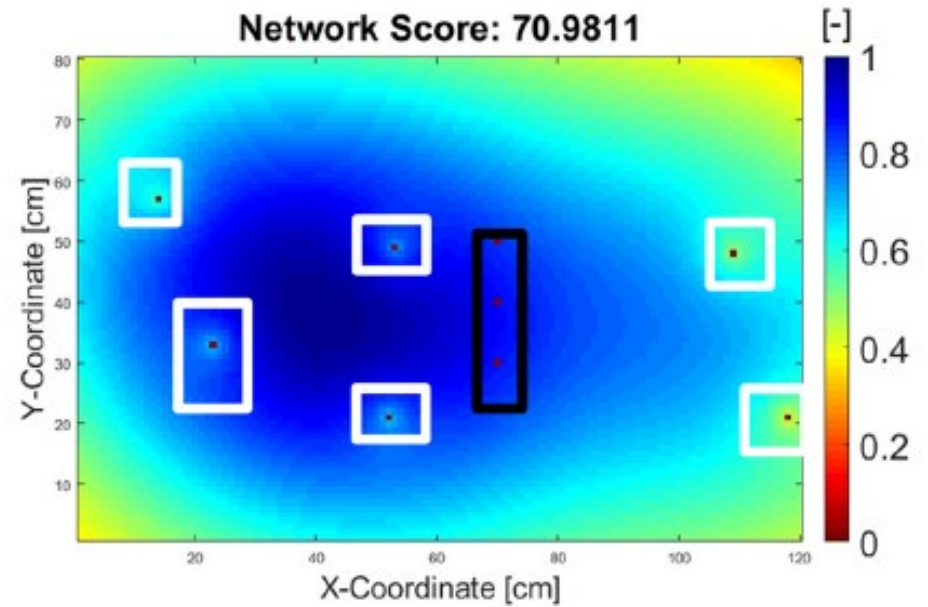




# Network score as a metric

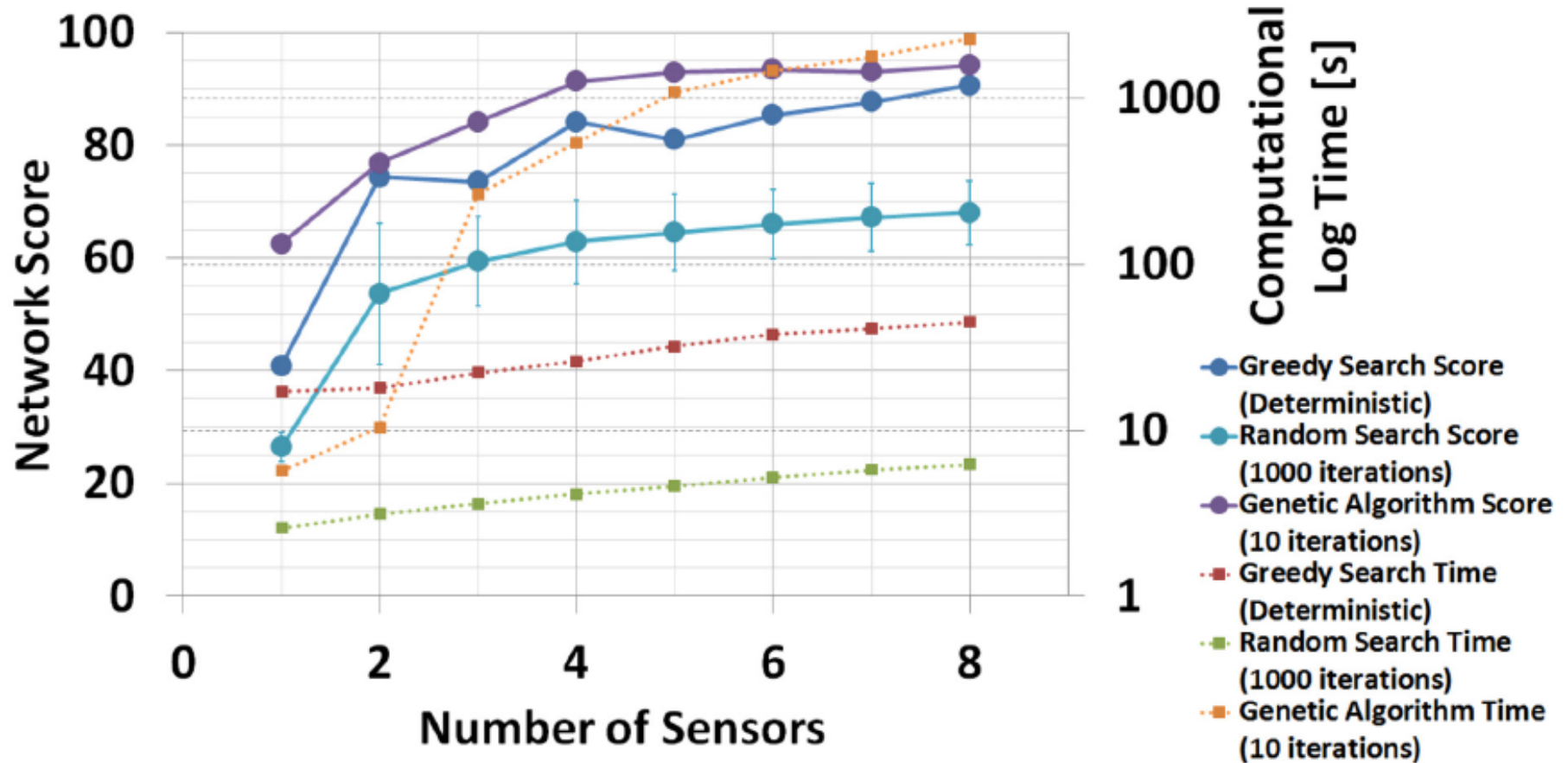


(a)



(b)

# Comparing AI algorithms



**Thank you  
for your  
attention!**

